

# XGT Series

## Programmable Logic Controller

Fast, Compact, Open Network Solution  
Next Generation Technology



### Automation Equipment



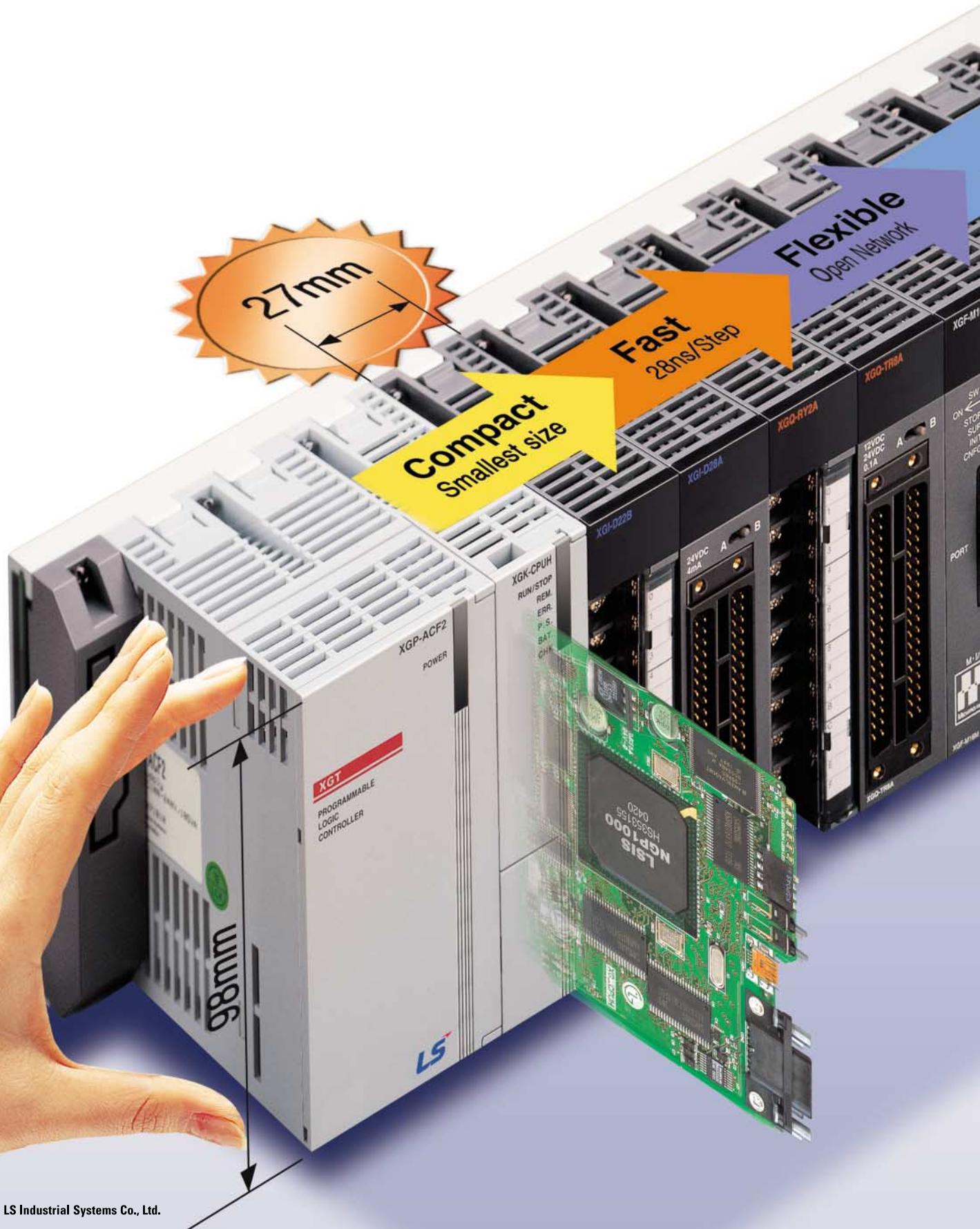


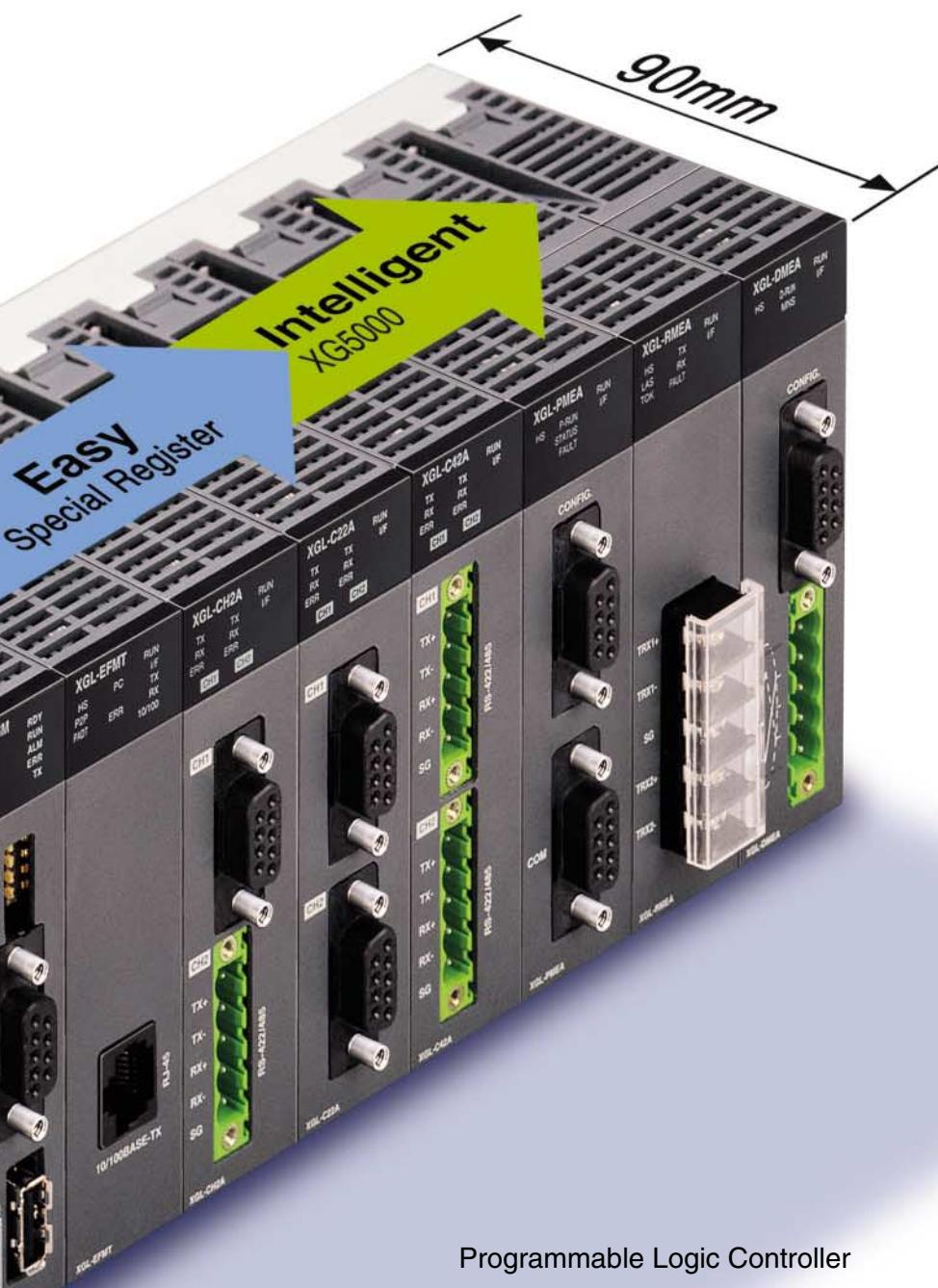
# Programmable Logic Controller **XGT** Series

XGT series incorporate the latest technological achievements in Programmable Logic Controller, made possible by experience and dedication to quality in design and manufacturing.

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Overview

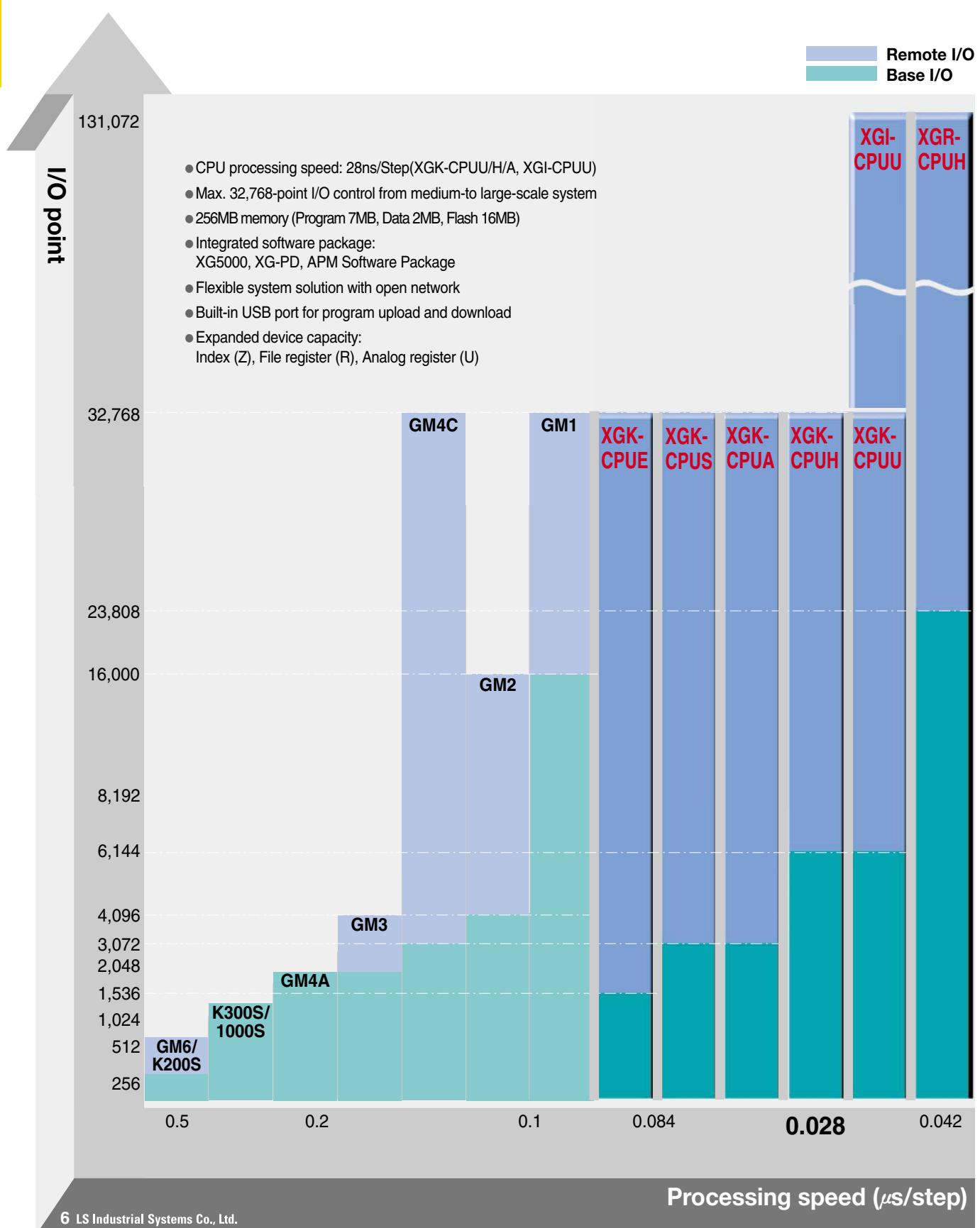
Programmable Logic Controller

# XGT Series

## neXt Generation Technology

XGT series is the next-generation solution with a new concept providing advanced engineering environment based on open network, fastest processing speed, compact size and user-friendly software.

XGT series is the Industrial Workhorse that can support various applications within the typical industrial plant.





Module Size



Size Innovation... **Compact**

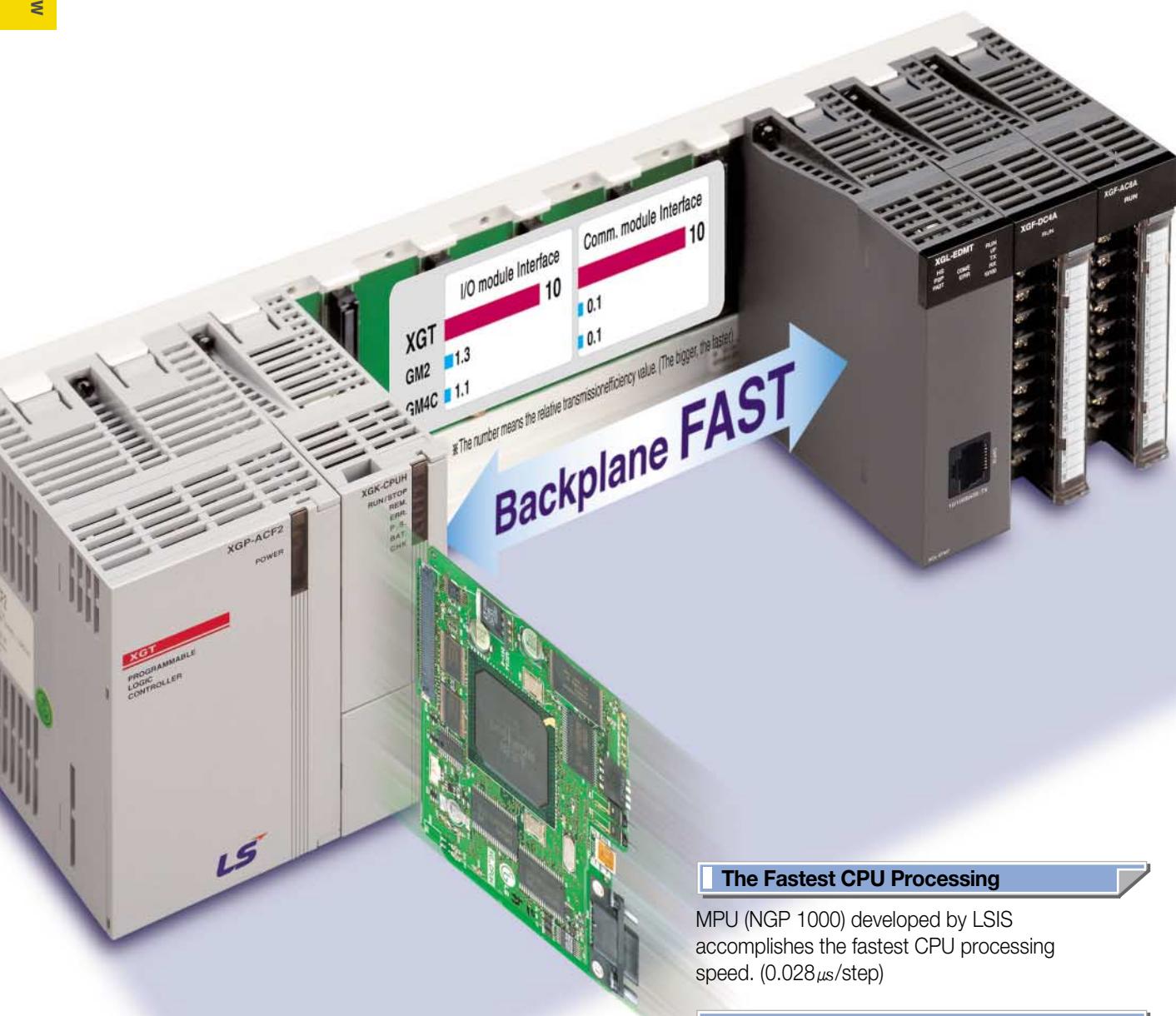
#### The smallest size

The smallest size (**Dimensions 27 × 98 × 90**) achieves cost-efficiency and various applications.

Item	Power Supply	CPU	8-slot Base
Size (W × H × D)	55 × 98 × 90	27 × 98 × 90	318 × 98 × 15

# Speed Innovation... **Fast**

Overview



## The Fastest CPU Processing

MPU (NGP 1000) developed by LSIS accomplishes the fastest CPU processing speed. (0.028 $\mu$ s/step)

## High-speed Interface (Base)

Dedicated bus controller and High-speed transmission algorithm achieve high performance of internal interface.

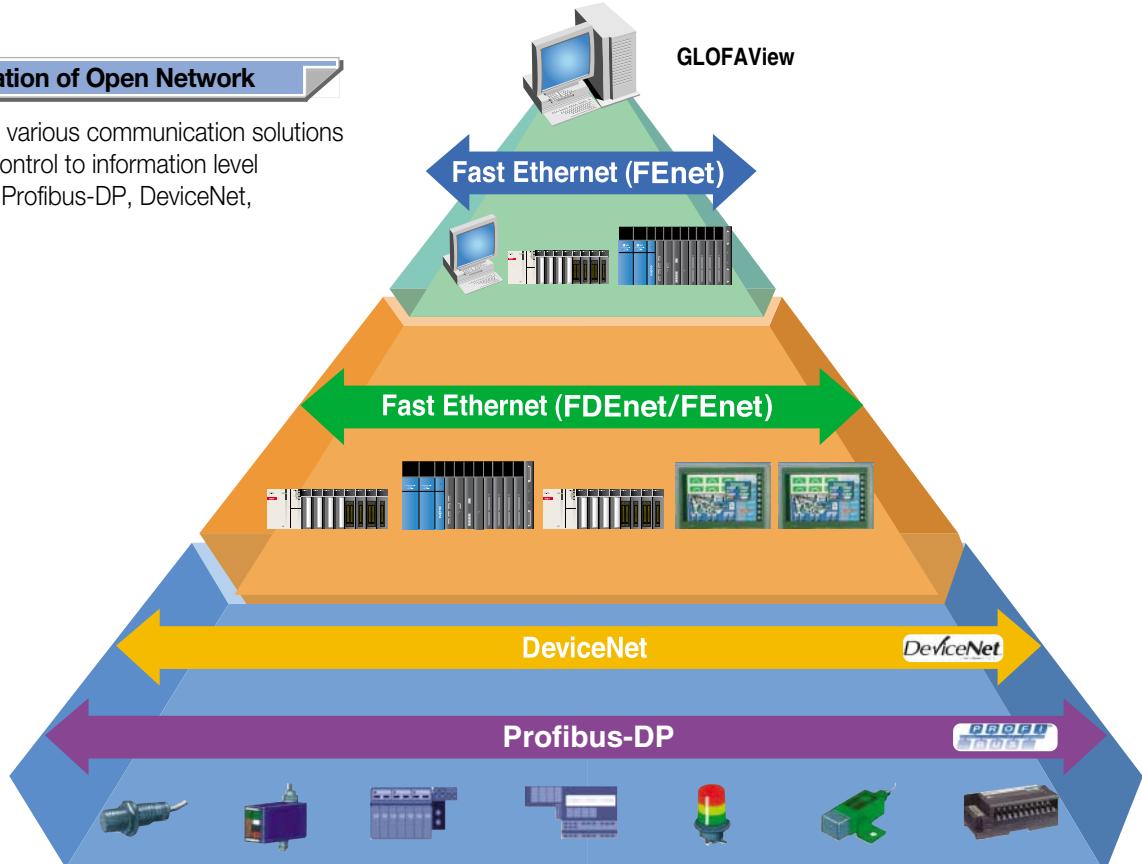
Main Base	Expansion Base
20Mbyte/sec	5Mbyte/sec

# Network Innovation... Flexible

Overview

## System Integration of Open Network

XGT series support various communication solutions ranging from field control to information level with Fast Ethernet, Profibus-DP, DeviceNet, MODBUS



Item	Fast Ethernet		Cnet	Profibus-DP	DeviceNet
	FEnet	FDEnet			
Transmission speed	100 / 10Mbps		300 ~ 115,200bps	Max. 12Mbps	Max. 500Kbps
Transmission distance	100m (Node to Node, UTP/STP) 2Km (Node to Node, Fiber Optic)		Max 500m (422 / 485)	Max. 1.2Km	Max 500m
Max. number of station	64 (HS link)		32	126	64
Service	HS link	●	●	-	●
	XG protocol	●	-	●	-
	General Protocol	● (MODBUS)	-	● (MODBUS)	-
	P2P	●	●	●	-
	XG5000 I/F	●	●	●	-
	E-Mail	●	-	-	-
Configuration software	XG-PD			XG-PD & SyCon	
Number of installation	24 ( HS link Service: 12, P2P Service: 8)				

# Engineering & Programming Innovation... Easy

## Special Register

XGT series expand device memory and support advanced programming environment with Index register (Z), File register (U), and Analog register (U).



### File register

As a non-volatile memory type, data are secured even in times of blackout or CPU reset.



### Analog register

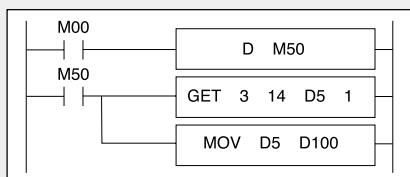
Assigning base, slot and memory buffer of an analog module to device, A/D conversion data can be accessed without analog commands.



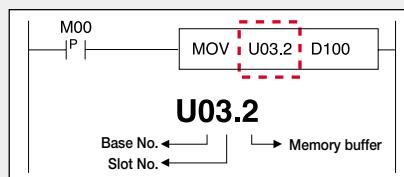
### Index register

Index register is used in the sequence program for array operation.

#### Example of Analog Register



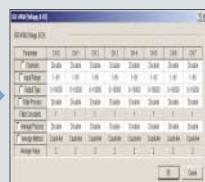
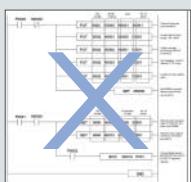
&lt;KGLWIN&gt;



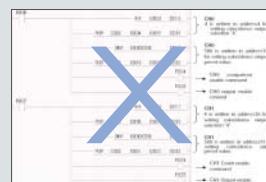
&lt;XG5000&gt;

## Analog Operation without Programming

Special module setup and operation is achieved by just parameter setting without additional program.



Set up analog module



Set up high-speed counter module

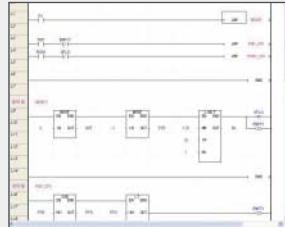
## Program Modularization and Task Operation

Available to run multiful programs through medulization of scan programs based on functions and author, and to operate task programs triggered by specific conditions.

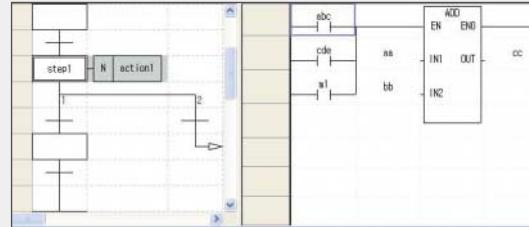
	Program type	Description	Number
Scan program	Scan	Executed in every scan	256-task
	Initialization task	Executed only one time when power turns on	1
	Time driven task	Executed with a constant time interval specified in parameter setting	32
Task program	Internal task	Executed by internal condition	32
	External interrupt task	Executed by external interrupt input	32

## IEC standard language (XGI): LD, SFC, ST

### Ladder Diagram



### SFC



### ST

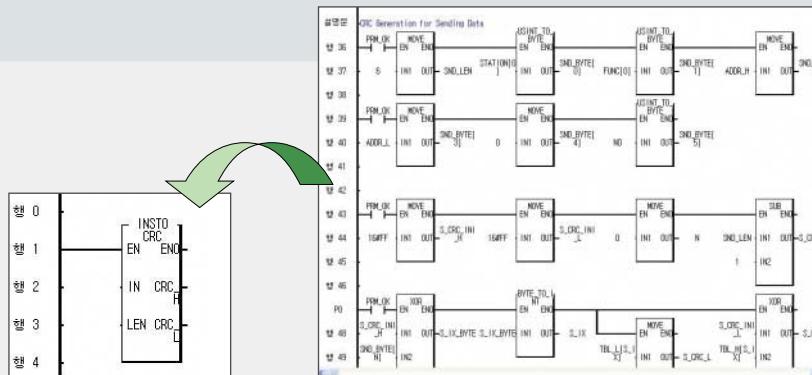
```

19 X2 := { - B - SQRT(D) } / (2.0*E) ;
20 END_IF ;
21
22 // CASE문 예제
23 TU := WORD_BCD_TO_INT(THUMBWHEEL);
24 TU_ERROR := 0;
25 CASE TU
26   1..5: DISPLAY := OVEN_TEMP;
27   2..5: DISPLAY := MOTOR_SPEED;
28   8..10: DISPLAY := GROSS - TARE;
29   4..10: DISPLAY := ADD(TU , 8);
30 ELSE: DISPLAY := ADD(TU , 8);
31 END_CASE;
32 TU_ERROR := 1;
33 END_CASE;
34 THM100 := INT_TO_BCD_WORD(DISPLAY);
35
36 // FOR문 예제
37 SUM := 0;
38 FOR I := 1 TO 3 DO
39   FOR J := 1 TO 2 DO
40     IF FLAG THEN EXIT; END_IF;
41     SUM := SUM + J ;
42   END_FOR;
43   SUM := SUM + I ;
44 END_FOR;
    
```

### ST features

- High-level Language
- Fit for the complicate algorithm
- Various open source (Compatibility)
- Easy data processing
- Convenient text editor

## User defined Function block (XGI)



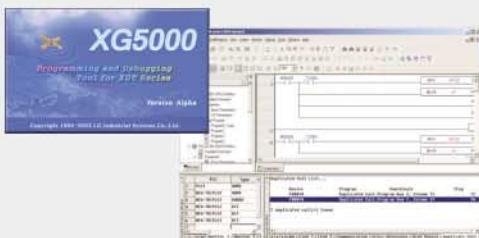
- Standardize the program using function or function block
- Register the standardized program as a library file and reuse the library for another project

# Software Innovation... Intelligent



## Integrated Programming & Engineering

XG5000 Software Package provides integrated engineering environment from basic programming to different special module setting as well as diagnosis. This package consists of XG5000 (PLC programming), XG-PD (Communication programming) and APM Software Package (Positioning programming).



## XG5000

Program Editing & Engineering Software  
Windows-based Easy Operation  
Multi-PLC Multi-Programming Support  
Various Monitoring & Diagnosis Functions



## XG-PD

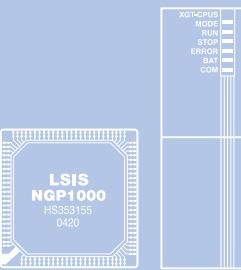
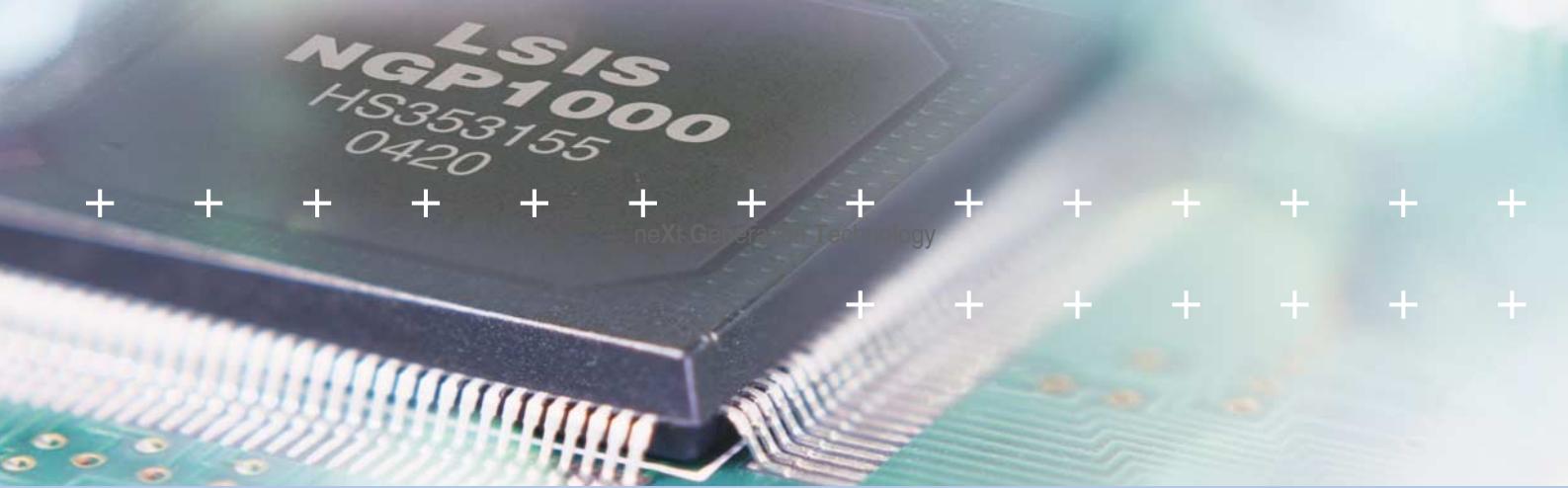
Comm. & Network Parameter Setting  
Protocol Editing / Network Diagnosis  
Frame Monitoring / Protocol Analysis



## APM S/W package

Positioning Parameter Setting  
Data Editing in EXCEL  
Various Monitoring & Diagnosis  
Tracking Function

Intelligent



# CPU & System configuration

CPU

XGT series contain variety of CPU types for customized solutions which support wide coverage from small/middle- to large size-system control.

IEC based CPU for high-speed and large scale application



## XGI-CPUU (IEC Standard)

- Program capacity: 1Mbyte
- I/O points: 6,144
- I/O device point: 131,072 (Remote I/O)
- Processing speed: 28ns/step
- IEC 61131-3 standard programming
  - LD (ladder), SFC (Sequential Function Chart)
  - ST (Structured Text)
  - User defined FB (Function block)
- Powerful built-in PID and Process control
  - Max. 256 loops and variety of process functions
- Utilize the same I/O with XGK CPU
- Enable to convert from GLOGA PLC program to XGI program



## XGI-CPUH (IEC Standard)

- Program capacity: 512Kbyte
- I/O points: 6,144
- I/O device point: 131,072 (Remote I/O)
- Processing speed: 28ns/step
- IEC 61131-3 standard programming
  - LD (ladder), SFC (Sequential Function Chart)
  - ST (Structured Text)
  - User defined FB (Function block)
- Powerful built-in PID and Process control
  - Max. 256 loops and variety of process functions
- Utilize the same I/O with XGK CPU
- Enable to convert from GLOGA PLC program to XGI program

## Premium CPU for high-speed and large scale application



### XGK-CPUU (Ultra capacity)

- Program capacity: 128K steps
- I/O points: 6,144
- I/O device point: 32,000 (Remote I/O)
- Processing speed: 28ns/step



### XGK-CPUA (Advanced)

- Program capacity: 32K step
- I/O point: 3,072
- I/O device point: 32,000 (Remote I/O)
- Processing speed: 28ns/step

### XGK-CPUH (High performance)

- Program capacity: 64K steps
- I/O points: 6,144
- I/O device point: 32,000 (Remote I/O)
- Processing speed: 28ns/step

## General sequence controller PLC CPU



### XGK-CPUS (Standard)

- Program capacity: 32K steps
- I/O points: 3,072
- I/O device point: 32,000 (Remote I/O)
- Processing speed: 84ns/step

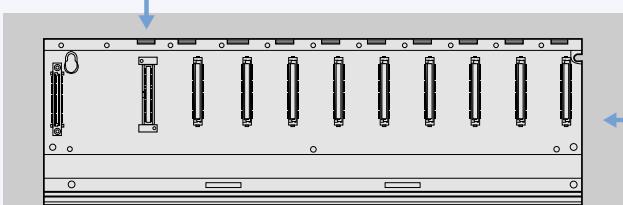


### XGK-CPUE (Economic)

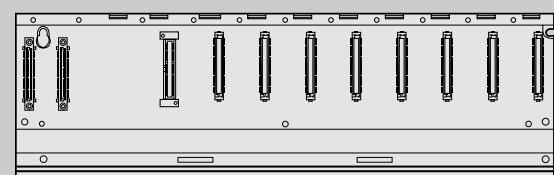
- Program capacity: 16K step
- I/O point: 1,536
- I/O device point: 32,000 (Remote I/O)
- Processing speed: 84ns/step

## CPU & System configuration / CPU module

### System composition

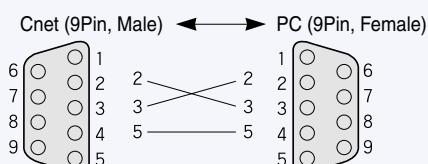


Item	Type	Description
Expansion cable	XGC-E041	Expansion cable 0.4m
	XGC-E061	Expansion cable 0.6m
	XGC-E121	Expansion cable 1.2m
	XGC-E301	Expansion cable 3.0m
	XGC-E501	Expansion cable 5.0m
	XGC-E102	Expansion cable 10m
	XGC-E152	Expansion cable 15m
Expansion terminator	XGT-TERA	Expansion terminator



Item	Main base	Expansion base
4 Slot	XGB-M04A	XGB-E04A
6 Slot	XGB-M06A	XGB-E06A
8 Slot	XGB-M08A	XGB-E08A
12 Slot	XGB-M12A	XGB-E12A

#### • XG5000 Cable (RS-232C)



CPU module			
Item	Type	Description	
USB cable	USB-301A	USB downloading cable	
RS-232C cable	KIC-050A	RS-232C downloading cable	
Power module			
AC	Free Voltage	XGP-ACF1 DC5V 3A XGP-ACF2 DC24V 0.6A	
	220V	XGP-AC23 DC5V 6A	
DC		XGP-DC42 DC5V 6A	
Input module			
Item	AC110V	AC220V	DC24V
8 points	-	XGI-A21A	XGI-D21A
16 points	XGI-A12A	-	XGI-D22A
	-	-	XGI-D22B
32 points	-	-	XGI-D24A
	-	-	XGI-D24B
64 points	-	-	XGI-D28A
	-	-	XGI-D28B
Output module			
Item	Relay	Triac	Transistor
8 points	XGQ-RY1A	-	-
16 points	XGQ-RY2A XGQ-RY2B	XGQ-SS2A	XGQ-TR2A XGQ-TR2B
	-	-	XGQ-TR4A
32 points	-	-	XGQ-TR4B
64 points	-	-	XGQ-TR8A XGQ-TR8B
Input/Output mixed module			
Item	16-point DC input	16-point TR output	
Special module			
Analogue input	XGF-AV8A XGF-AC8A XGF-AD8A XGF-AD4S XGF-AD16A	Voltage input type, 8Ch Current input type, 8Ch Voltage/ Current input, 8Ch Voltage/ Current input, 4Ch (isolated) Voltage/ Current input, 16Ch	
Analogue output	XGF-DV4A XGF-DC4A XGF-DV8A XGF-DC8A XGF-DV4S XGF-DC4S	Voltage output type, 4Ch Current output type, 4Ch Voltage output type, 8Ch Current output type, 8Ch Voltage output, 4Ch (isolated) Current output, 4Ch (isolated)	
High-speed counter	XGF-HO2A XGF-HD2A XGF-PO3A XGF-PO2A	Pulse (OC) input type, 2Ch Pulse (LD) input type, 2Ch Pulse (OC) output type, 3 axes Pulse (OC) output type, 2 axes	
Positioning	XGF-PO1A XGF-PD3A XGF-PD2A XGF-PD1A	Pulse (OC) output type, 1 axis Pulse (LD) output type, 3 axes Pulse (LD) output type, 2 axes Pulse (LD) output type, 1 axis	
Temperature control	XGF-TC4S XGF-RD4A XGF-RD4S	Thermocouple input, 4Ch RTD input, 4Ch RTD input, 4Ch (insulated)	
Temperature controller	XGF-TC4UD	Temperature controller, 4 loops, Universal input	
Communication module			
RAPIEnet	XGL-EIMT XGL-EIMH XGL-EIMF XOL-EIMT XOL-EIMF	RAPIEnet Twisted fair 2Ch RAPIEnet Fiber optic/Twisted fair 1Ch RAPIEnet Fiber optic 2Ch RAPIEnet Twisted fair 2Ch for PC RAPIEnet Fiber optic 2Ch for PC	
Cnet	XGL-CH2A XGL-C22A XGL-C42A	RS-232C/RS-422 RS-232C, 2Ch RS-422, 2Ch	
Ethernet (Open)	XGL-EFMF XGL-EFMT XGL-ESHF XGL-EHST	Fiber optic, Master, SC type Twisted pair, Master, RJ-45 Fast Ethernet, Industrial Ring module Fast Ethernet, Switching hub	
Ethernet (Dedicated)	XGL-EDMF XGL-EDMT	Fiber optic, Master, SC type Twisted pair, Master, RJ-45	
Rnet	XGL-RMEA	Rnet, Master, TP	
DeviceNet	XGL-DMEA	DeviceNet, Master	
Profibus-DP	XGL-PMEA	Profibus-DP, Master	

# CPU & System configuration / CPU module

## Specifications

Item	Description			Standard		
Ambient temperature	0 ~ 55 °C					
Storage temperature	-25 ~ +70 °C					
Ambient humidity	5 ~ 95%RH (Non-condensing)					
Storage humidity	5 ~ 95%RH (Non-condensing)					
Occasional vibration						
Vibration resistance	Frequency 10 ≤ f < 57Hz 57 ≤ f < 150Hz	Acceleration -	Pulse width 0.075mm	10 times each direction (X, Y and Z)		
	9.8m/s <sup>2</sup> {1G}			IEC 61131-2		
Continuous vibration						
	Frequency 10 ≤ f < 57Hz 57 ≤ f < 150Hz	Acceleration -	Pulse width 0.035mm	(X, Y and Z)		
	4.9m/s <sup>2</sup> {0.5G}					
Shock resistance	<ul style="list-style-type: none"> <li>• Peak acceleration: 147 m/s<sup>2</sup> {15G}</li> <li>• Duration: 11ms</li> <li>• Half-sine, 3 times each direction per each axis</li> </ul>			IEC 61131-2		
Noise resistance	Square wave impulse noise Electrostatic discharge Radiated electromagnetic field noise Fast transient/ Burst noise	<ul style="list-style-type: none"> <li>±1,500Vp-p</li> <li>±4kV</li> <li>27~500MHz, 10V/m</li> <li>0.25kV</li> </ul>		LSIS Standard IEC 61131-2, IEC 1000-1-2 IEC 61131-2, IEC 1000-1-3 IEC 61131-2, IEC 1000-1-4		
Operating Ambience	Free from corrosive gases and excessive dust					
Altitude	Up to 2,000m					
Pollution degree	Less than equal to 2					
Cooling	Air-cooling					

\* Pollution degree 2 is nonconductive pollution of the sort where occasionally a temporary conductivity caused by condensation must be expected.

Item	Description					Remarks																		
	XGK-CPUE	XGK-CPUS	XGK-CPUA	XGK-CPUH	XGK-CPUU																			
Operation method	Cyclic execution of stored program, Time-driven interrupt, Process-driven interrupt																							
I/O control method	Batch processing by scan synchronization (Refresh), Direct input/output by instructions																							
Program language	Ladder diagram, Instruction list																							
Number of instructions	<table border="1"> <tr> <td>Basic Application</td> <td>42</td> <td>600</td> <td></td> <td></td> <td></td> </tr> </table>						Basic Application	42	600															
Basic Application	42	600																						
Processing speed	<table border="1"> <tr> <td>Sequence instruction (μs)</td> <td>0.084 μs/step</td> <td>0.028 μs/step</td> <td></td> <td></td> <td></td> </tr> <tr> <td>Application instruction (μs)</td> <td>0.252 μs/step</td> <td>0.084 μs/step</td> <td></td> <td></td> <td></td> </tr> <tr> <td>Floating instruction (μs)</td> <td>±: 0.602 μs (S), 1.078 μs (D) ×: 1.106 μs (S), 2.384 μs (D) ÷: 1.134 μs (S), 2.66 μs (D)</td> <td>±: 0.602 μs (S), 1.078 μs (D) ×: 1.106 μs (S), 2.384 μs (D) ÷: 1.134 μs (S), 2.66 μs (D)</td> <td></td> <td></td> <td></td> </tr> </table>						Sequence instruction (μs)	0.084 μs/step	0.028 μs/step				Application instruction (μs)	0.252 μs/step	0.084 μs/step				Floating instruction (μs)	±: 0.602 μs (S), 1.078 μs (D) ×: 1.106 μs (S), 2.384 μs (D) ÷: 1.134 μs (S), 2.66 μs (D)	±: 0.602 μs (S), 1.078 μs (D) ×: 1.106 μs (S), 2.384 μs (D) ÷: 1.134 μs (S), 2.66 μs (D)			
Sequence instruction (μs)	0.084 μs/step	0.028 μs/step																						
Application instruction (μs)	0.252 μs/step	0.084 μs/step																						
Floating instruction (μs)	±: 0.602 μs (S), 1.078 μs (D) ×: 1.106 μs (S), 2.384 μs (D) ÷: 1.134 μs (S), 2.66 μs (D)	±: 0.602 μs (S), 1.078 μs (D) ×: 1.106 μs (S), 2.384 μs (D) ÷: 1.134 μs (S), 2.66 μs (D)																						
Program capacity	16K Steps	32K Steps	32K Steps	64K Steps	128K Step																			
I/O points (available to install)	With 16-point I/O	384	768	768	1536	1536																		
	With 32-point I/O	768	1536	1536	3072	3072																		
	With 64-point I/O	1536	3072	3072	6144	6144																		
Data area	P	P0000 ~ P2047F (32768 points)				I/O relay																		
	M	M0000 ~ M2047F (32768 points)				Auxiliary relay																		
	K	K000 ~ K2047F (32768 points)				Special relay																		
	L	L000 ~ L11263F (32768 points)				Link relay																		
	F	F000 ~ F2047F (32768 points)				Keep relay																		
	T	100ms: T0000 - T0999 10ms: T1000 - T1499 1ms: T1500 - T1999 0.1ms: T2000 - T2047				Timer (Adjustable)																		
	C	C0000 ~ C2047				Counter																		
	S	S00.00 ~ S127.99				Step controller																		
	D	D0000 ~ D19999		D0000 ~ D32767		Register																		
	U	U0.0~U1F.31	U0.0~U3F.31	U0.0~U3F.31	U0.0~U7F.31	Analog resister																		
	Z	128points				Index register																		
File register	R	RAM: 1 block		RAM: 2 blocks		1 block: R0 ~ R32767																		
		Flash: 2M byte, 32 blocks																						
Program type	Total program	256																						
	Initialization	1 (INT)																						
	Time-driven	32																						
	External	32																						
	Internal	32																						
Operation mode	RUN, STOP, DEBUG																							
Self-diagnosis	Execution, Delay, Memory error, I/O error, Battery error, Power error																							
Programming port	RS-232C (1Ch), USB (1Ch)																							
Data retention at power failure	Set "retain" at data declaration																							
Max. expansion stage	2	4	4		8																			
Current consumption (mA)	960																							
Weight (Kg)	0.12																							

## Specifications

Item		XGI-CPUU	XGI-CPUH	Remarks	
<b>Operation system</b>		Reiterative operation, fixed cycle operation, constant scan			
<b>I/O Control system</b>		Scan synchronous batch processing system(refresh system), direct system by command			
<b>Program language</b>		Ladder Diagram, SFC (Sequential Function Chart), ST (Structured Text), IL (Read only)			
<b>No. of commands</b>	Operator	18			
	Basic function	136 types + real number operation function			
	Basic function block	43			
	Dedicated function block	Dedicated function blocks by special function modules, communication dedicated function block(P2P)			
<b>Operation processing speed (basic command)</b>	Basic	0.028μs/step			
	MOVE	0.084μs/step			
	Real number operation	±:0.392μs(S), 0.924μs(D) ×:0.896μs(S), 2.240μs(D) ÷:0.924μs(S), 2.254μs(D)		S: Single real number D: Double real number	
<b>Program memory capacity</b>		1Mbyte	512Kbyte	Including upload program	
I/O points(installable)		6,144points			
Max. I/O memory contact)		131,072points			
<b>Data memory</b>	Symbolic variable area(A)		512KB (max. 256KB retain settable)		
	I variable(I)		16Kbyte		
	Q variable(Q)		16Kbyte		
	Direct variable	M	256KB (max. 128KB retain settable)	64kbyte per block	
		R	64Kbyte * 2block		
	Flag variable	W	128Kbyte	System flag	
		F	4Kbyte	PID flag	
		K	16Kbyte	High speed link flag	
		L	22Kbyte		
		U	8Kbyte		
<b>Flash area</b>		2Mbyte, 32block		Controllable by R device	
<b>Timer</b>		No point limit		20 bytes of symbolic variable area per point	
<b>Counter</b>		Time range: 0.001~ 4,294,967.295 second(1,193 hours)			
		No point limit		8 bytes of symbolic variable area per point	
<b>Program structure</b>	Coefficient range : 64 bit expression				
	Total no. of programs		256		
	Initialization task		1		
	Fixed cycle task		32		
<b>Operation mode</b>		Internal device task		32	
<b>Restart mode</b>		RUN, STOP, DEBUG			
<b>Self diagnosis</b>		Cold, Warm			
<b>Built-in function</b>		Operation delay monitoring, memory fault, I/O fault, battery fault, power fault and etc			
<b>Download port</b>		Modbus slave, PID			
<b>Data protection in case of power failure</b>		RS-232C(1CH), USB(1CH)			
<b>Max. base extension</b>		Retain area setting by basic parameters			
<b>Current consumption(mA)</b>		8		Total length :15 m	
<b>Weight (kg)</b>		960			
		0.12			

**XGK system configuration**

Item	XGK-CPUE	XGK-CPUS	XGK-CPUA	XGK-CPUH	XGK-CPUU																																																			
<b>Max. expansion stage</b>	1 stages	3 stages	3 stages	7 stages	7 stages																																																			
<b>Max. installation of module</b>	24 modules	48 modules	48 modules	96 modules	96 modules																																																			
<b>Max. number of I/O point</b>	1,536	3,072	3,072	6,144	6,144																																																			
<b>Max. expansion distance</b>			15m																																																					
Assignment of I/O number (Fixed)	<ul style="list-style-type: none"> <li>64 points are assigned to each slot of base regardless of installation of module.</li> <li>I/O numbers equivalent to 12 slots are assigned to a base.</li> <li>The starting number of base '0' is P0000.</li> </ul>																																																							
	<ul style="list-style-type: none"> <li>Refer to the following figure regarding the I/O number assignment of 12 slots</li> </ul> <table border="1"> <thead> <tr> <th>Slot number:</th><th>0</th><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th><th>6</th><th>7</th><th>8</th><th>9</th><th>10</th><th>11</th> </tr> <tr> <th>Power</th><td>64 points</td><td>64 points</td> </tr> <tr> <th>CPU</th><td>P0 P3F</td><td>P40 P7F</td><td>P80 P11F</td><td>P120 P15F</td><td>P160 P19F</td><td>P200 P23F</td><td>P240 P27F</td><td>P280 P31F</td><td>P320 P35F</td><td>P360 P39F</td><td>P400 P43F</td><td>P440 P47F</td> </tr> </thead> <tbody> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> </tbody> </table>					Slot number:	0	1	2	3	4	5	6	7	8	9	10	11	Power	64 points	CPU	P0 P3F	P40 P7F	P80 P11F	P120 P15F	P160 P19F	P200 P23F	P240 P27F	P280 P31F	P320 P35F	P360 P39F	P400 P43F	P440 P47F																							
Slot number:	0	1	2	3	4	5	6	7	8	9	10	11																																												
Power	64 points	64 points	64 points	64 points	64 points	64 points	64 points	64 points	64 points	64 points	64 points	64 points																																												
CPU	P0 P3F	P40 P7F	P80 P11F	P120 P15F	P160 P19F	P200 P23F	P240 P27F	P280 P31F	P320 P35F	P360 P39F	P400 P43F	P440 P47F																																												
I/O assignment (Variable)	<ul style="list-style-type: none"> <li>I/O point is assigned automatically according to the installed module.</li> <li>I/O parameter is used to install modules.</li> <li>The starting number of base '0' is P0000.</li> <li>16 points are assigned automatically to the slot of special or communication module</li> </ul>																																																							
	<ul style="list-style-type: none"> <li>Refer to the following figure regarding the I/O number assignment of 12 slots.</li> </ul> <table border="1"> <thead> <tr> <th>Slot number:</th><th>0</th><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th><th>6</th><th>7</th><th>8</th><th>9</th><th>10</th><th>11</th> </tr> <tr> <th>Power</th><td>16 points</td><td>16 points</td><td>32 points</td><td>64 points</td><td>16 points</td><td>32 points</td><td>32 points</td><td>64 points</td><td>32 points</td><td>16 points</td><td>32 points</td><td>32 points</td> </tr> <tr> <th>CPU</th><td>P00 P0F</td><td>P10 P1F</td><td>P20 P3F</td><td>P40 P7F</td><td>P80 P8F</td><td>P90 P10F</td><td>P110 P12F</td><td>P130 P16F</td><td>P170 P18F</td><td>P190 P19F</td><td>P200 P21F</td><td>P220 P23F</td> </tr> </thead> <tbody> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> </tbody> </table>					Slot number:	0	1	2	3	4	5	6	7	8	9	10	11	Power	16 points	16 points	32 points	64 points	16 points	32 points	32 points	64 points	32 points	16 points	32 points	32 points	CPU	P00 P0F	P10 P1F	P20 P3F	P40 P7F	P80 P8F	P90 P10F	P110 P12F	P130 P16F	P170 P18F	P190 P19F	P200 P21F	P220 P23F												
Slot number:	0	1	2	3	4	5	6	7	8	9	10	11																																												
Power	16 points	16 points	32 points	64 points	16 points	32 points	32 points	64 points	32 points	16 points	32 points	32 points																																												
CPU	P00 P0F	P10 P1F	P20 P3F	P40 P7F	P80 P8F	P90 P10F	P110 P12F	P130 P16F	P170 P18F	P190 P19F	P200 P21F	P220 P23F																																												
The standard I/O number assignment is 64 points. (Fixed)	<p>The standard I/O number assignment is 64 points. (Fixed)</p>																																																							

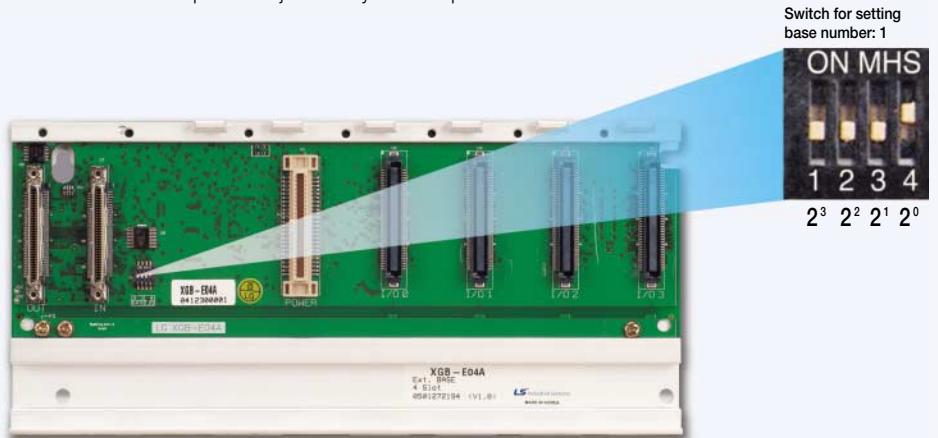
**XGI system configuration**

Item	XGI-CPUH						XGI-CPUU																																																									
<b>Max. expansion stage</b>	7																																																															
<b>Max. installation of module</b>	96																																																															
<b>Max. number of I/O point</b>	1,536 (for 16point I/O module) 3,072 (for 32point I/O module) 6,144 (for 64point I/O module)																																																															
<b>Max. expansion distance</b>	15m																																																															
I/O assignment	<ul style="list-style-type: none"> <li>64 points are assigned to each slot of base regardless of installation of module.</li> <li>No limit in installation of special module</li> <li>Special module is controlled by function block and the memory assignment is done automatically</li> </ul>					<ul style="list-style-type: none"> <li>Refer to the following figure regarding the I/O assignment of 12 slots</li> </ul> <table border="1"> <thead> <tr> <th>Slot number:</th><th>0</th><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th><th>6</th><th>7</th><th>8</th><th>9</th><th>10</th><th>11</th> </tr> <tr> <th>Power</th><td>16 points</td><td>16 points</td><td>32 points</td><td>64 points</td><td>16 points</td><td>32 points</td><td>32 points</td><td>64 points</td><td>32 points</td><td>16 points</td><td>32 points</td><td>32 points</td> </tr> <tr> <th>CPU</th><td>P00 P0F</td><td>P10 P1F</td><td>P20 P3F</td><td>P40 P7F</td><td>P80 P8F</td><td>P90 P10F</td><td>P110 P12F</td><td>P130 P16F</td><td>P170 P18F</td><td>P190 P19F</td><td>P200 P21F</td><td>P220 P23F</td> </tr> </thead> <tbody> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> </tbody> </table>							Slot number:	0	1	2	3	4	5	6	7	8	9	10	11	Power	16 points	16 points	32 points	64 points	16 points	32 points	32 points	64 points	32 points	16 points	32 points	32 points	CPU	P00 P0F	P10 P1F	P20 P3F	P40 P7F	P80 P8F	P90 P10F	P110 P12F	P130 P16F	P170 P18F	P190 P19F	P200 P21F	P220 P23F													
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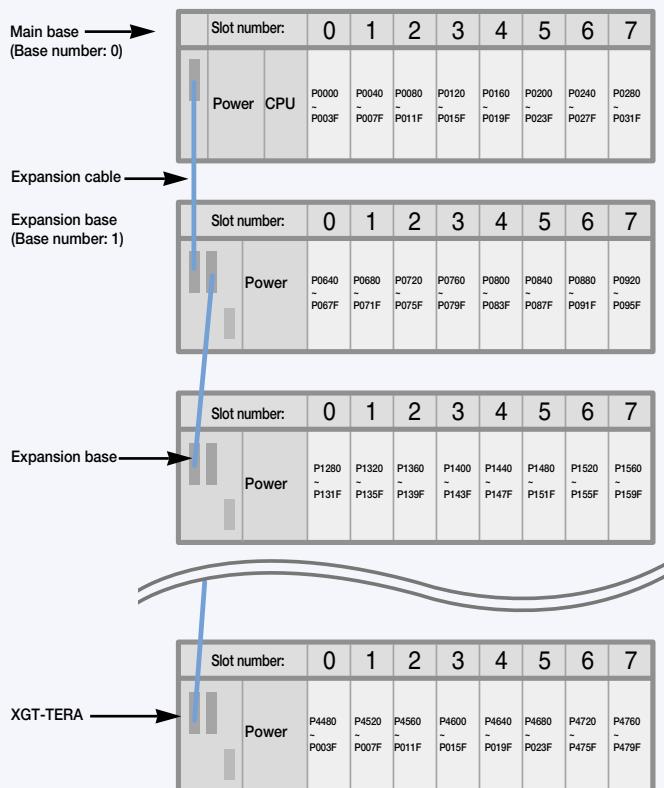
## Expansion system composition

1. The following figure is the example of expansion system with the fixed I/O point type of XGK-CPUH.

2. The address of I/O point is adjustable by XG5000 parameter.



The lowest expansion base should be connected to the upper stage with expansion terminator(XGT-TERA).



XGT-TERA should be installed at the end of the last expansion base.

## CPU & System configuration / I/O module

### Features

- 8, 16, 32, 64 points I/O module
- Operation monitoring by LED display
- Easy maintenance: Terminal block type, one-touch installation of module



### Input module specifications

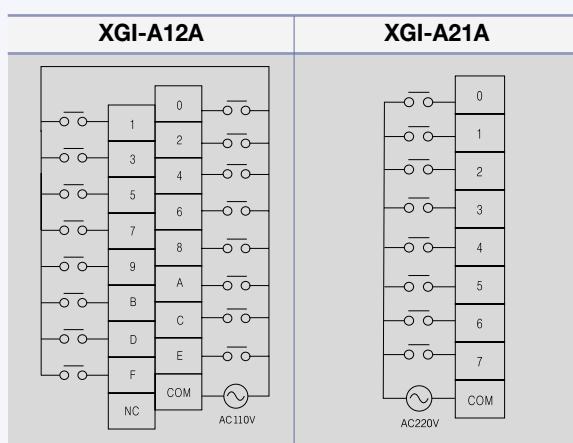
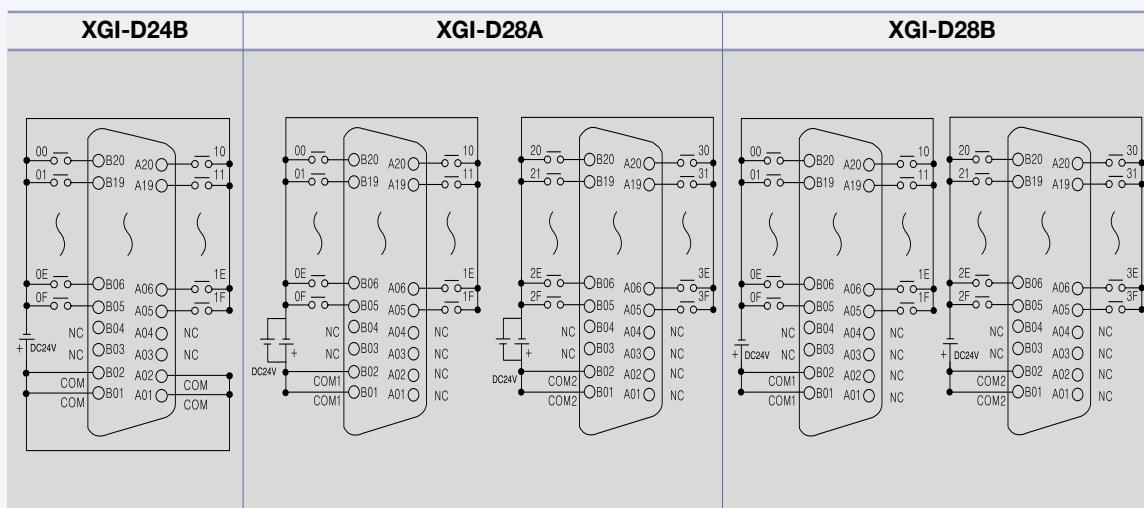
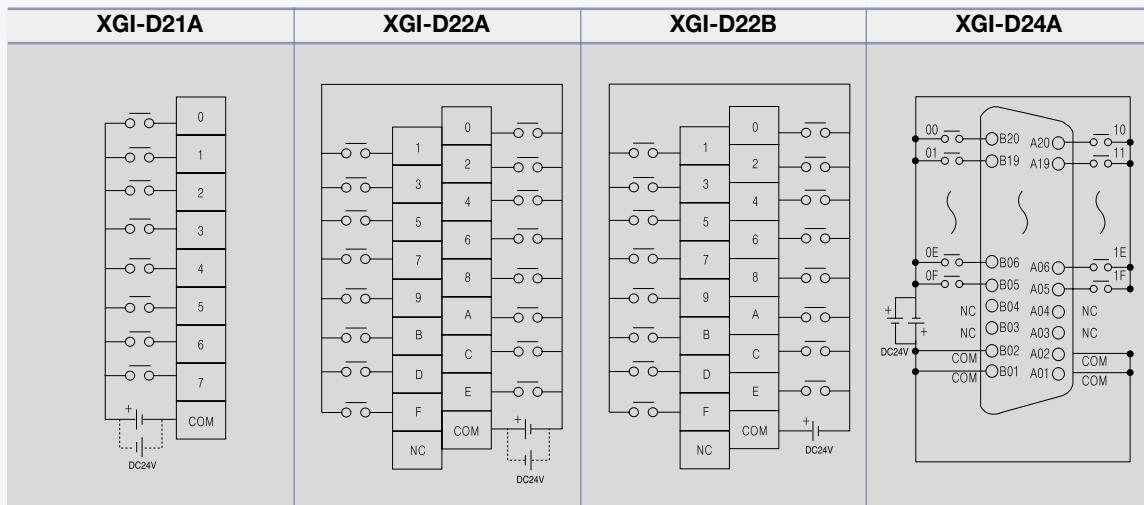
Input type		DC input							AC input				
Type		XGI-D21A	XGI-D22A	XGI-D22B	XGI-D24A	XGI-D24B	XGI-D28A	XGI-D28B	XGI-A12A	XGI-A21A			
Input point		8	16		32		64		16	8			
Rated input voltage		DC24V			AC100~120V			Free voltage					
Rated input current		4mA			8mA			17mA					
ON voltage/current		19V or more / 3mA or less			AC80V or more / 5mA or less			AC130V or more / 10mA or less					
OFF voltage/current		DC11V or more / 1.7mA or less			AC30V or more / 1mA or less			AC60V or more / 2mA or less					
Response	Off→On	1ms/5ms/10ms/20ms/70ms (set by CPU parameter) Initial value: 3ms							15mA or less				
	On→Off	1ms/5ms/10ms/20ms/70ms (set by CPU parameter) Initial value: 3ms							25mA or less				
Common (COM)		8 points/COM	16 points/COM		32 points/COM			16 points/COM	8 points/COM				
Insulation method		Photocoupler											
Current consumption (mA)		20	30		50		60		30	20			
Weight (Kg)		0.1	0.12		0.1		0.15		0.13	0.13			

### Output module specifications

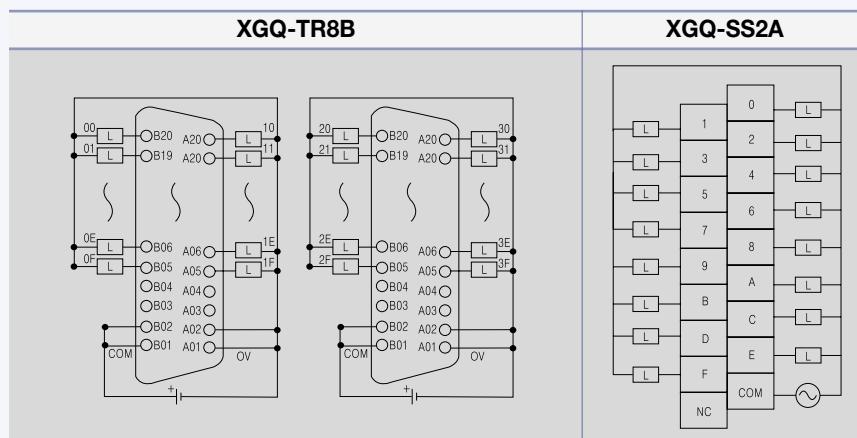
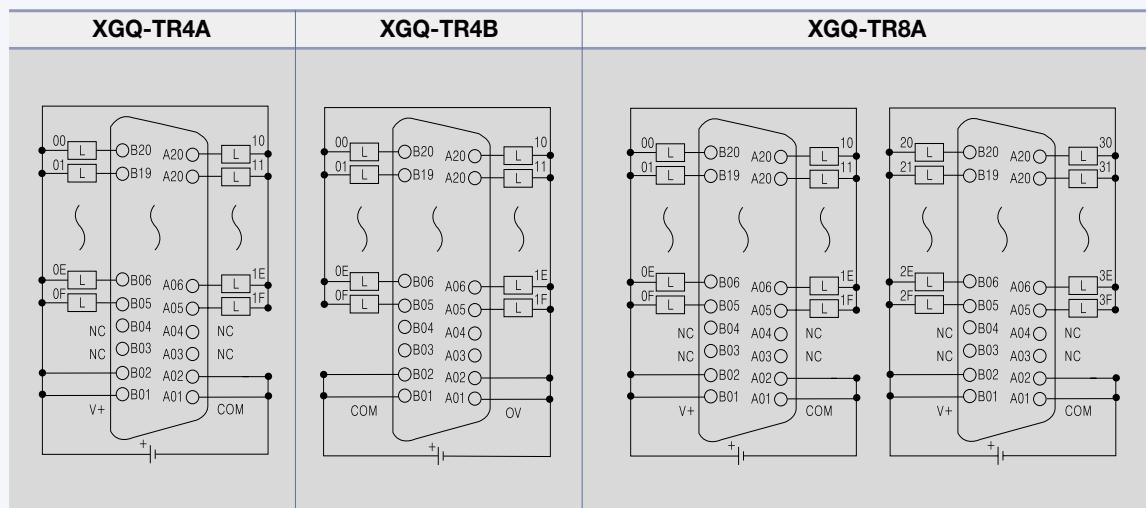
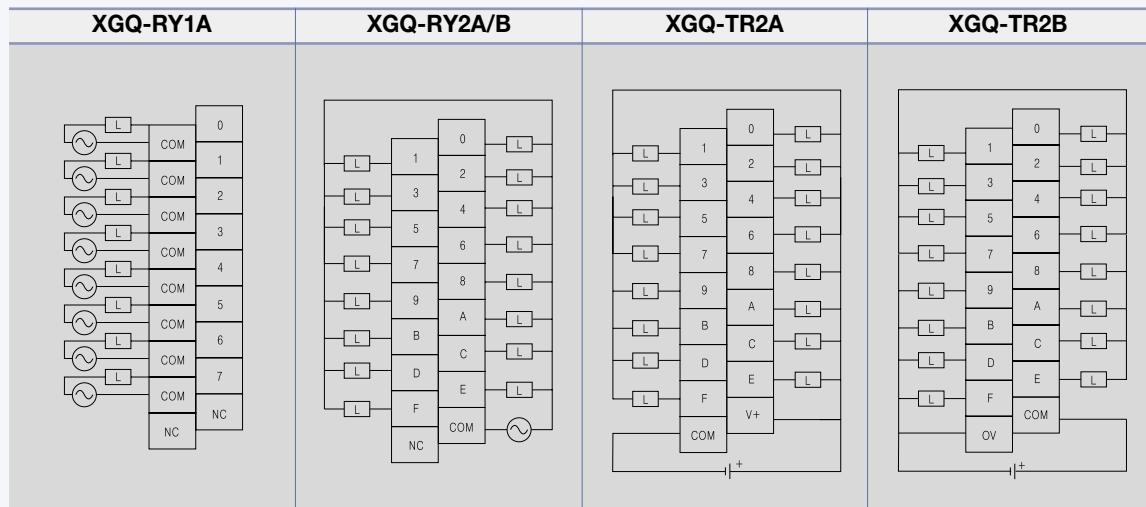
Input type		Relay			Transistor					Triac				
Type		XGQ-RY1A	XGQ-RY2A	XGQ-RY2B	XGQ-TR2A	XGQ-TR2B	XGQ-TR4A	XGQ-TR4B	XGQ-TR8A	XGQ-TR8B	XGQ-SS2A			
Output point		8	16		16		32		64		16			
Rated load voltage		DC12/24V, AC110/220V			DC12/24V			AC110/220V						
Rated output current	1 point	2A			0.5A		0.1A			0.6A				
	Common	5A			4A		2A			4A				
Response time	Off→On	10ms or less			1ms or less					1ms or less				
	On→Off	12ms or less			1ms or less					0.5cycle +1ms or less				
Common (COM)		1 point/COM	16 points/COM		32 points/COM					16 points/COM				
Insulation method		Relay			Photocoupler									
Current consumption (mA)		260	500		70		130		230		300			
Weight (Kg)		0.13	0.17	0.19	0.11		0.1		0.15		0.2			
Surge killer		-		Varistor	Zener diode					Varistor				
External power supply		-			DC					-				

Note) B1, B2 of 32, 62 points terminal (connector) are shorted inside of the product.

### Wiring diagram for input modules



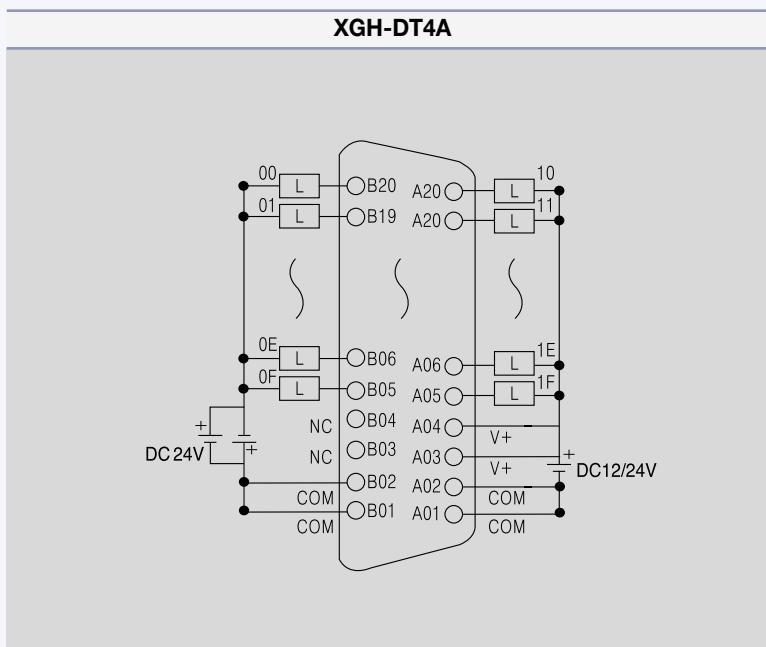
## Wiring diagram for output modules



### Input/output mixed type (XGH-DT4A)

Input		Output		
Input points	16 points	Input points	16 points	
Insulation method	Photo coupler	Insulation method	Photo coupler	
Rated input voltage	DC24V	Rated input voltage	DC12/24V	
Rated input current	4mA	Rated input current	DC10.2~26.4V	
Input voltage range	DC20.4~28.8V	Input voltage range	0.1A/point, 1.6A/COM	
Insulation pressure	AC560Vrms / 3Cycle	Insulation pressure	0.1mA or less	
On voltage/current	DC19V or more / 3mA or more	On voltage/current	0.7A/10ms or less	
Off voltage/current	DC11V or more / 1.7mA or more	Off voltage/current	Zener diode	
Input resistance	5.6 kΩ	Input resistance	DC 0.2V or less	
Response	Off→On (Setting by CPU parameter) Initial value: 3ms	Response	Off→On 1ms or less	
	1ms/3ms/5ms/10ms/20ms/70ms/100ms		On→Off 1ms or less (rated load, resistance load)	
	1ms/3ms/5ms/10ms/20ms/70ms/100ms (Setting by CPU parameter) Initial value: 3ms			
Common (COM)	16 points/COM			
Operation display	LED lighting when output is ON			
Internal current consumption	100mA			
External connection	40-point connector			
Weight (kg)	0.1			

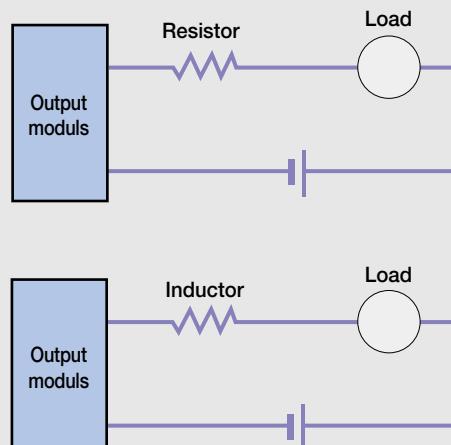
### Wiring diagram for mixed type



\* Input address for XGK CPU is P00~P0F and Output address is P10~P1F when it is installed on the slot 0.  
Input address for XGI CPU is %IX0.0.0~%IX0.0.15 and Output address is %QX0.0.16~%QX0.0.31

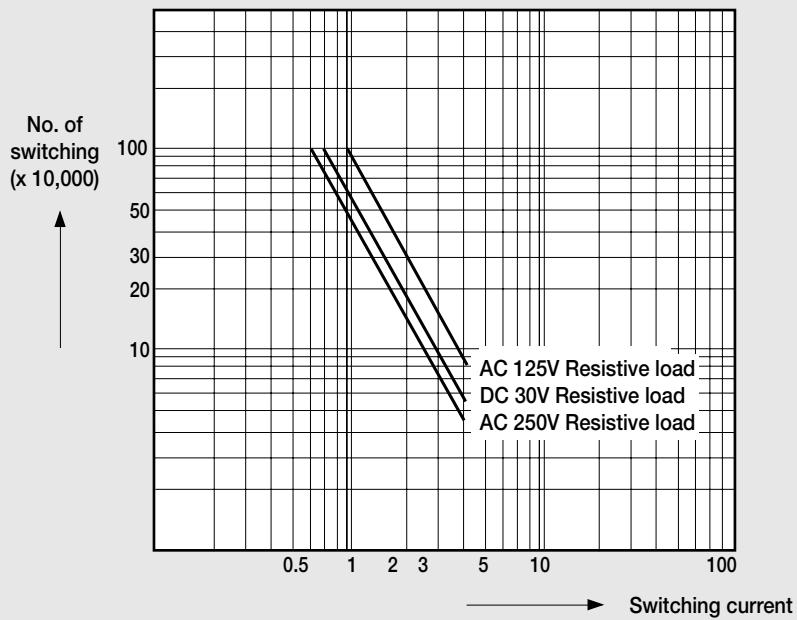
## Precaution during installation of I/O module

- XGT has 2 kinds of digital input type: Current sink input, Current source input. For DC input module has different wiring depending on the input type, digital input type should be selected with consideration about connected input device.
- Max. number of simultaneous input point differs according to the module type. Therefore, review specification of input module before its application.
- Use an interrupt module when a response of high-speed input is demanded. But only one interrupt module can be installed per CPU module.
- If switching frequency is high or inductive switching load is used, the lifespan of relay output module will be reduced. Therefore, it is recommended to use transistor output module or triac output module.
- When driving an inductive load with output module, set the maximum switching frequency as 'ON' for 1 second and 'OFF' for 1 second.
- When using counter or timer with DC/DC converter, it is possible to have inrush current which cause a break down. Therefore to reduce an effect of inrush current, connect resistor or inductor to load or use the module whose max. load current is high.

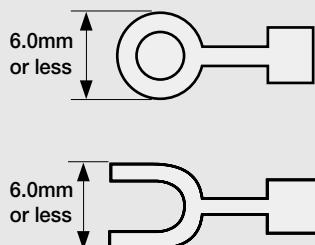


- Fuse of output module is not exchangeable to prevent a damage of external wiring when output module has a short-circuit.
- The number of simultaneous 'ON' points varies depending on input voltage, ambient temperature. Refer to the specification of input module.

- The following graph presents the relay lifespan of relay output module. It shows the maximum lifespan of relay which is used in the relay output.



- Compressed terminal attaching sleeve cannot be mounted to XGT terminal block. The following picture shows appropriate compressed terminals for terminal block.



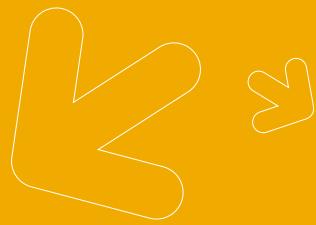
- Use 0.3~0.75mm<sup>2</sup> twisted pair, below 2.8mm thickness cable for connecting to terminal block.
- Be careful when choosing and using the cable since the permissible current differs according to the insulation thickness.
- Joint torque of fixed screw and terminal block screw of the module needs to be within the range in the following table.

Joint	Joint torque range
I/O module terminal block screw (M3)	42~58 N · cm
I/O module terminal block fixed screw (M3)	68~89 N · cm

- Thermal protector is built in transistor module. Thermal protector is a function that protects PLC from an overload and overheating.



XGR



# Redundancy system

Redundancy system for high-speed process control based on IEC



- Processing speed: 42ns/step
- I/O Points: Max. 131,072
- Total memory: 32MB (Program 7MB, Data 2MB, Reserved 7MB, Flash 16MB)
- Switching over time: 50ms
- Built-in 256 PID loops control



### High performance

- Processing speed: 42ns/step
- CPU synchronization via fiber optic cable
- I/O Points: Max. 131,072
- Total memory: 32MB (Program 7MB, Data 2MB, Reserved 7MB, Flash 16MB)
- Switching over time: 50ms

### Easy expansion installation using network

- Max. 31 expansion base
- Distance: Fiber 2km (Max. expansion 60km), Twisted pair 100m (Max. expansion 3km)
- Program upload and download via expansion base
- No limit to install the communication master on the expansion base

### Enhanced maintenance via system history and network ring configuration

- Convenient system analyze using Operation history, Error history, System history
- Ring configuration to prevent a line disconnection error
- Network monitoring, Protocol monitoring function
- Error channel monitoring via flag
- Graphic display for the system configuration
- Safe module exchange via Wizard



### IEC 61131-3 Standard language

- LD, ST, SFC, IL (read only)
- Program configuration and data type based on IEC

### Variety of communication function

- Easy interface using Open network (Ethernet, Profibus-DP, DeviceNet, RS-232C, RS-422/485, etc)
- Max. 24 communication module installation on the expansion base (High speed link 12, P2P 8)
- Network diagnosis via network and frame monitoring
- PLC link via dedicated communication base on Ethernet (RAPIDnet)

### Variety of input and output module

- 8 / 16 / 32 / 64 points (8 / 16 points Relay output)
- Input / Output / Mixed module

### Enhanced analog function

- Enable to install the analog module on the expansion base (Max. 250, Analog input 139)
- Insulated type and Temperature module
- Easy to set the parameter via I/O parameter and flag
- Debugging function via special module monitoring

### Integrated programming & engineering environment

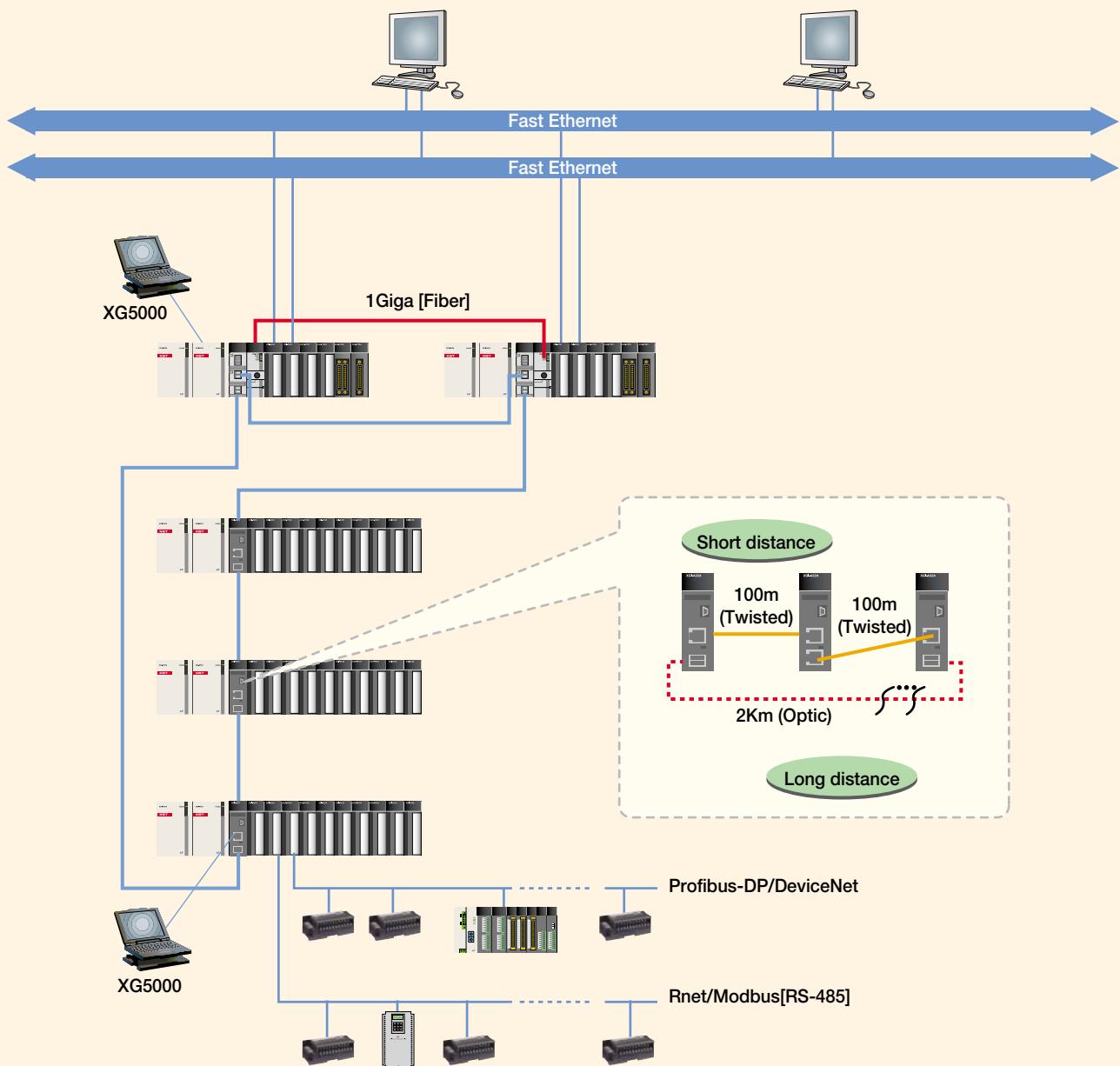
- XG5000 : Easy to program, various monitoring functions and enhanced editing function
- XG-PD : Convenient setup for communication and network parameter
- XG-PDAPM software package: Software package for positioning module

### XGR Configuration

- Base, Power, CPU, Network redundancy
- Dual port and 3 kinds of media (Twisted-Twisted, Optic-Optic, Twisted-Optic)



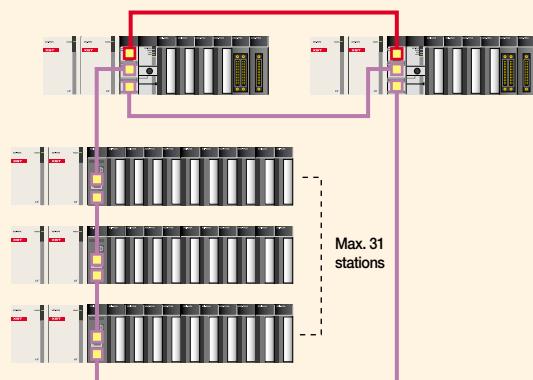
System



## Redundancy system / System configuration method

### System configuration

- Fiber-optic



#### XGR-CPUH/F

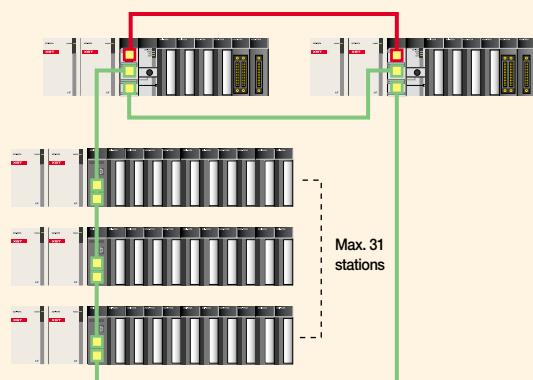
- Main CPU
- Fiber optic: Max. distance 2Km



#### XGR-DBSF

- Expansion drive module
- Fiber optic: Max. distance 2Km (Installed on the expansion base)
- Max. 31 stations

- Twisted pair



#### XGR-CPUH/T

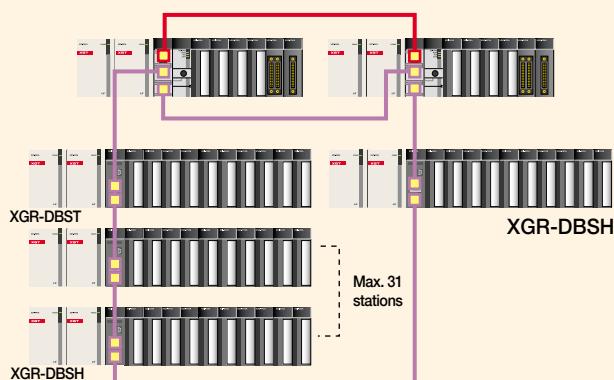
- Main CPU
- Twisted fair: Max. distance 100m



#### XGR-DBST

- Expansion drive module
- Twisted fair : Max. distance 100m (Installed on the expansion base)
- Max. 31 stations

- Hybrid (Twisted pair + Fiber Optic)



#### XGR-CPUH/T XGR-CPUH/F

- Main CPU
- Fiber optic: Max. distance 2Km
- Twisted fair: Max. distance 100m



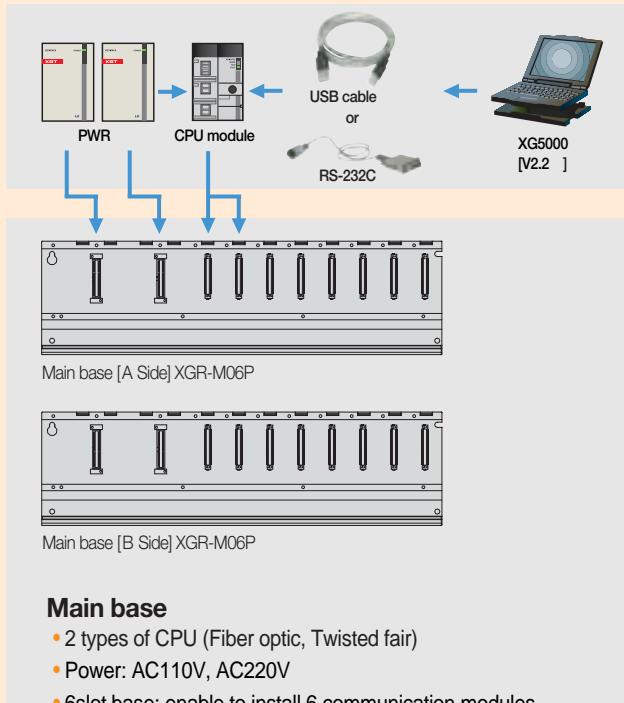
#### XGR-DBSH

- Expansion drive module
- Fiber optic: Max. distance 2Km
- Twisted fair: Max. distance 100m (Installed on the expansion base)
- Max. 31 stations

\* Max. expandable distance: Fiber optic 60km, Twisted fair 3km  
\* CPU synchronization cable: 2m, 5m

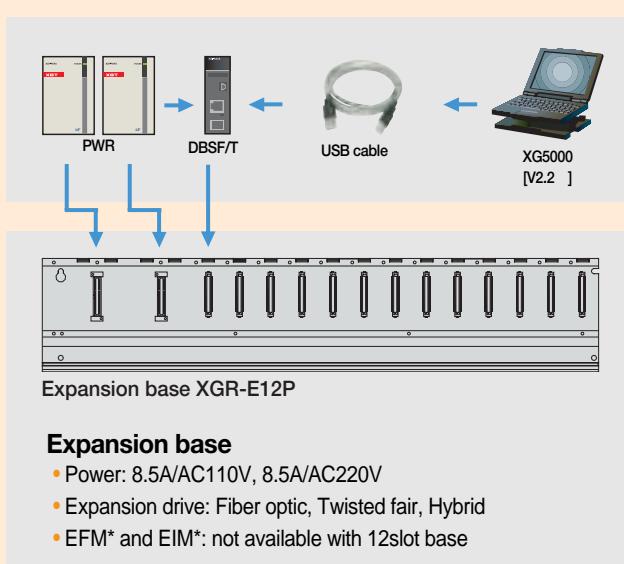
## Redundancy system / System configuration

### System configuration



#### Main base

- 2 types of CPU (Fiber optic, Twisted fair)
- Power: AC110V, AC220V
- 6slot base: enable to install 6 communication modules



#### Expansion base

- Power: 8.5A/AC110V, 8.5A/AC220V
- Expansion drive: Fiber optic, Twisted fair, Hybrid
- EFM\* and EIM\*: not available with 12slot base

CPU module	
Type	I/O point
XGR-CPUH/T [Twisted fair]	
XGR-CPUH/F [Fiber optic]	131,072 points
Type	I/O point
USB-301A	USB downloading cable
K1C-050A	RS232C downloading cable
XGC-F201	CPU synchronization cable: 2m
XGC-F501	CPU synchronization cable: 5m
Power	
XGR-AC12	110V 5.5A (Main base)
XGR-AC13	110V 8.5A (Expansion base)
XGR-AC22	220V 5.5A (Main base)
XGR-AC23	220V 8.5A (Expansion base)

Base		
XGR-M06P	6Slot [Main base]	
XGR-E12P	12Slot [Expansion base]	
Expansion drive		
XGR-DBST	Fiber optic - Fiber optic	
XGR-DBSF	Twisted fair - Twisted fair	
XGR-DBSH	Twisted fair - Fiber optic	
Item		
Input module		
	AC110V	AC220V
8 points	-	XGI-A21A
	XGI-A12A	-
16 points	-	-
	-	XGI-D22B
32 points	-	-
	-	XGI-D24A
64 points	-	-
	-	XGI-D24B
	-	XGI-D28A
	-	XGI-D28B
Item		
Output module		
	Relay	Triac
8 points	XQQ-RY1A	-
	XQQ-RY2A	XQQ-SS2A
16 points	XQQ-RY2B	-
	-	XQQ-TR2B
32 points	-	-
	-	XQQ-TR4A
64 points	-	-
	-	XQQ-TR4B
	-	XQQ-TR8A
	-	XQQ-TR8B
Item		
Input/Output mixed module		
	16-point DC input	16-point TR output
Special module		
Analog input	XGF-AV8A	Voltage input type, 8Ch
	XGF-AC8A	Current input type, 8Ch
	XGF-AD8A	Voltage/ Current input, 8Ch
	XGF-AD4S	Voltage/ Current input, 4Ch (Isolated)
	XGF-AD16A	Voltage/ Current input, 16Ch
Analog output	XGF-DV4A	Voltage output type, 4Ch
	XGF-DC4A	Current output type, 4Ch
	XGF-DV8A	Voltage output type, 8Ch
	XGF-DC8A	Current output type, 8Ch
	XGF-DV4S	Voltage output, 4Ch (Isolated)
High-speed counter	XGF-DC4S	Current output, 4Ch (Isolated)
	XGF-HO2A	Pulse (OC) input type, 2Ch
	XGF-HD2A	Pulse (LD) input type, 2Ch
	XGF-PO3A	Pulse (OC) output type, 3 axes
	XGF-PO2A	Pulse (OC) output type, 2 axes
Positioning	XGF-PO1A	Pulse (OC) output type, 1 axis
	XGF-PD3A	Pulse (LD) output type, 3 axes
	XGF-PD2A	Pulse (LD) output type, 2 axes
	XGF-PD1A	Pulse (LD) output type, 1 axis
	XGF-TC4S	Thermocouple input, 4Ch
Temperature control	XGF-RD4A	RTD input, 4Ch
	XGF-RD4S	RTD input, 4Ch (Insulated)
	XGF-TC4UD	Temperature controller, 4 loops, Universal input
Communication module		
RapiNet	XGL-EIMT	RapiNet Twisted fair 2Ch
	XGL-EIMH	RapiNet Fiber optic/Twisted fair 1Ch
	XGL-EIMF	RapiNet Fiber optic 2Ch
	XOL-EIMT	RapiNet Twisted fair 2Ch For PC
Cnet	XOL-EIMF	RapiNet Fiber optic 2Ch For PC
	XGL-CH2A	RS-232C/RS-422
	XGL-C22A	RS-232C, 2Ch
	XGL-C42A	RS-422, 2Ch
Ethernet (Open)	XGL-EFMF	Fiber optic, Master, SC type
	XGL-EFMT	Twisted pair, Master, RJ-45
	XGL-ESHF	Fast Ethernet, Industrial Ring module
	XGL-EHST	Fast Ethernet, Switching hub
Ethernet (Dedicated)	XGL-EDMF	Fiber optic, Master, SC type
	XGL-EDMT	Twisted pair, Master, RJ-45
Rnet	XGL-RMEA	Rnet, Master, TP
DeviceNet	XGL-DMEA	DeviceNet, Master
Profibus-DP	XGL-PMEA	Profibus-DP, Master

## Specification

Item		Description		Remark
		XGR-CPUH/F	XGR-CPUH/T	
Media		Fiber optic	Twisted pair	
Operation method		Cyclic execution, Periodic operation, Interrupt operation, Fixed scan		
I/O control method		Scan synchronized batch processing method (Refresh method)		
Program language		LD (Ladder Diagram), ST (Structured Text), SFC (Sequential Function Chart), IL (Read only)		
Number of Standard function Instructions	Operator Standard function block	18 130 + Real type function 41		
Processing speed	Special function/ function block	Special function block, Process control function block		
Real type	LD	0.042 $\mu$ s/Step		
	MOV	0.126 $\mu$ s/Step		
		$\pm$ : 0.602 $\mu$ s(S), 1.078 $\mu$ s(D) x : 1.106 $\mu$ s(S), 2.394 $\mu$ s(D) $\div$ : 1.134 $\mu$ s(S), 2.66 $\mu$ s(D)		S: Real type D: Long real type
I/O points		23,808 points (31 stage *12 slot *64 points)		
I/O memory		I: 131,072 points, Q: 131,072 points (Total: 1131,072)		
DRAM	Program memory	7MB		Including Upload, Parameter, System area
	Data memory	2MB		
	Reserved memory	7MB		*Battery back-up memory: 8MB
Flash memory		16MB		
Data memory	Direct variable	256k Byte		
	Auto allocated variable	512k Byte		
	Timer	No limitation, Range: 0.001sec ~ 4,259,967.295sec (1,193hours)		
File register	Counter	No limitation, Range: -32,768 ~ +32,767		
	System	4k Byte		
	Flag	64k Byte		L, N area
	Communication	64k Byte		
	Special	2k Byte (32 base, 16 slot, 32 channel )		U area: Analog device area
Program		64k Byte *2		R area: read/write (Command, XG5000)
Operation mode	Number of program blocks	256		
	Initial task	1 (_INT)		
	Cycle task	32		
	Internal device task	32		
Restart mode		RUN, STOP, DEBUG		
Self diagnostic functions		Warm, Cold		
Program download		Watchdog timer, Memory error, I/O error, Battery error, Power Supply error		
Data retain		RS-232C (1CH), USB (1CH)		
Max. expansion base		Auto allocated variable: set by variable definition Direct variable: set by parameter 31 stages		

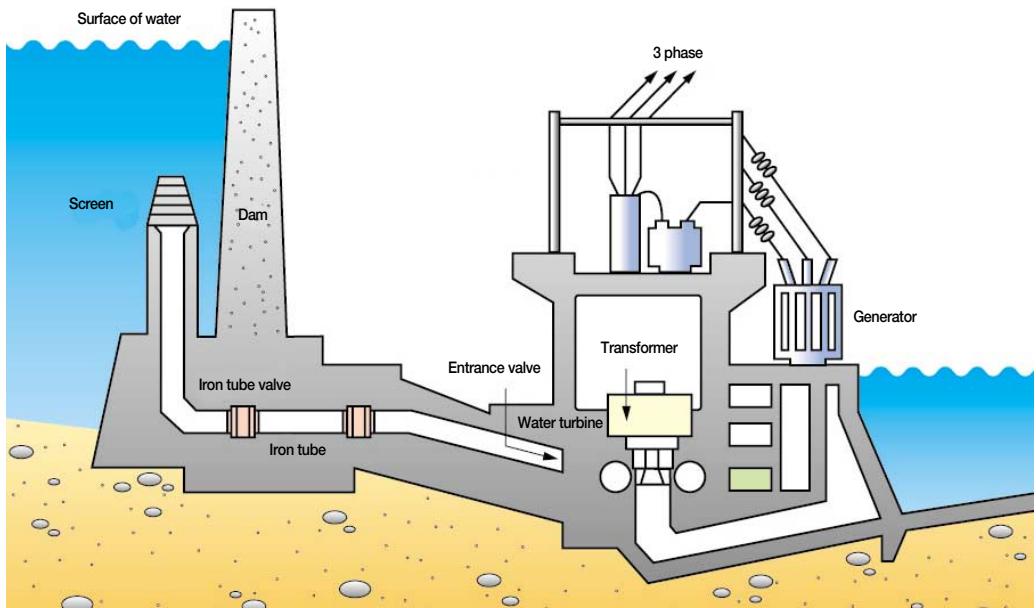
## Specification

Item		Hardware		Remark
CPU module		2 slot / Fiber, Twisted fair		
Expansion drive module		1 slot / Fiber, Twisted fair, Hybrid		
Base		Main base: 6 slot, Expansion base: 12 slot		
Power	AC110V		5V-5.5A	
	AC220V		5V-5.5A	
	AC110V		5V-8.5A	
	AC220V		5V-8.5A	
Expansion method and Max. expansion base		31 stages by network		
Base number setting		Rotary switch of expansion drive module		
Distance between expansion bases		Twisted fair: 100m (3km), Fiber: 2km (60km)		
Master/Standby switching over time		50ms or less		

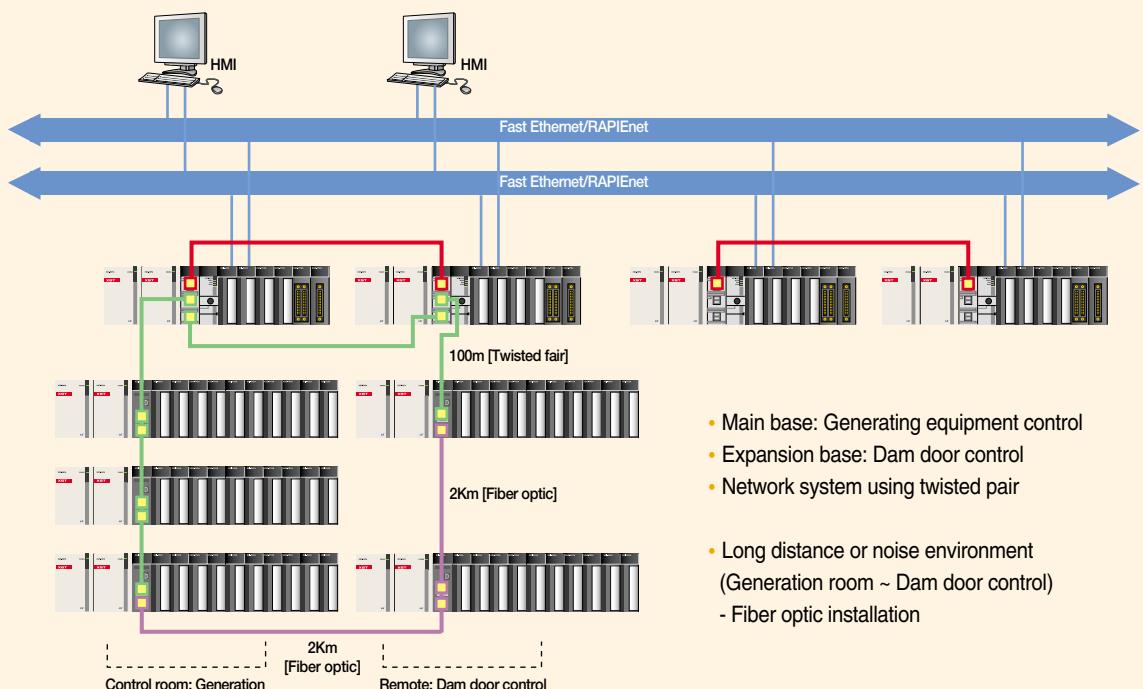
## Available modules for each base

	Base	Available modules
1	Main base	CPU, Ethernet module (XGL-EFMx), RAPIEnet module (XGL-EIMx) * x: T (Twisted fair), F (Fiber optic), H (Hybrid)
2	Expansion base	I/O modules for XGI (Ethernet based communication module should be installed on Main base) Number of communication module: 12 for High-speed link, 8 for P2P Number of analog module: Analog input (139), Analog output (250)

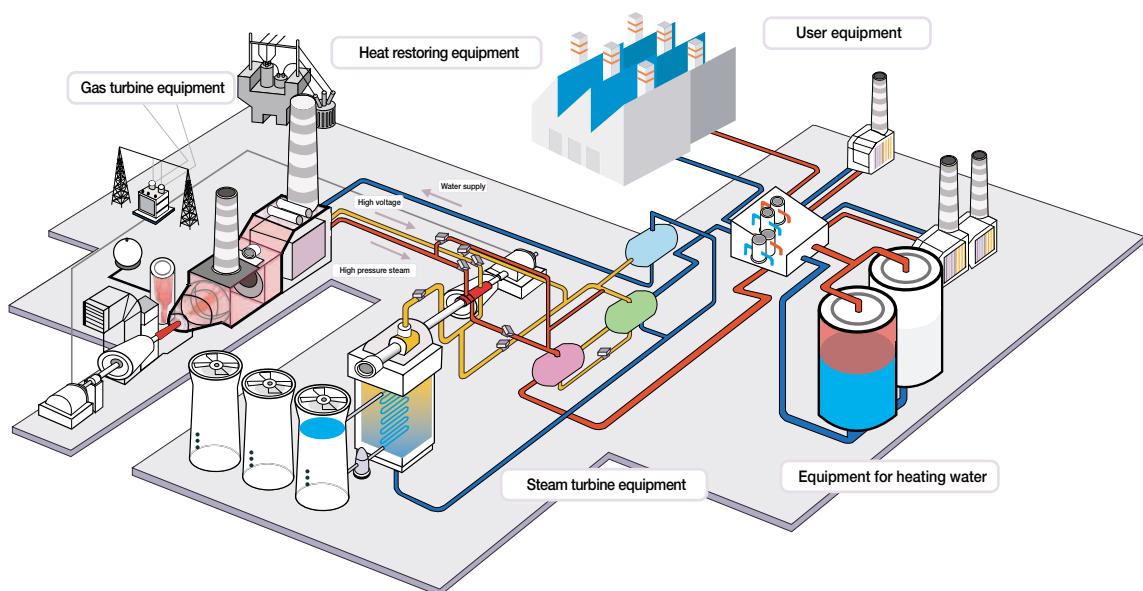
### Water power generation or Dam door control



### System configuration

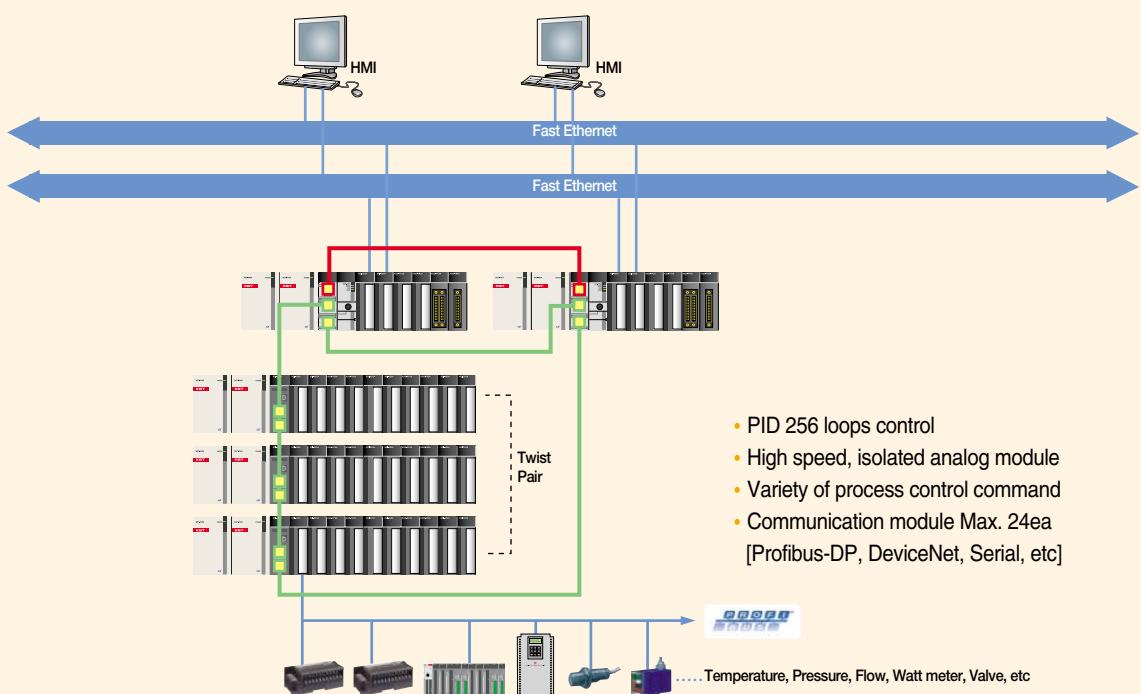


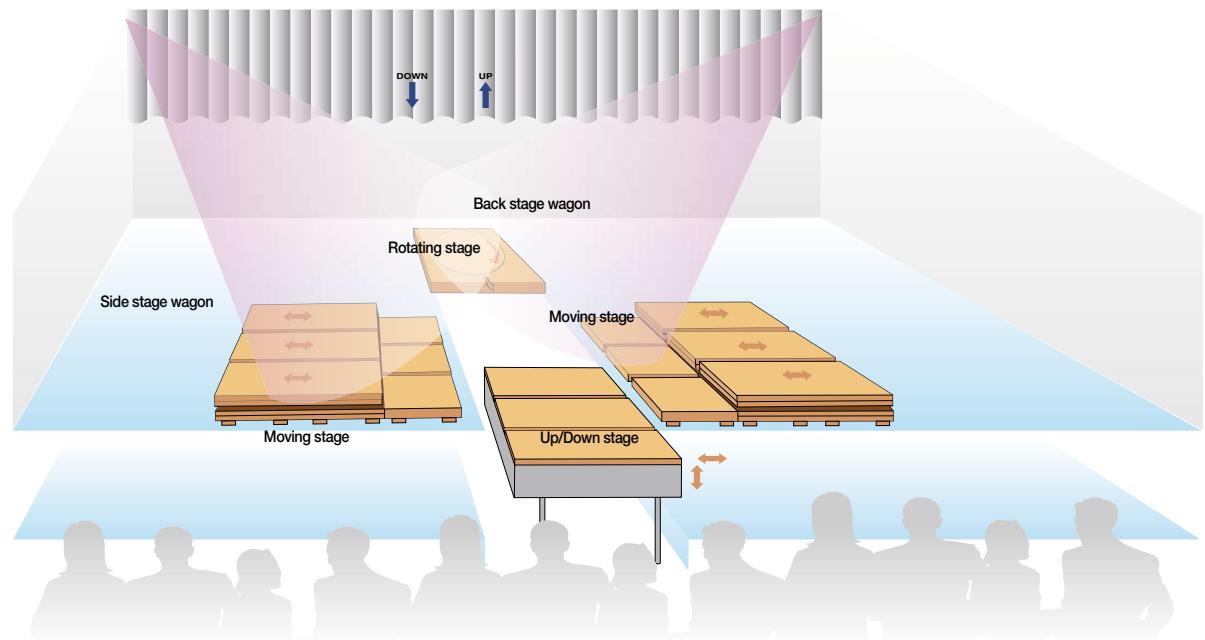
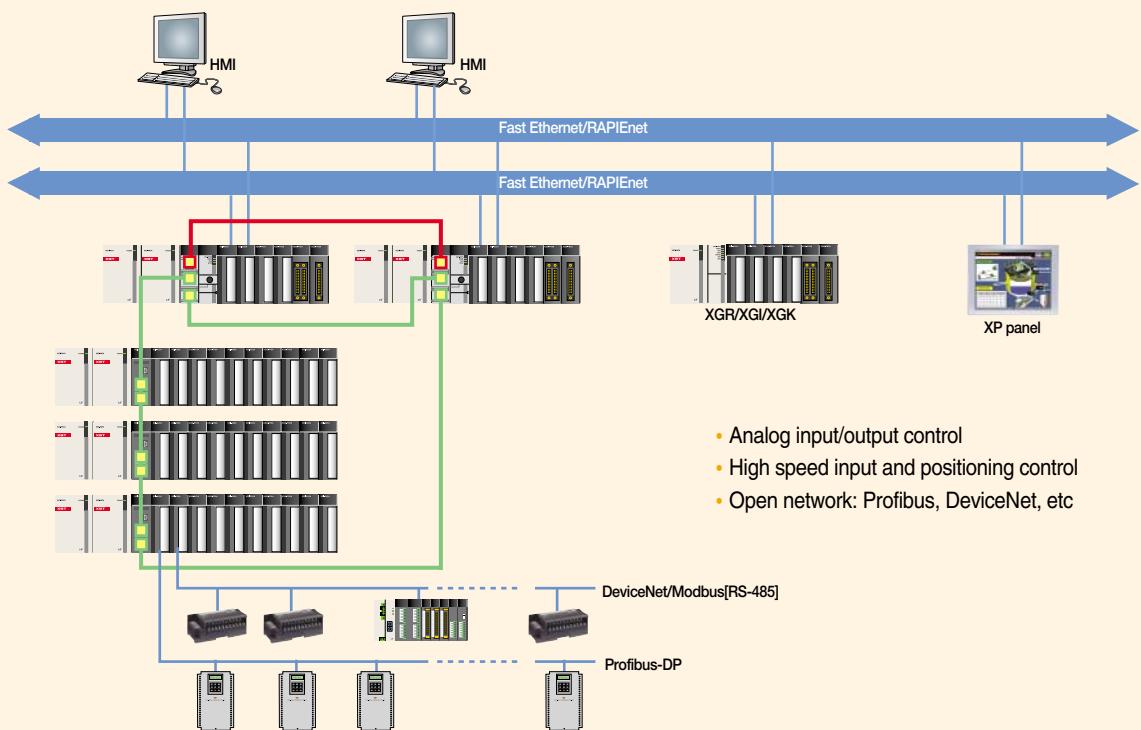
## Generating boiler control



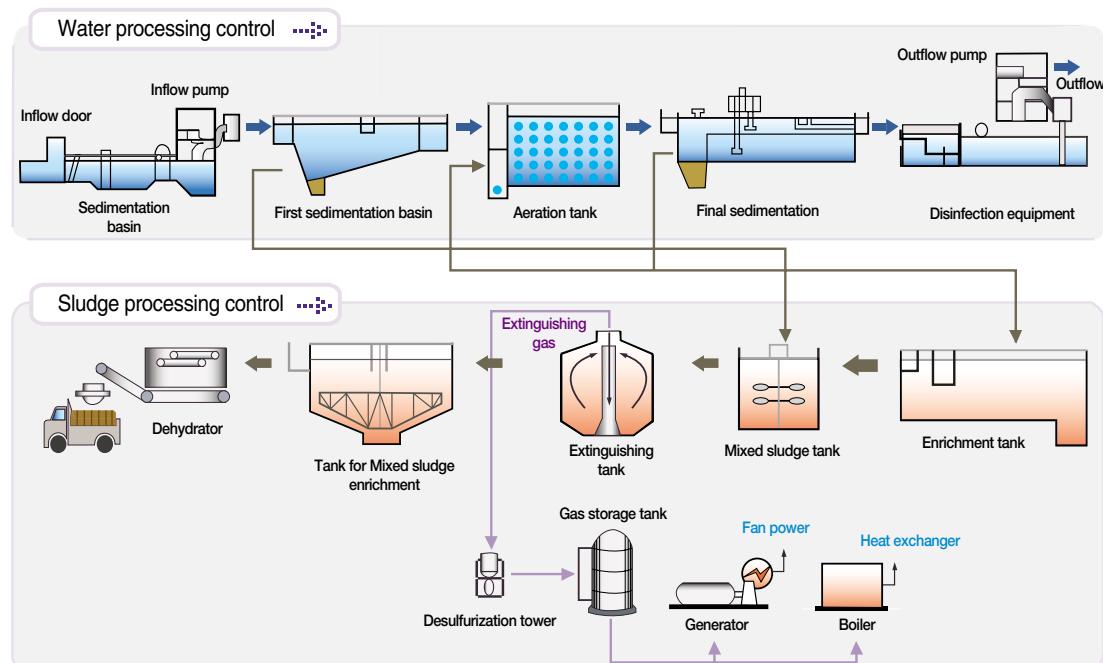
System

## System configuration



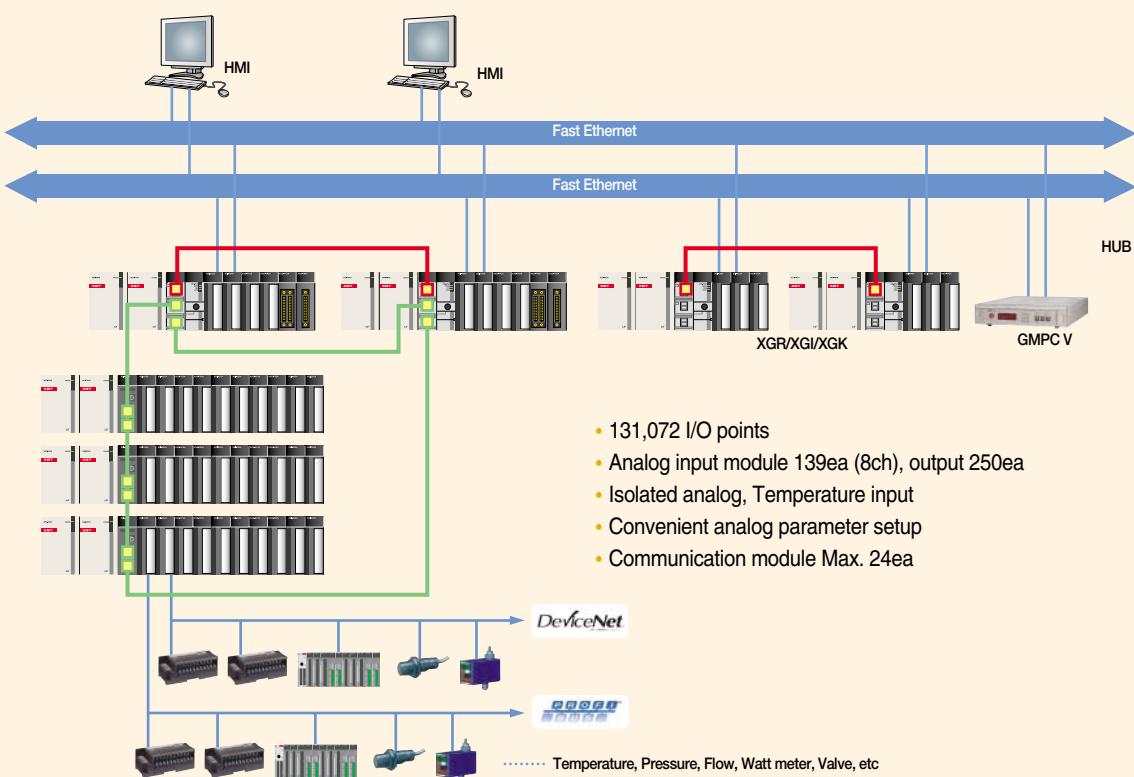
**Stage control****System configuration**

## Water processing control

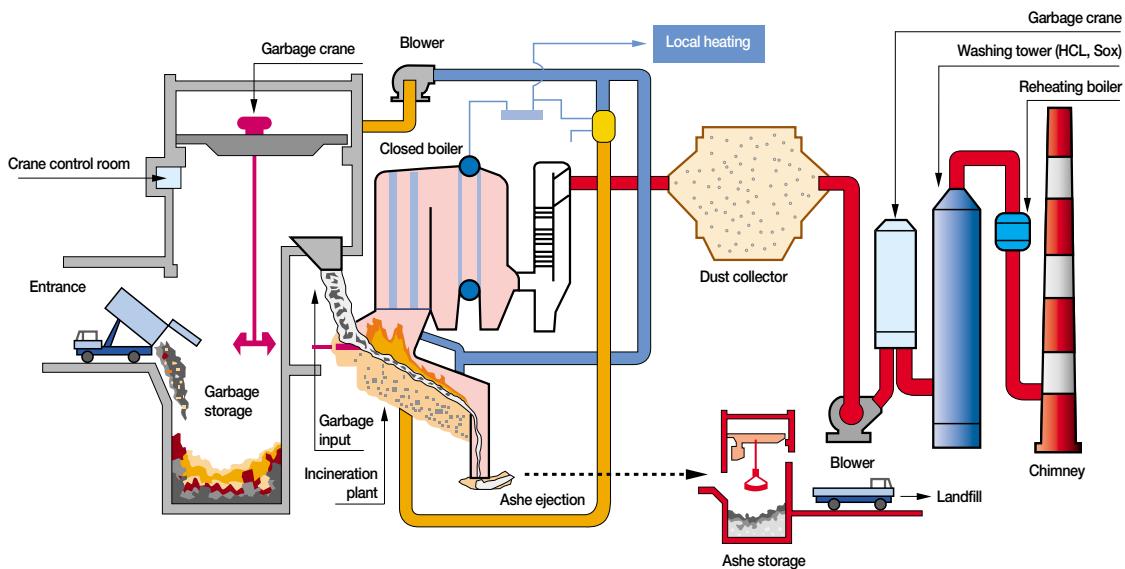


System

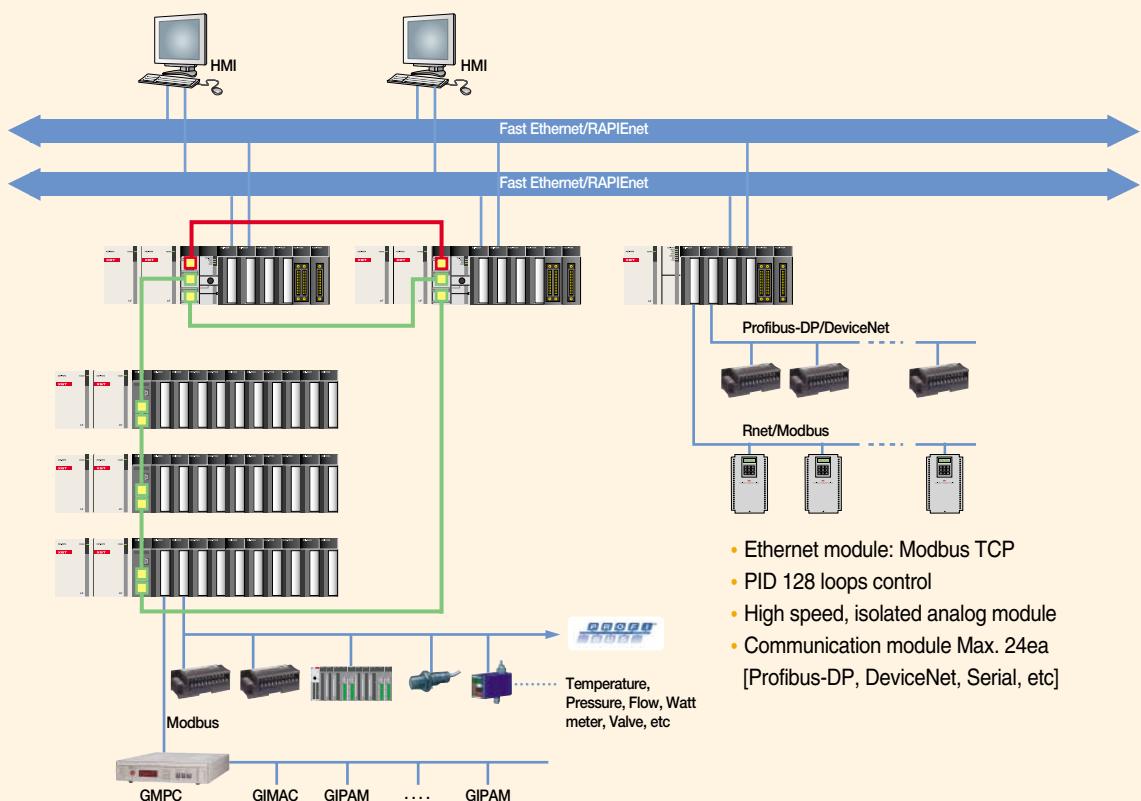
## System configuration



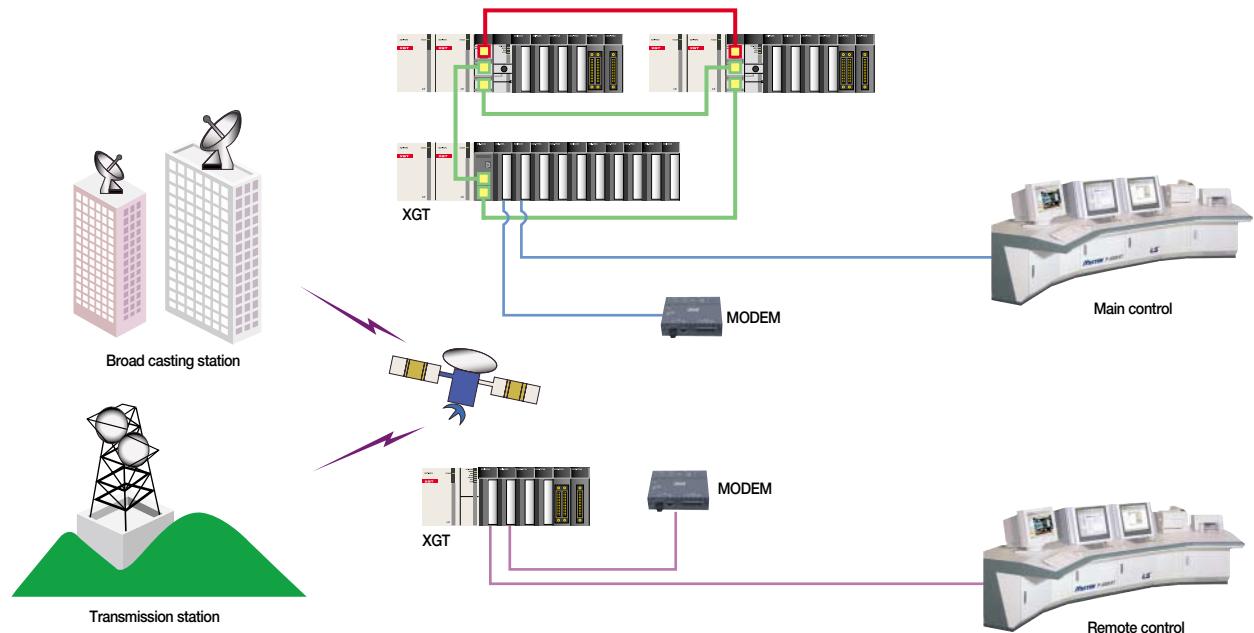
### Incinerator control



### System configuration

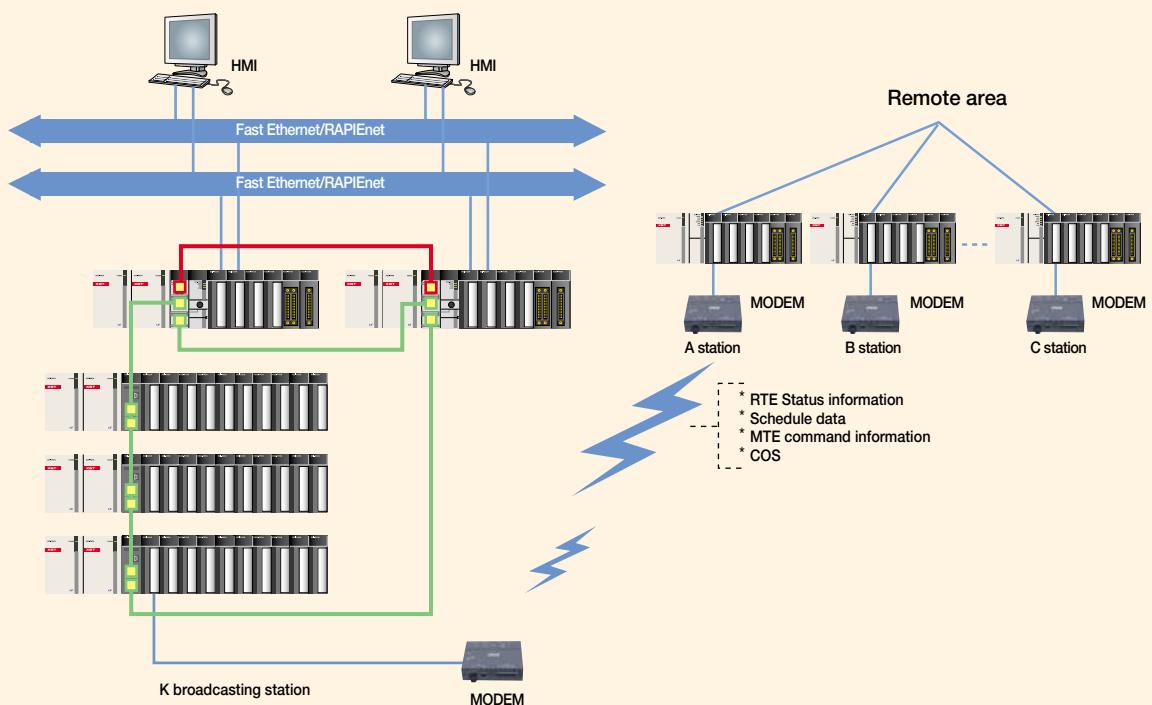


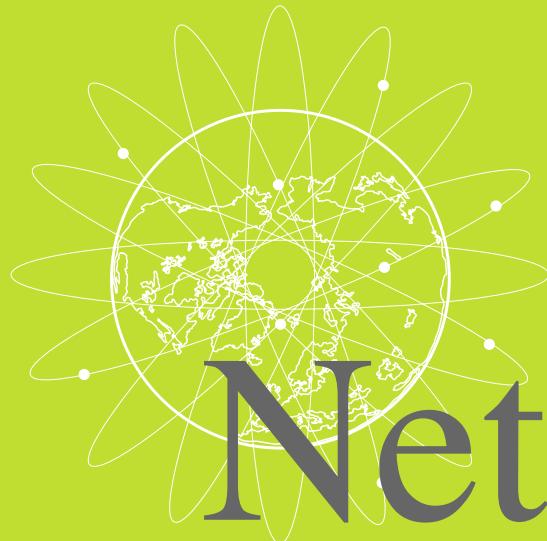
## Broad casting system



System

## System configuration





# Network

Along with Ethernet, Profibus-DP, and DeviceNet, XGT series provide the maximum in control integration and communication flexibility.



**XGT****RAPIEnet**

- Communication speed: 100Mbps
- Dual port [T.Pair/F.Optic/Hybrid]
- Built-in high performance industrial switch
- Cyclic Communication[Broadcast Service]
  - 1block:200word
  - Send 64block / Receive 128block
- Event Communication[Peer to Peer Service]

**XGT Fast Ethernet**

- 10/100Mbps Industrial high-speed Ethernet
- 10/100Base-TX, 100Base-FX (Optical)
- Open Ethernet (FEnet) and LSIS dedicated Ethernet (FDEnet)
- High reliability and performance with 32-bit processor
- Various connection to MMI S/W (XGT, MODBUS/TCP)

**XGT Cnet**

- RS-232C/485/422 communication
- Long-distance communication via modem connection
- Various connection to MMI S/W (XGT, MODBUS RTU, MODBUS ASCII)
- User-defined communication support
- Convenient P2P master (XGT, MODBUS)

**XGT Rnet**

- Communication speed: 1Mbps
- Communication distance: Max. 750m
- Max. 6 repeaters (up to 5.25km)
- Network management using Auto-scan (Slave module information)

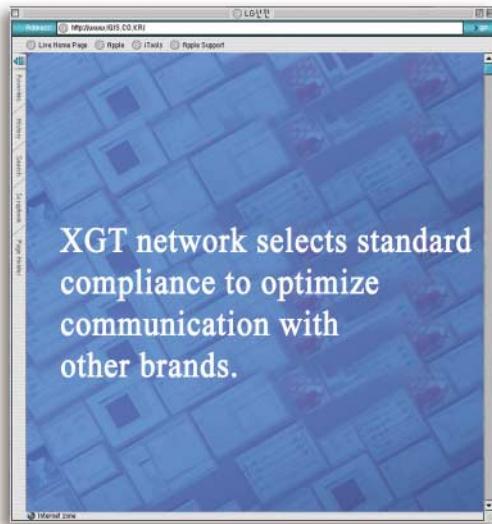
**XGT Dnet (DeviceNet)**

- Connectable to other PLCs and devices
- Compliance of the ODVA standard
- Flexible communication speed setting: 125/250/500Kbps
- Multi-drop and T branch connection
- Communication distance: Max. 500m
- Convenient parameter setting through SyCon/HS link parameter

**XGT Pnet (Profibus-DP)**

- Optimum communication for a master automation device and distributed slave I/O devices
- Fast slave communication omitting application layer
- Communication distance: Max. 1200m
- Convenient parameter setting through SyCon/HS link parameter

## Features

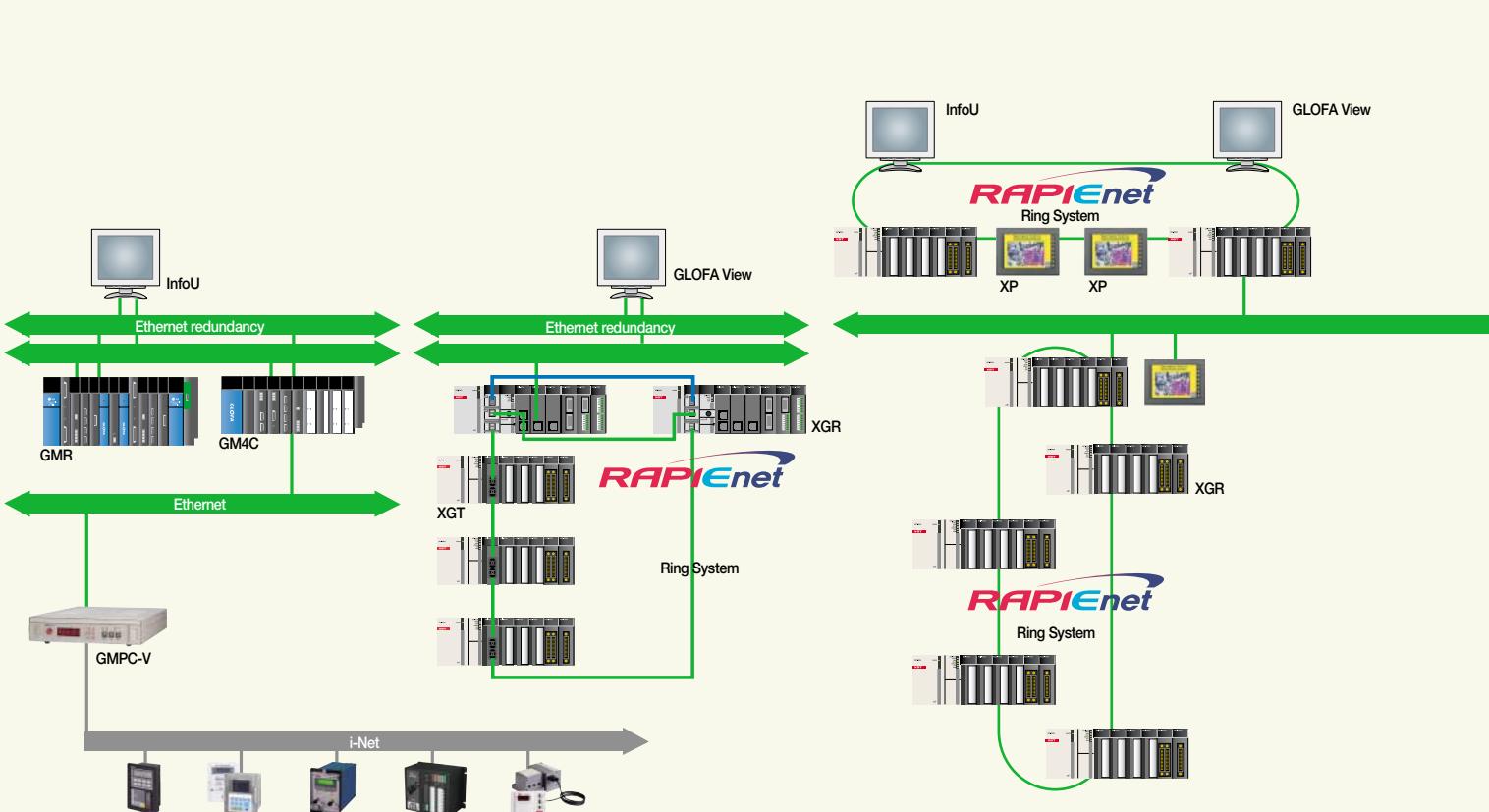


### RAPIDnet

- Communication speed: 100Mbps
- Dual port (T.Pair / F.Optic / Hybrid)
- Built-in high performance industrial switch
- Cyclic Communication (Broadcast Service)
  - 1block:200word
  - Send 64block / Receive 128block
- H/W based Dual port Full duplex Switching
- Real-time / Non real-time service

### XGT Fast Ethernet

- 10/100Mbps Industrial high-speed Ethernet
- 10/100Base-TX, 100Base-FX (Optical)
- Open (Information level) Ethernet: FEnet
- LSIS dedicated (Between LS PLCs) Ethernet: FDEnet
- High reliability and performance with 32-bit processor
- Various connection to MMI S/W (XGT, MODBUS)
- Enhanced network diagnosis



**XGT Cnet**

- RS-232C/485/422 communication
- Long-distance communication via modem connection dedicated line modem connection
- Various connection to MMI S/W (XGT, MODBUS RTU, MODBUS ASCII)
- User-defined communication
- Convenient P2P master (XGT, MODBUS)

**XGT Rnet**

- High-speed communication: 1Mbps
- Long communication distance: Max. 750m
- Max. 6 repeaters (up to 5.25km)
- Network management using Auto-scan (Slave module information)

**XGT Dnet (DeviceNet)**

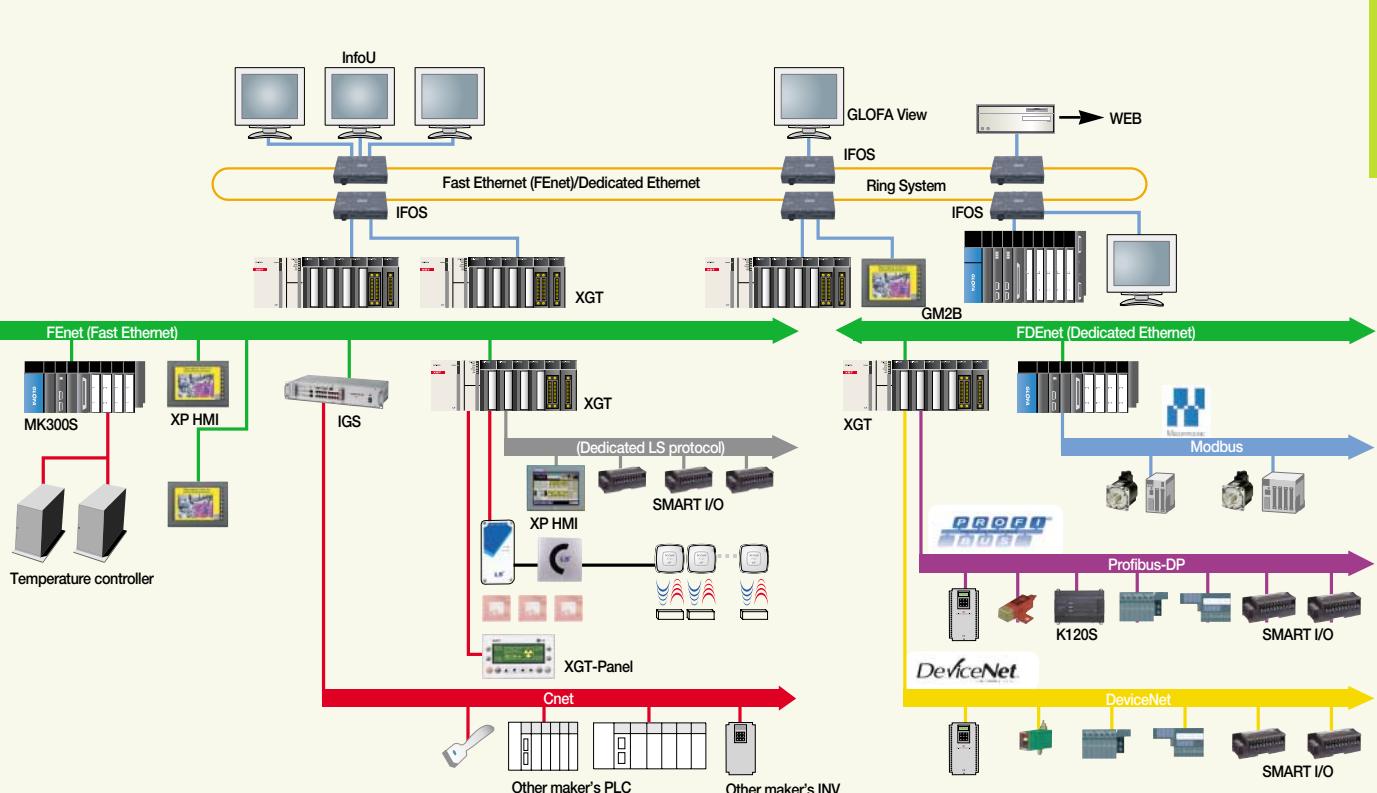
- Connectable to other PLCs and control device
- Compliance of the ODVA standard
- Flexible communication speed setting: 125/250/500Kbps
- Multi-drop and T branch connection
- Long communication distance: Max. 500m

**XGT Pnet (Profibus-DP)**

- Optimum communication for a master automation device and distributed slave I/O devices
- Fast slave communication omitting application layer
- Long communication distance: Max. 1200m
- Communication using High-speed link parameter

**No. of network module available**

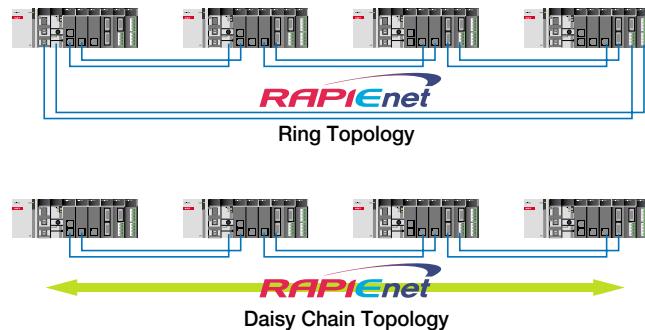
Item	XGK / XGI / XGR CPU
Total network module	24
High-speed link module	12
P2P service	8



## Features

### 100Mbps Dual Port Ethernet

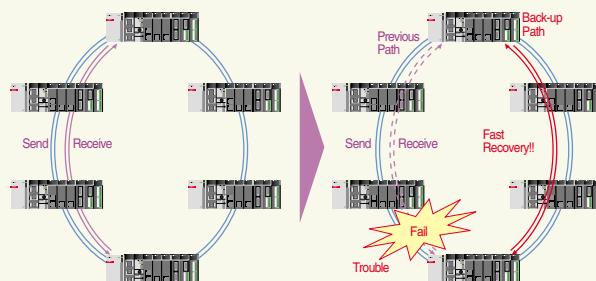
- Communication speed: 100Mbps
- Dual port (T.Pair / F.Optic / Hybrid)
- Built-in high performance industrial switch
- Cyclic Communication (Broadcast Service)
  - 1block: 200word
  - Send 64block / Receive 128block
- Event Communication (Peer to Peer Service)



### Hardware based Full duplex switching

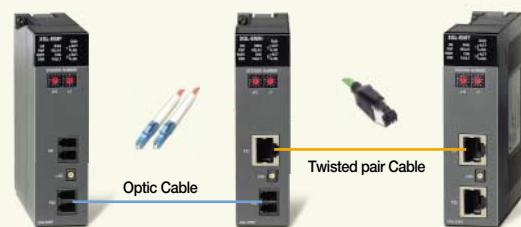
- Dual port full duplex switching  
(Forwarding/Receiving)
- Real-time / Non real-time service (Frame )

## Redundancy System



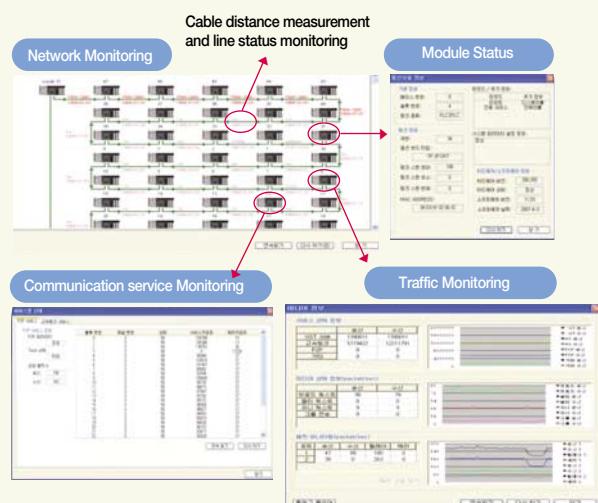
## Hybrid System

- Twisted pair, Fiber optic, Hybrid(T.P+F.O)



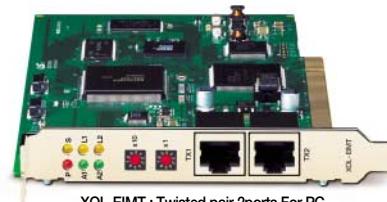
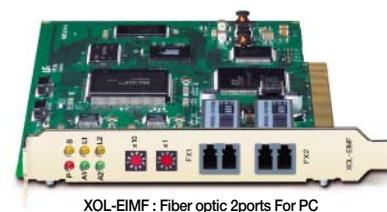
## Intelligent Diagnostic Functions

- Alarm for station number collision
- Cable distance measurement (Twisted fair cable)
- Convenient wiring using auto cross over
- Various diagnosis and Network status information
  - (a) CPU status
  - (b) Communication module status
  - (c) Communication service
    - (HS link, Dedicated service, P2P) status
  - (d) Auto scan function to supply module information within the network
  - (e) Packet and Data ring monitoring receiving to Communication module
  - (f) Module diagnosis via network



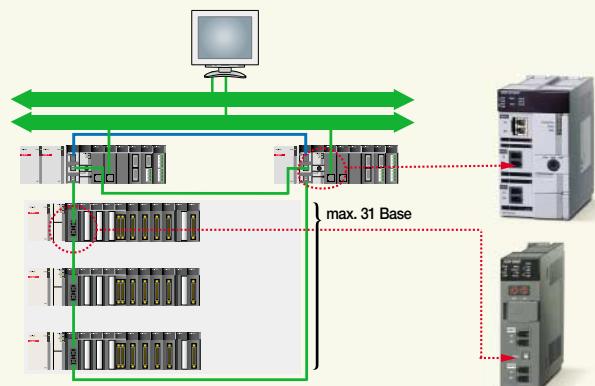
## Specification

Item		Specification	
		100BASE-FX	100BASE-TX
Transmission	Transmission speed	100Mbps	100Mbps
	Media	Fiber optic	Twisted pair
	Transmission method	Base band	Daisy Chain, Ring topology
	Topology	2km	100m
	Distance (Node to node)	128km	6,400m
	Max. Node	64 nodes	
	Max. Protocol	1,516bytes	
	Media access method	CSMA/CD	
	Frame error check	CRC 32 = $X^{32}+X^{25}+X^{23}+\dots+X^2+X+1$	
	Max. Number of installation	For PLC 12	For PC 1
	Mountable slot	For PLC Main base ~ 7 <sup>th</sup> Expansion base (XGK-CPUH/XGI-CPUU) Main base ~ 3 <sup>rd</sup> Expansion base (XGK-CPUS/CPUA) Main base ~ 1 <sup>st</sup> Expansion base (XGK-CPUE)	For PC PCI slot
Communications device	Communication method	P2P	High speed link
	Data block	Client / Server 700word x 64Block	Multicast, Unicast 12,800word
	Data per block	700word	6,400word
	PLC ↔ PLC	•	•
Fail Safe	PLC ↔ PC	Available soon	•
	Dual communication line	•	
Network diagnosis	Recovery Time	Within 10m	
	Bypass of the fail station	•	
	Cable distance measurement	•	
PADT	Station number collision detection	•	
Dimension (mm)	For PLC	98(H) x 27(W) x 90(D)	
	For PC	18(H) x 120(W) x 174(D)	
Current consumption (mA)	For PLC	Twisted pair: 330, Fiber optic: 670, Mixed: 510	
	For PC	Twisted pair: 630, Fiber optic: 630	
Wight (g)	For PLC	Twisted pair: 102, Fiber optic: 109, Mixed: 105	
	For PC	Twisted pair: 104, Fiber optic: 128	



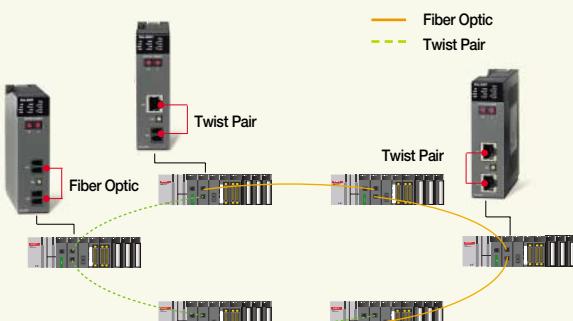
## Redundancy rack type expansion system

- Built-in type for CPU (Redundancy CPU)
  - Max. 31expansion base
- Easy installation
  - Base Auto scan
  - Analog module setup with I/O parameter
  - Easy programming for analog using global variable
  - Max. 24 communication module
- Long distance expansion (Fiber optic: 2km) and loader connection
- Twisted pair/ Fiber optic/ Mixed type communication modules for various system environment

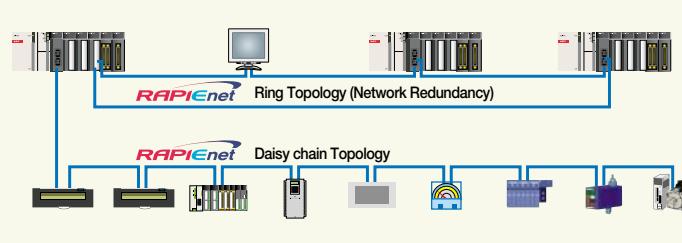


## Controller Level communication

- XGK/XGI/XGR PLC2PLC communication
- Enable to configure Daisy chain without External switch
- Service periodic: within 5ms



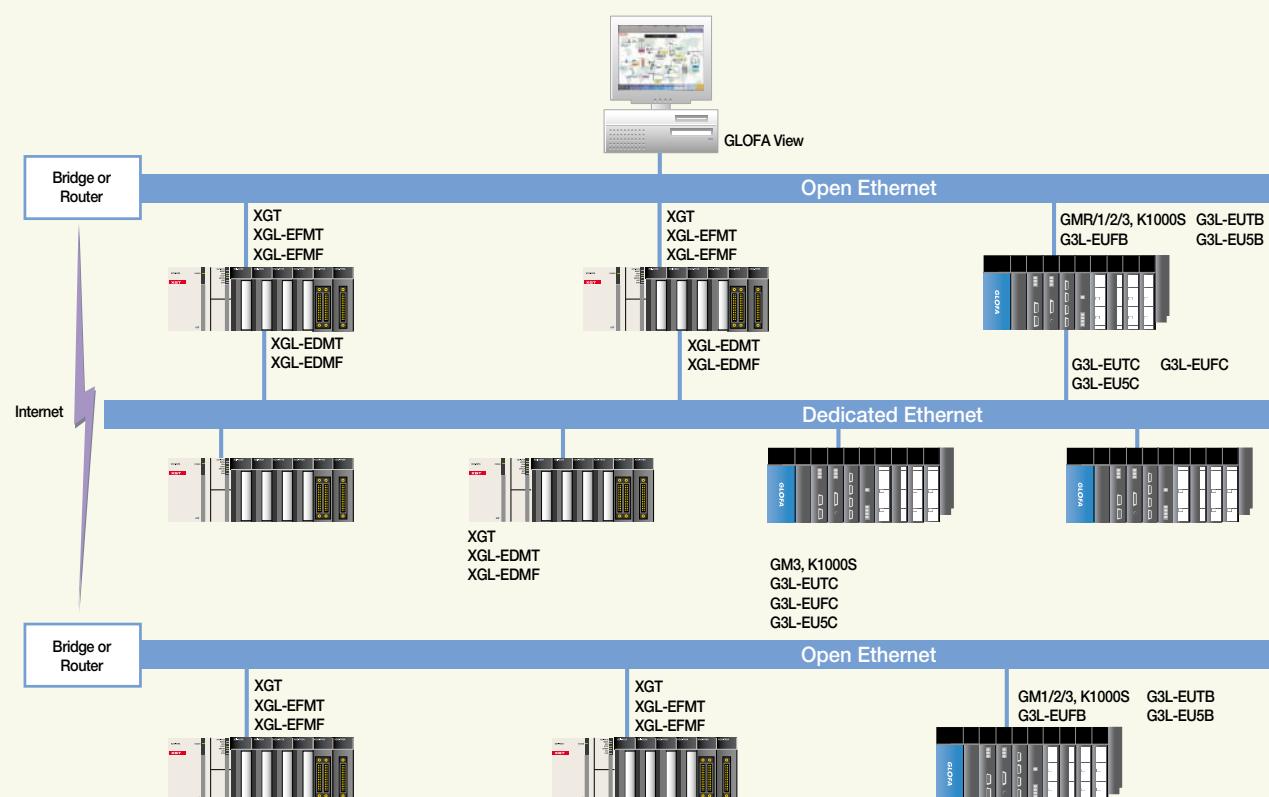
## System configuration



## Network / XGT Ethernet system

### Features

- 10/100Mbps industrial high-speed Ethernet (IEEE802.3)
- High-speed link block (Send 32blocks, Receive 128blocks)
- 10/100Base-TX, 100Base-FX (Fiber optic)
- Open Ethernet and Dedicated protocol
- High performance by 32bit processor
- Remote connection via XG5000
- Module reset function
- Modbus TCP protocol
- Network diagnosis via auto scan
- Easy network configuration and setup via XG-PD
- User defined protocol and P2P service
- PING Test function
- Communication information for services  
(High speed link, Dedicated service, Media status)



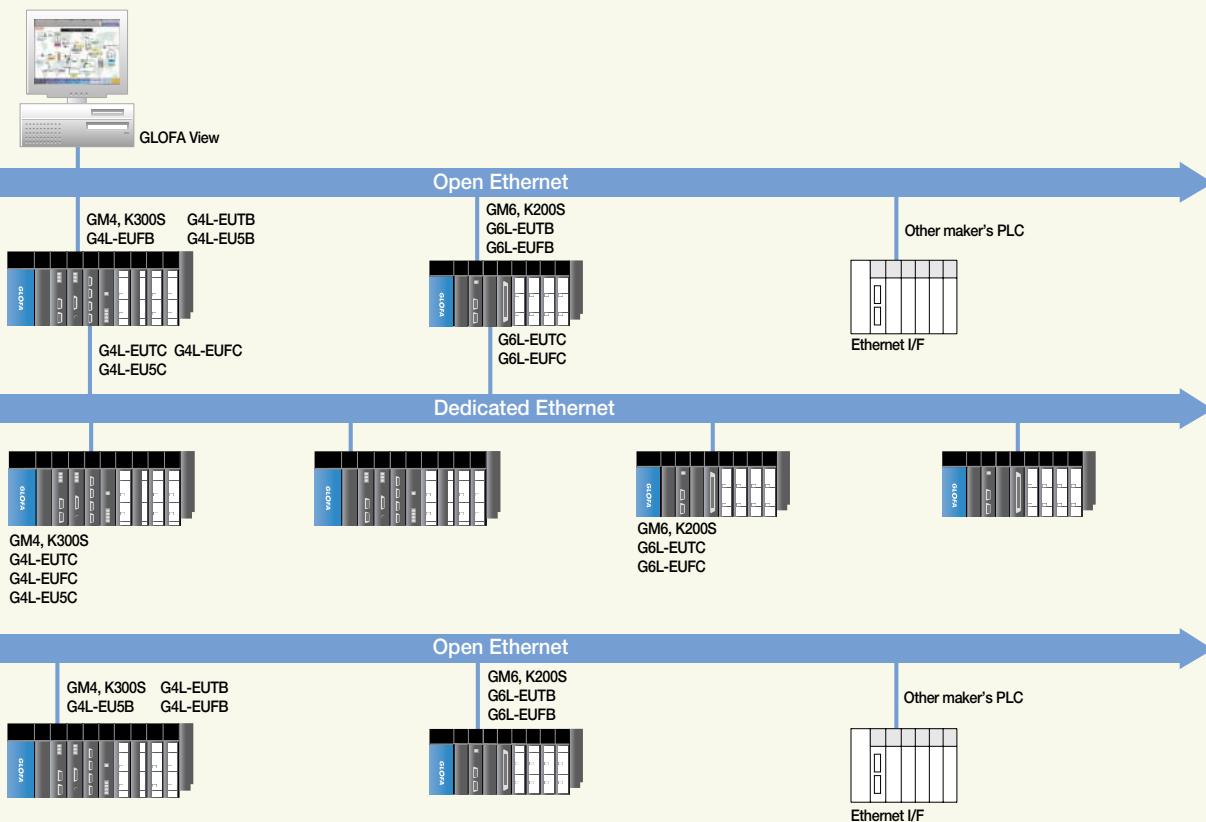
## Specification

### Open Ethernet

Item	XGL-EFMT	XGL-EFMF
Communication spec.	10/100 BASE-TX	100 BASE-FX, Fiber Optic
Protocol	TCP/IP, UDP/IP	
Service	With LS PLCs With other devices Application	High-speed link, P2P service P2P service Dedicated protocol service, XG5000 service, E-Mail service
HS link sending/receiving data		200 words/block (Max. 128 blocks)
No. of channel connectable to upper stage		16 channels
General use		Communication with PC (HMI) and external devices, High-speed communication among LSIS PLCs
Purpose	UTP/STP Category 5	62.5/125 $\mu$ m, Multi-mode, SC connector
Current consumption (mA)	410	630
Weight (kg)	0.11	0.15

### Dedicated Ethernet

Item	XGL-EDMT	XGL-EDMF
Communication spec.	10/100 BASE-TX	100 BASE-FX, Fiber Optic
Protocol	Dedicated protocol	
Service	With LS PLCs With other devices Application	High-speed link, P2P service - XG5000 service
Sending/receiving data		200 words /block
No. of connection stations		64 stations
General use		High-speed link communication among LSIS PLCs
Purpose	UTP/STP Category 5	62.5/125 $\mu$ m, multi-mode, SC connector
Current consumption (mA)	410	630
Weight (kg)	0.11	0.15



## Network / XGT Industrial Optic Ring System

### Features

- 100Base-FX media
- Industrial high-speed Ethernet (IEEE802.3)
- High-speed link to communicate between LS PLCs
- High-speed block to link between modules
- High-speed link and Max. 16 P2P communication
- Loader service via Ethernet (XG5000): Dedicated TCP/IP port 2002
- Easy connection to other system using P2P and XG-PD
- Dedicated protocol and Modbus TCP
- DHCP (Dynamic Host Configuration Protocol)
- Access table to communicate with PC (HMI)



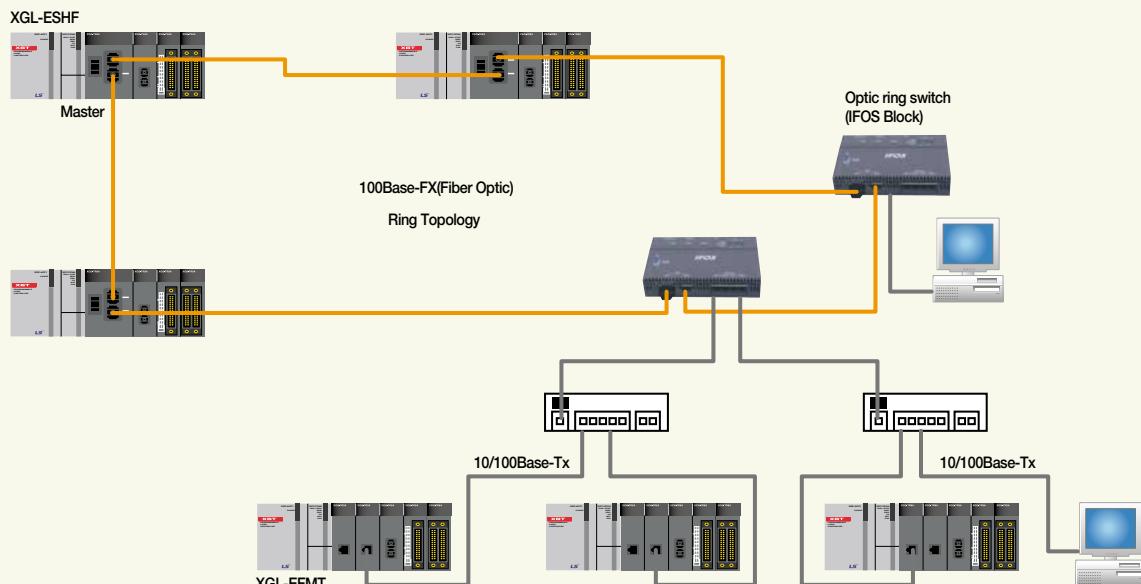
### Specification

	Item	XGL-ESHF(100BASE-FX)
Transmission	Communication speed	100Mbps
	Method	Base band
	Max. Distance(Node to node)	2km
	Max. Segment length	-
	Max. node	50ea / segment
	Distance (Node to node)	0.5m
	Max. Protocol size	1,500 bytes
	Media access method	CSMA/CD
	Frame error check	CRC 32
Current consumption (A)		1.2
Weight (g)		220g

### Fiber optic cable

Item	Description
Cable type	Twin strands of Multi mode fiber (MMF)
Connector	SC type
Diameter	62.5/125 $\mu$ m
Wave length	1,350nm
Diminution	Within 2dB/1,000m

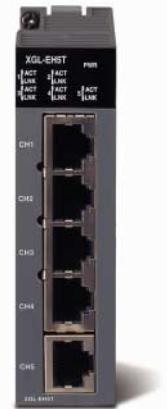
### System configuration



## Network / XGT Ethernet switching hub

### Features

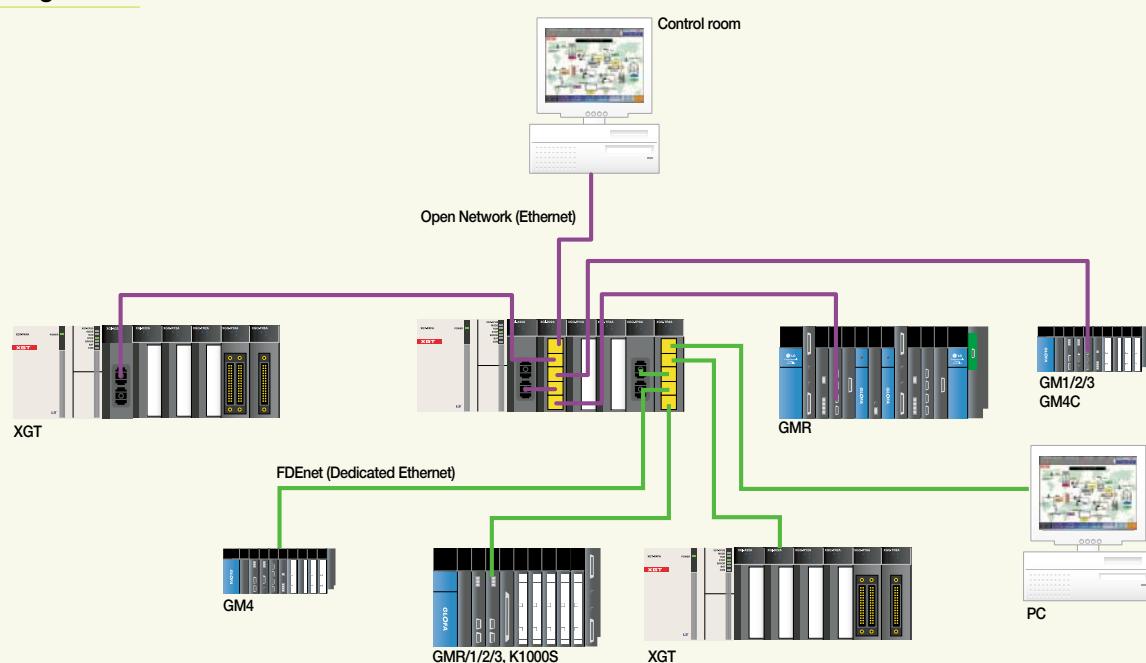
- Rack type: No external power
- Reliability for industrial standard
- Auto Crossover
- FG (Frame Ground) for RJ-45 connector
  - Decreased communication error by shielded FTP/STP cable



### Specification

Item		XGL-EH5T
Transmission	Communication speed	10/100Mbps
	Port type	10/100BASE-TX, TP cable, RJ-45 socket, 5ports
	Interface	Auto-Crossing, Auto-Nego., Auto-Polarity
	Distance	100m
	Diagnosis	LED (PWR, Link status, Data)
Current consumption (mA)		550
Weight (g)		90

### System configuration



## Network / Computer-Link

### Features

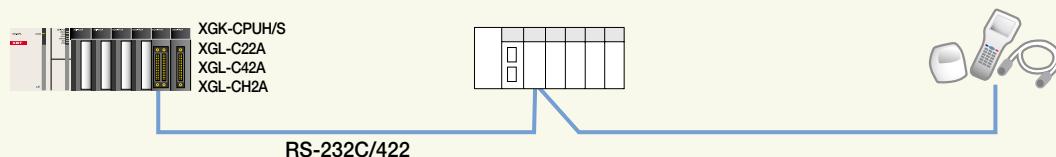
- Easy protocol editing and communication parameter setting: XG-PD
- Long-distance communication via modem connection
- Dedicated protocol for multi-drop configuration connectable up to 32 units
- RS-232C/422 communication port
- Flexible communication speed setting (300~115,200bps)
- Supporting full duplex and half duplex communication
- Max. 12 modules available in one CPU
- P2P service: User-defined communication and XGT/MODBUS master
- Various connection to MMI S/W (XGT, MODBUS RTU, MODBUS ASCII)
- Various diagnosis functions using XG-PD (I/O, link status, service status)
- Communication service information (Dedicated service, P2P service)
- Supporting simultaneously dedicated service in remote connection
- Communication without additional setting when replacing communication module

### Various independent operation mode

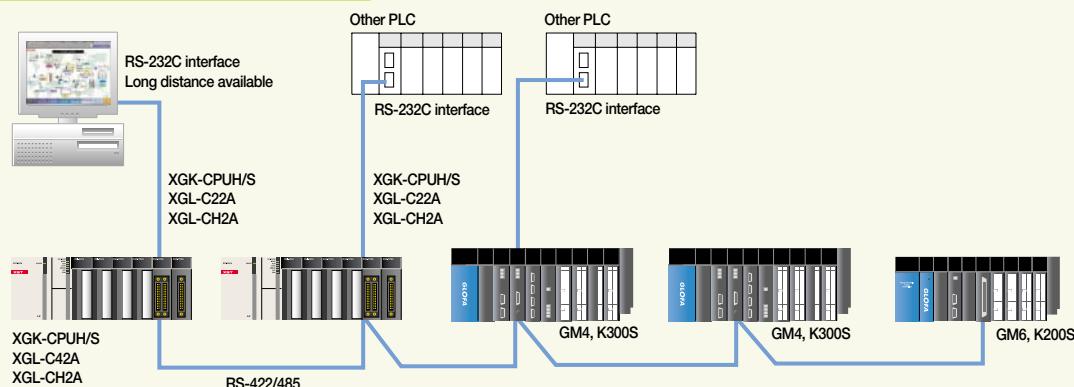
- Operation mode
- Dedicated protocol mode (Simultaneous support)
- Program upload/download by XG5000 protocol (RS-232C)  
Communication using LSIS dedicated protocol
- User-defined communication of P2P mode and XGT/MODBUS master



### Communication via RS-232C/422



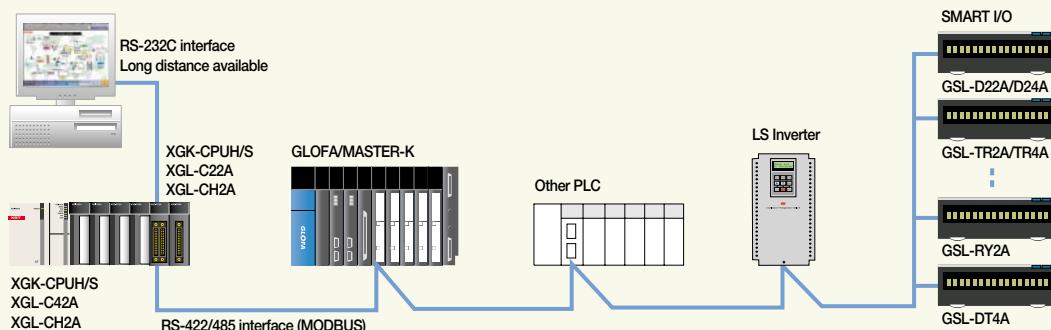
### 1: N and N: M connection (LSIS and other)



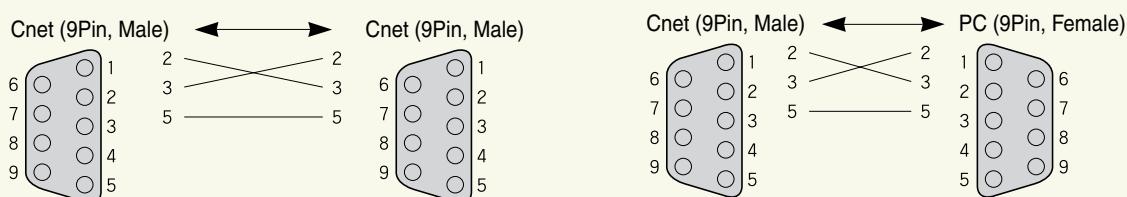
## Specifications

Item	Specifications				
	XGL-C22A	XGL-C42A	XGL-CH2A		
Interface	RS-232C, 2 channels	RS-422, 2 channels	RS-232C/RS-422, 1 channel		
Modem connection	Remote communication with external devices via modem connection. Available for only RS-232C port.				
Communication mode	Dedicated mode	1: 1 or 1: N communication using LSIS dedicated protocol			
	XG5000 mode	Program upload/download and remote control			
	P2P mode	Communication by protocol using XG-PD (Interface with other PLCs), XGT, MODBUS RTU/ASCII master communication			
Operation mode	Server (Slave)	Remote connection simultaneously using XGT/MODBUS Server, user-defined			
	Master	XGT, MODBUS RTU/ASCII master, user-defined			
Data type	Start Bit	1			
	Data Bit	7 or 8			
	Stop Bit	1 or 2			
	Parity	Even/Odd/None			
	Setting	Basic parameter setting with XG-PD			
Synchronization	Asynchronous				
Transmission speed (bps)	Selectable among 300/600/1,200/2,400/4,800/9,600/19,200/38,400/57,600/115,200 bps				
Station number setting	Up to 32 stations from 0 to 31 with XG-PD				
Transmission distance	RS-232C: Max. 15m (Extendible by using modem), RS-422/485: Max. 500m				
Modem communication	Available	Not available	Available via RS-232C		
Network configuration	RS-232C 1: 1, RS-422 1: 1, 1: N, N: M				
Diagnosis function	Available through LED and XG-PD diagnosis service				
Max. number of installation	12				
Current consumption (mA)	310	300	310		
Weight (Kg)	0.12	0.12	0.12		

## MODBUS



## Cnet cable connection

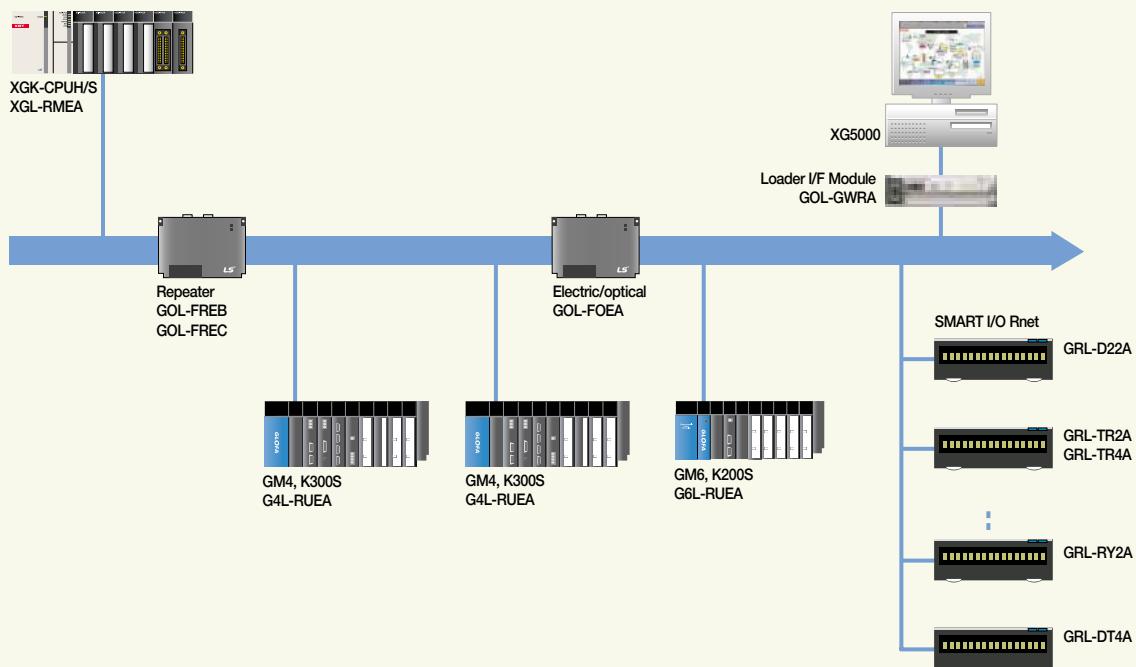


## Features

- Communication speed: 1Mbps
- Communication distance: Max. 750m
- Available to use max. 6 repeaters (Up to 5.25Km)
- Network management using Auto-scan (Slave module information)
- Multi-drop network with smart I/O
- Network diagnosis and monitoring by XG-PD
- Max. 64 stations of slave modules controlled by one master module



## System configuration



## Specifications

Item	Specifications (XGL-RMEA)
Transmission speed	1Mbps
Encoding	Manchester Biphasic-L
Transmission distance (Per segment)	Max. 750m
Transmission distance (When using repeater)	Max. 750m * (6 repeater +1) = 5.25Km
Transmission cable	Twisted pair shield cable
Max. number of connection stations	Master + Slave = 64 stations (with repeater), 1 segment=32 stations (with master)
Max. size of protocol	256 bytes
Medium access method	Circulated Token Passing
Frame error check	CRC 16 check
Max. number of installation	12
Installation position	Main base or expansion base
Current consumption (mA)	410
Weight (Kg)	0.12

## SMART I/O

- Reduction of wiring and real-time control of distributed I/O
- Various I/O module (16/32 points)



## Repeater specifications

Item	Specifications
Type	G0L-FREB: AC110V ~ AC220V, G0L-FREC: DC 24V
Communication speed	1Mbps
Transmission method	Twisted pair shield cable
Transmission distance	Max. 750m per repeater
Max. number of installation between stations	Max. 6 repeaters
Max. distance between stations	5.25Km (when 6 repeaters are installed)
Fault data reception	Error data transmission
Frame error check	CRC 16 check

## Network cable and peripheral devices

Item	Specifications	Remarks
Twisted pair electric cable	LIREV-AMESB, 2 x 1mm, 18AWG	LS cable
RF terminator	110Ω, 1/2 Watt	-

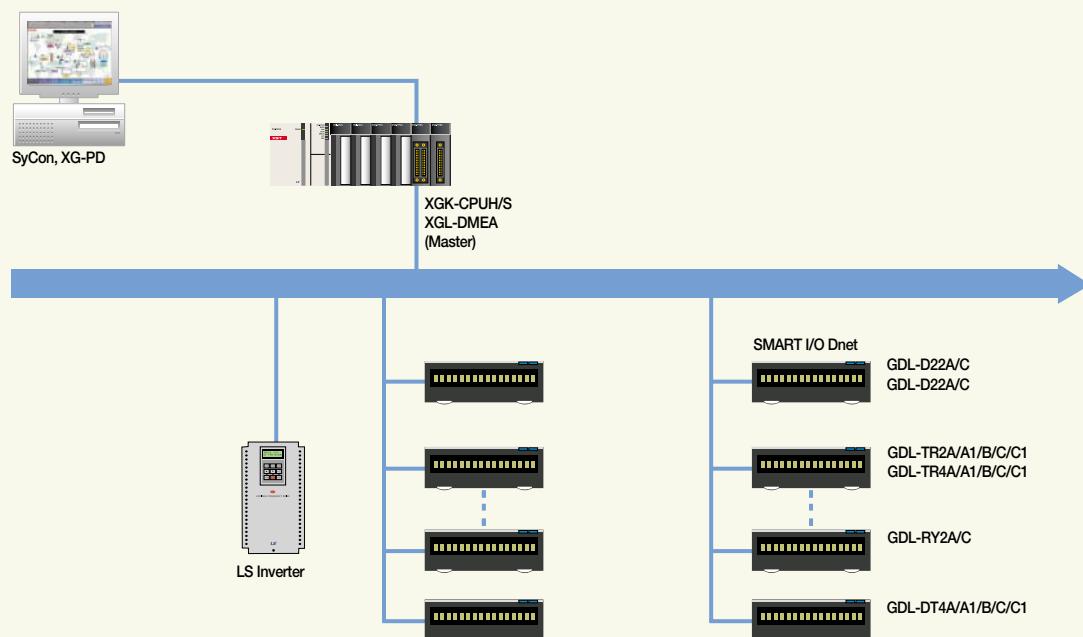
## Network / DeviceNet system

### Features

- DeviceNet protocol
- Direct control of various I/O devices via Dnet system
- Max. 63 slave modules controlled by one master module
- Flexibility in network configuration: Multi-drop and T branch connection
- Connectable to other master module and various slave modules
- Providing 'Auto Network Scan' function and various information with configuration tool (SyCon)
- Communication using High-speed link parameter
- Connectable to various slave I/O including other module  
(Common I/O, Actuator, Switch, Optical switch, Valve, Inverter,  
A/D module, Position controller etc..)
- Automatic monitoring of slave modules in the network:  
Auto-scan (XG-PD)
- Easy expansion: up to 12 master modules
- Network setting by SyCon/XG-PD  
(Parameter setting, diagnosis and monitoring)



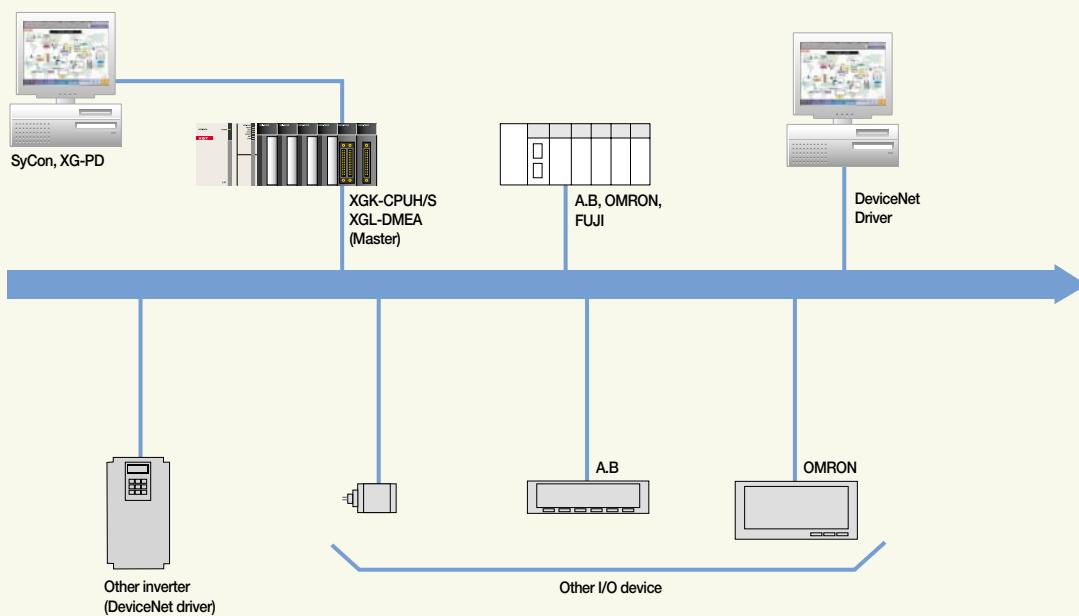
### System configuration with LSIS products



## Specifications

Item	Specifications (XGL-DMEA)			
Module type	Master			
Transmission distance and speed	Trans. speed	Max. network length	Max. drop cable	Length of all drop cable
	500kbps	100m	6m	39m
	250kbps	250m	6m	78m
	125kbps	500m	6m	156m
Max. number of connection stations	64 stations (Master 1 + Slave 63)			
Max. number of node	Max. 64 MAC ID (Node address)			
Communication method	Bit Strobe, Poll, COS, Cyclic			
Diagnosis function	Duplicated station check Abnormal station detection/CRC error check/Scan List/Operation display (LED)			
Cable	Dnet dedicated cable: 5 (Signal: 2, power: 2, shield: 1)			
Max. number of installation	12			
Configuration tool	SyCon			
Configuration port	RS-232C Configuration Port			
Current consumption (mA)	440			
Weight (Kg)	0.11			

## System configuration with other products



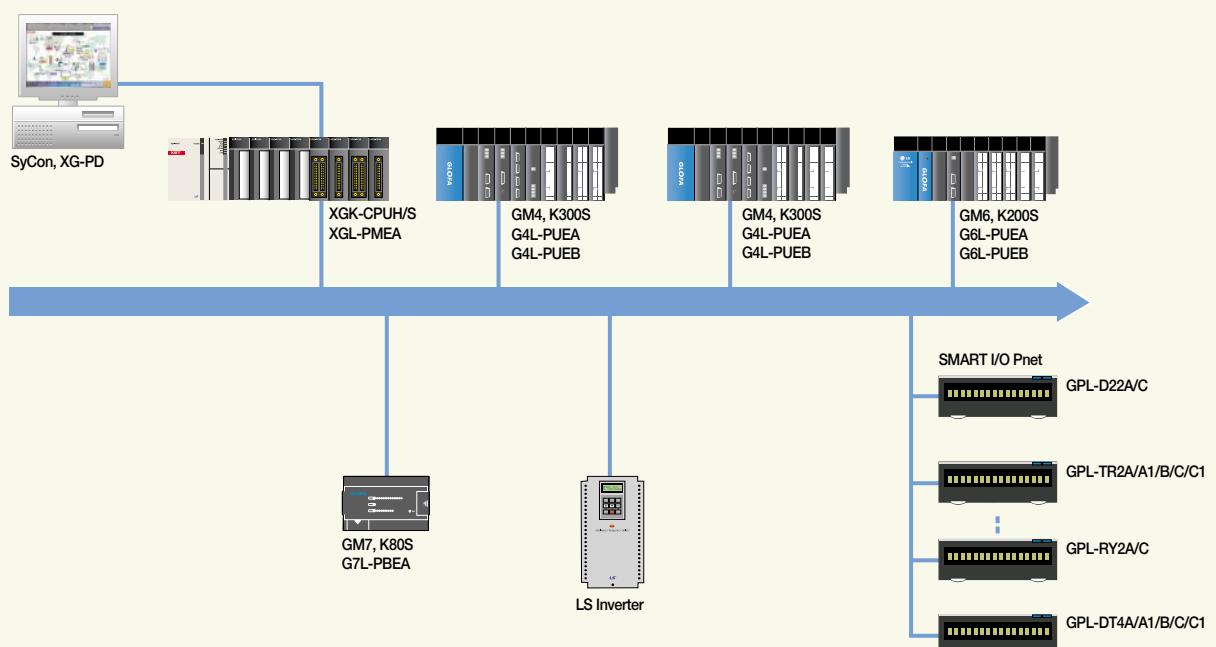
## Network / Profibus system

### Features

- Profibus-DP protocol
- Proper to communicate among a master automation device and distributed slave I/O devices.
- Fast slave communication without application layer
- Transmission speed: 9.6Kbps ~ 12Mbps
- Transmission distance: Max. 1,200m
- Max. 126 slave stations available (32 stations per segment)
- Network setting using SyCon/XG-PD  
(Parameter setting, diagnosis and monitoring)
- I/O data of master station: 7kbytes
- Automatic monitoring of slave modules in the network:  
Auto-scan (XG-PD)
- Multi master
- Providing 'Auto Config' and various information  
with configuration tool (SyCon)



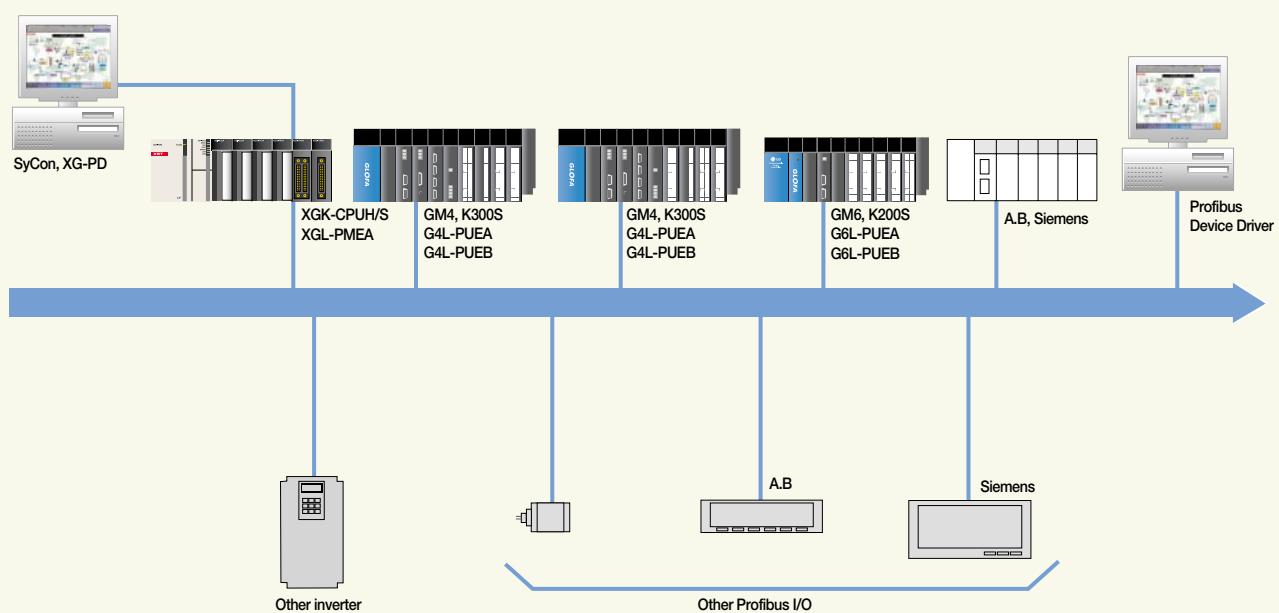
### System configuration with LSIS products



## Specifications

Item	Specifications (XGL-PMEA)	
Module type	Master	
Network type	Profibus-DP	
Standard	EN50170/DIN19245	
Interface	RS-485 (Electric)	
Media access	Token Passing & Poll	
Topology	Bus	
Modulation	NRZ	
Cable	Shield Twisted Pair Cable	
Transmission distance	1,000m	9.6K~187Kbps
and speed	400m	500Kbps
	200m	1.5Mbps
	100m	3M~12Mbps
Max. number of slave per network		126
Max. number of slave per segment		32
Max. I/O data	Input: 3584byte, Output: 3584byte	
Max. number of communication points	7Kbytes	
Communication parameter setting	XG-PD, SyCon	
Max. number of installation	12	
Configuration Tool	SyCon	
Configuration Port	RS-232C Configuration Port	
Current consumption (mA)	550	
Weight (Kg)	0.11	

## System configuration with other products

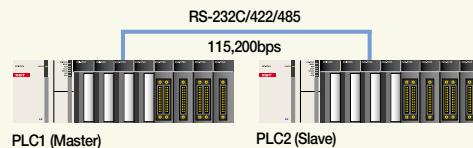


## Network / Computer-Link

**Communication among PLCs** This is a system configuration communicating between XGT PLCs by serial communication. In this case, PLC 1 is the master (Client) and other PLC should be slaves (Server). It is called Master/Slave communication. Master PLC is defined by comm. basic parameter and P2P setting. And slave PLC is defined by basic parameter and driver setting.

### Configuration

PLC1 reads present value, C0000 of PLC2's up-counter and then saves it in M0200 of PLC1.

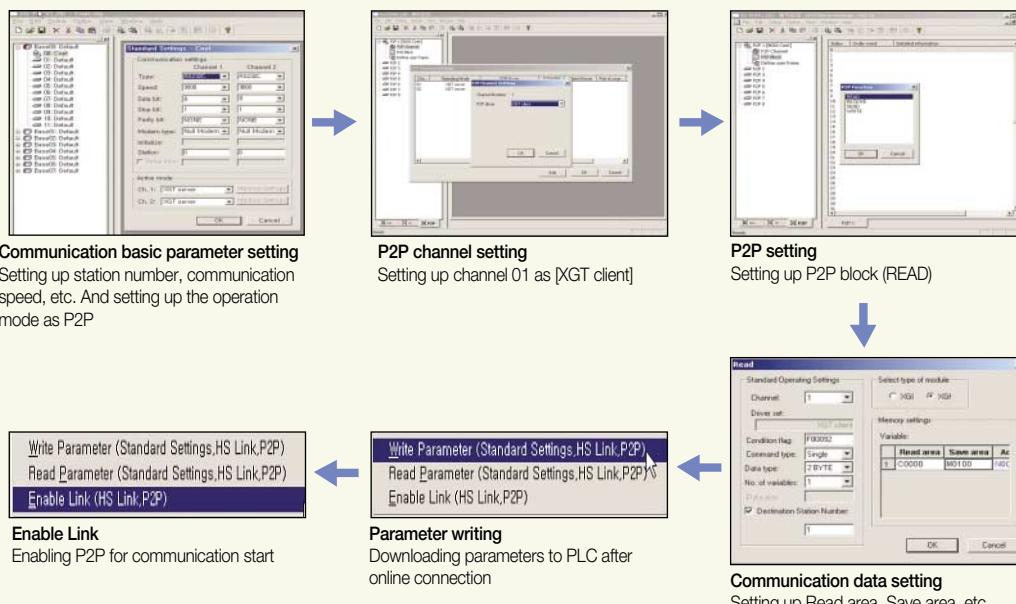


### Data memory

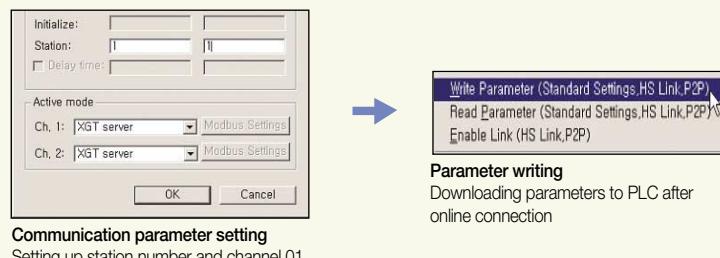
PLC station	PLC memory	Setting Item
PLC 1	M0100	1. XG-PD parameter setting, 2. XG5000 programming
PLC 2	C0000	1. XG-PD parameter setting, 2. XG5000 programming

### XG-PD setting

#### PLC 1 setting (Master)



#### PLC 2 setting (Slave)

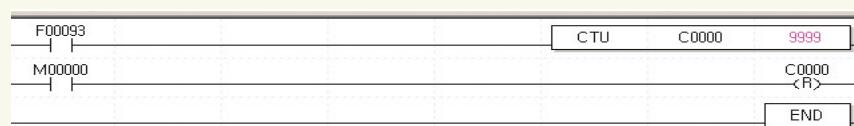


\* For basic parameter setting and SyCon setting/change, reset the module (Online reset).

### XG5000 programming

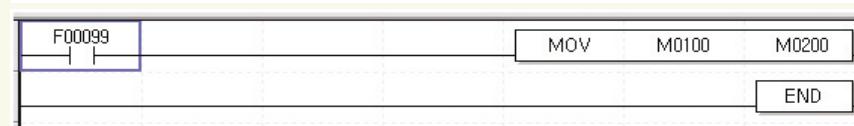
#### PLC station 2 setting

Make up-counter program using CTU command



#### PLC station 1 setting

Check out the counter value of M0100 is transmitted.

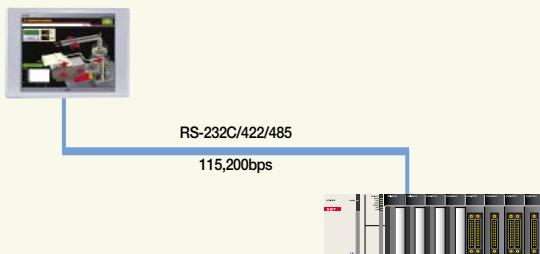


## HMI communication configuration

This is a system configuration to monitor and control PLC (XGT) by XP (HMI). In this case, PLC is the slave (Server) and XP should be the master (Client). PLC is defined by comm. basic parameter and driver setting.

### Configuration

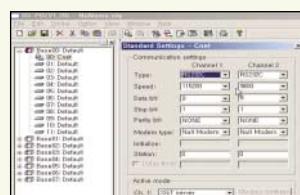
Making On/Off touch tag for controlling M0001 of XGT



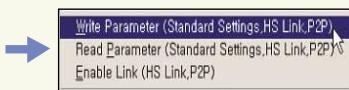
### Data memory

PLC memory	Setting item	PMU
M000D1	1. XG-PD parameter setting	Using touch tag
	2. XG5000 programming	

### XG-PD setting



**Basic communication parameter setting**  
Setting up station number, communication speed, etc And setting up the operation mode as XGT server



**Parameter writing**  
Downloading parameters to PLC after online connection



**PMU setting**  
Setting up communication setting (speed, data, stop, parity, etc) same as XGT

\* For basic parameter setting and SyCon setting/change, reset the module (Online reset).

### XG5000 programming

**Create program that P00010 is on right after M00001 is on.**



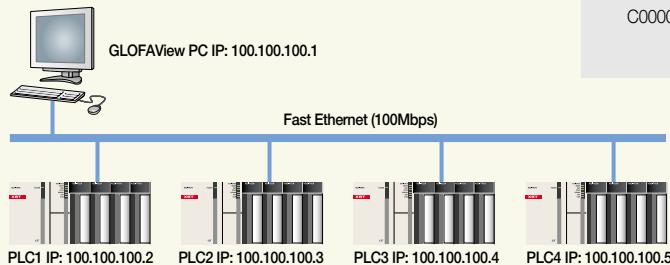
## Network / Communication example (Ethernet)

### HMI communication configuration

This is a data communication system configuration among XGT PLCs via Ethernet network. In this case, communication is possible by HS link among PLCs. It just needs basic parameter setting and HS link item setting.

### Configuration

Read the up-counter value C0000 of PLC1 and monitor it in GLOFAview.

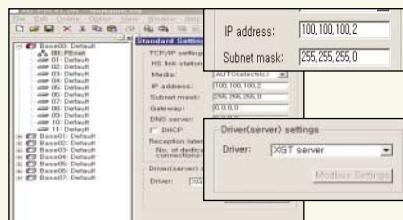


### Data memory

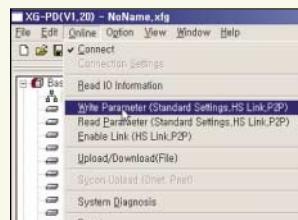
PLC memory	Setting item	GLOFAView
C0000	1. XG-PD parameter setting	Using analog tag
	2. XG5000 programming	

### XG-PD setting

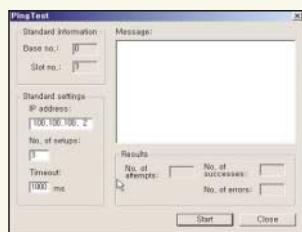
#### PLC 1 setting (Master)



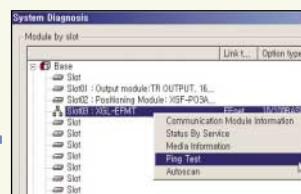
Basic communication parameter setting  
Specifying IP address and Subnet mask of PLC as above



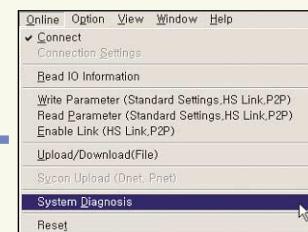
Parameter writing  
Downloading parameters to PLC after online connection



Ping Test  
Starting diagnosis after inputting IP address of PLC



System Diagnosis  
Selecting Ping Test

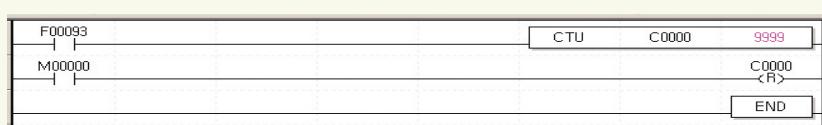


Communication test  
Checking online and system diagnosis

\* For basic parameter setting and SyCon setting/change, reset the module (Online reset).

### XG5000 programming

Make the up-counter program using CTU command.



Check out if the counter value of CTU value is transmitted.

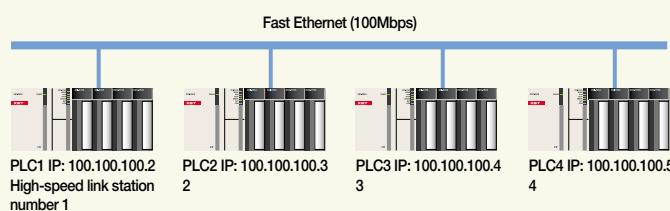


## High-speed link communication

This is a configuration for XGT to communicate each other via Ethernet. It just needs communication basic parameter setting and High-speed link item setting.

### Configuration

Read present value C0000 of PLC1 and transmit it to M0000 of PLC2.

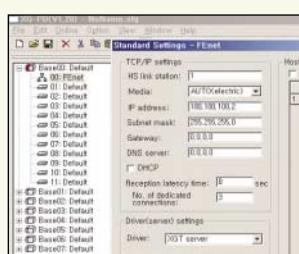


### Data memory

PLC station	PLC memory	Setting Item
PLC 1	C0000	1. XG-PD parameter setting, 2. XG5000 programming
PLC 2	M0100	1. XG-PD parameter setting, 2. XG5000 programming

### XG-PD setting

#### PLC station 1 setting



Basic communication parameter setting  
Specifying HS link station, IP address and Subnet mask of PLC as above

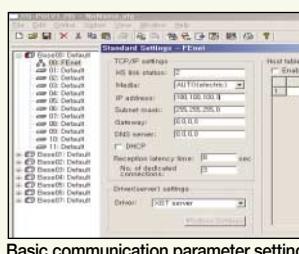


Communication data setting  
Setting up communication data in HS link item as above

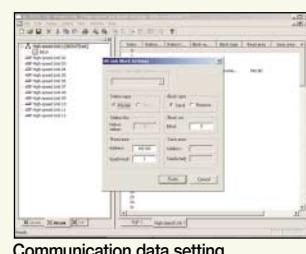
Write Parameter (Standard Settings,HS Link,P2P)  
Read Parameter (Standard Settings,HS Link,P2P)  
Enable Link (HS Link,P2P)

Parameter writing  
Downloading parameters to PLC after online connection

#### PLC station 2 setting



Basic communication parameter setting  
Specifying HS link station, IP address and Subnet mask of PLC as above



Communication data setting  
Setting up communication data in HS link item as above

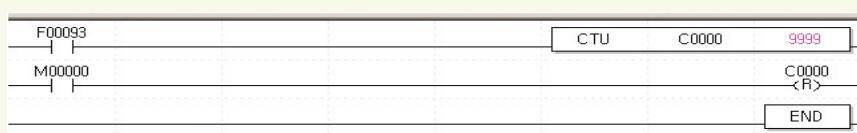
Write Parameter (Standard Settings,HS Link,P2P)  
Read Parameter (Standard Settings,HS Link,P2P)  
Enable Link (HS Link,P2P)

Parameter writing  
Downloading parameters to PLC after online connection

### XG5000 programming

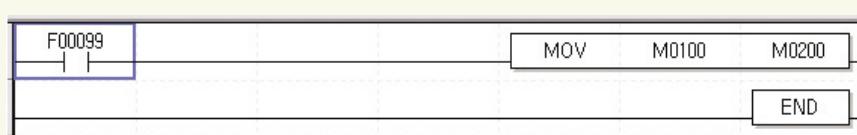
#### PLC1 setting

Make the up-counter program using CTU command



#### PLC2 setting

Check out if the counter value of M0100 is transmitted.



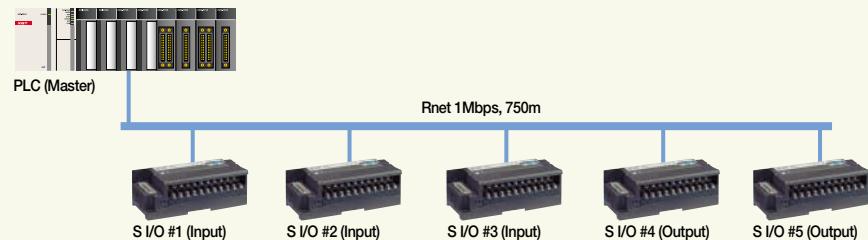
## Network / Communication example (Rnet)

### Remote I/O configuration

LSIS developed communication method is Rnet which is 'Distributed Control System' using Smart I/O. In this case, PLC is the master and the other Smart I/O are slaves. It just needs basic parameter setting for communication and High-speed link setting.

### Configuration

PLC controls each Smart I/O (16-point).

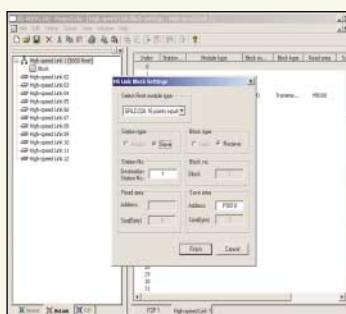


### Data memory

Smart I/O #	Smart I/O address	PLC address	Setting item
1	P0000	P0010 (P00100~P0010F)	
2	P0000	P0011 (P00110~P0011F)	
3	P0000	P0012 (P00120~P0012F)	
4	P0000	P0013 (P00130~P0013F)	
5	P0000	P0014 (P00140~P0014F)	1. XG-PD parameter setting, 2. XG5000 programming

### XG-PD setting

Communication data setting  
Setting up type name, station number, address of each station's Smart I/O in HS link item as following example.



Index	Station	Module type	Block No.	Block type	Block size	Write area
0	1	GRLC20A 16 points in+1	1	Recieve	P0010	2
1	2	GRLC20A 16 points in+1	1	Recieve	P0011	2
2	3	GRLC20A 16 points in+1	1	Recieve	P0012	2
3	4	GRLC20A 16 points in+1	1	Recieve	P0013	2
4	5	GRLC20A 16 points in+1	1	Recieve	P0014	1

HS link registration completed

**Write Parameter (Standard Settings, HS Link,P2P)  
Read Parameter (Standard Settings, HS Link,P2P)  
Enable Link (HS Link,P2P)**

**Parameter writing**  
Downloading parameters to PLC after online connection

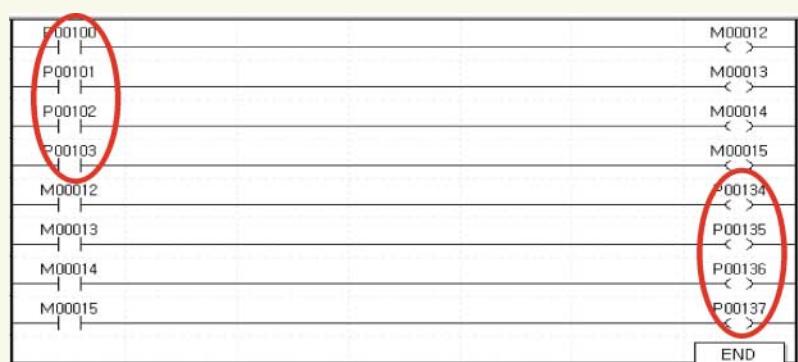
**Write Parameter (Standard Settings, HS Link,P2P)  
Read Parameter (Standard Settings, HS Link,P2P)  
Enable Link (HS Link,P2P)**

**Enable Link**  
Enabling link for communication start

\* For basic parameter setting and SyCon setting/change, reset the module (Online reset).

### XG5000 programming

**Write a program using I/O address of Smart I/O.**

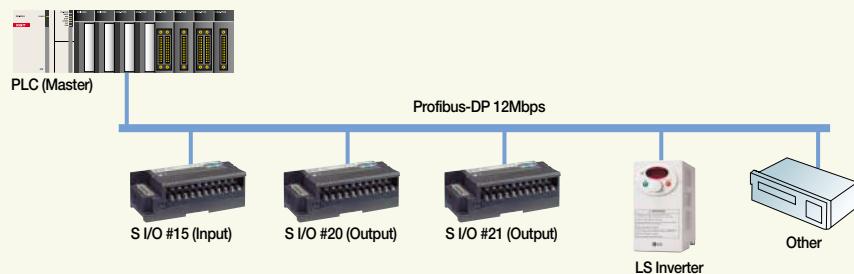


## High-speed link communication among PLCs

XGT can create 'Distributed Control System' with Smart I/O, Inverter, pneumatic device via Profibus-DP. In this case, PLC is the master and the other devices such as Smart I/O are slaves. It just needs SyCon, basic parameter and High-speed link setting.

### Configuration

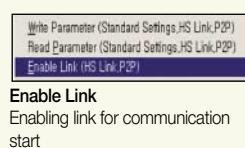
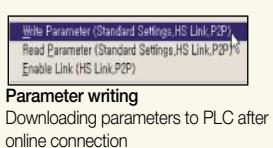
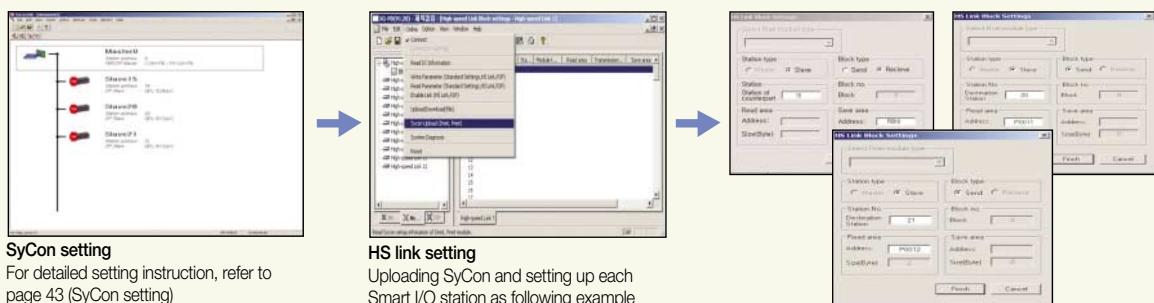
PLC controls each Smart I/O (16-point).



### Data memory

Smart I/O #	Smart I/O address	PLC address	Setting item
15	P0000	P0010 (P00100~P0010F)	1. SyCon setting 2. XG-PD parameter setting, 3. XG5000 programming
20	P0000	P0011 (P00110~P0011F)	
21	P0000	P0012 (P00120~P0012F)	

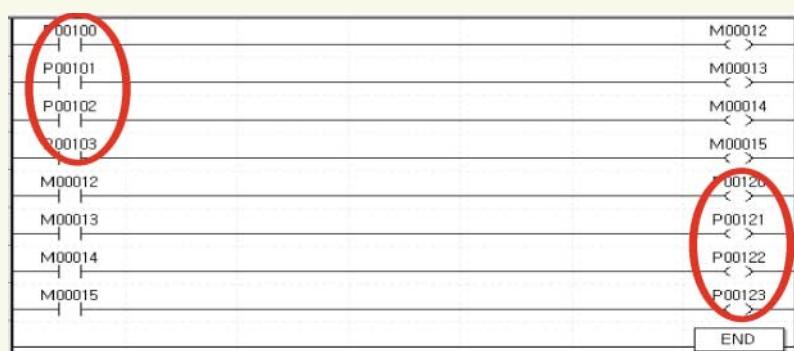
### XG-PD setting



\* For basic parameter setting and SyCon setting/change, reset the module (Online reset).

### XG5000 programming

**Write a program using I/O address of Smart I/O Pnet**



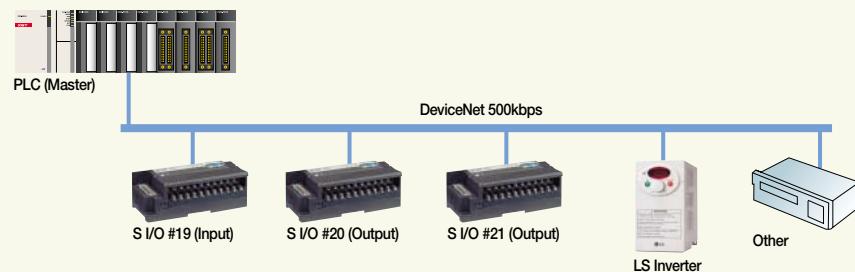
## Network / Communication example (DeviceNet)

### High-speed link communication between PLCs

XGT can create 'Distributed Control System' with Smart I/O, Inverter, pneumatic device via Dnet. In this case, PLC is the master and the other devices such as Smart I/O are Slaves. It just needs SyCon, basic parameter and High-speed link setting.

### Configuration

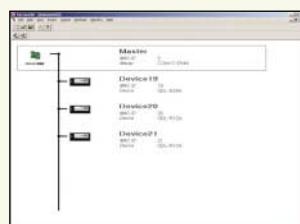
**PLC controls each Smart I/O (16 points).**



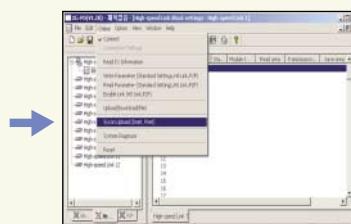
### Data memory

Smart I/O #	Smart I/O address	PLC address	Setting item
19	P0000	P0010 (P00100~P0010F)	1. SyCon setting
20	P0000	P0011 (P00110~P0011F)	2. XG-PD parameter setting,
21	P0001	P0012 (P00120~P0012F)	3. XG5000 programming

### XG-PD setting



**SyCon setting**  
For detailed setting instruction, refer to page 43 (SyCon setting)



**HS link setting**  
Uploading SyCon and setting up each Smart I/O station as following example



**Parameter writing**  
Downloading parameters to PLC after online connection

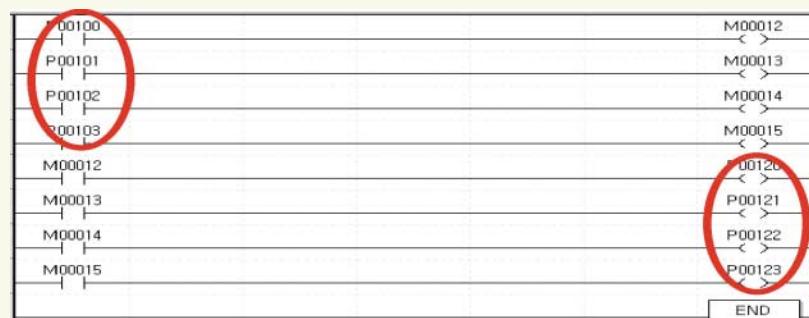


**Enable Link**  
Enabling link for communication start

\* For basic parameter setting and SyCon setting/change, reset the module (Online reset).

### XG5000 programming

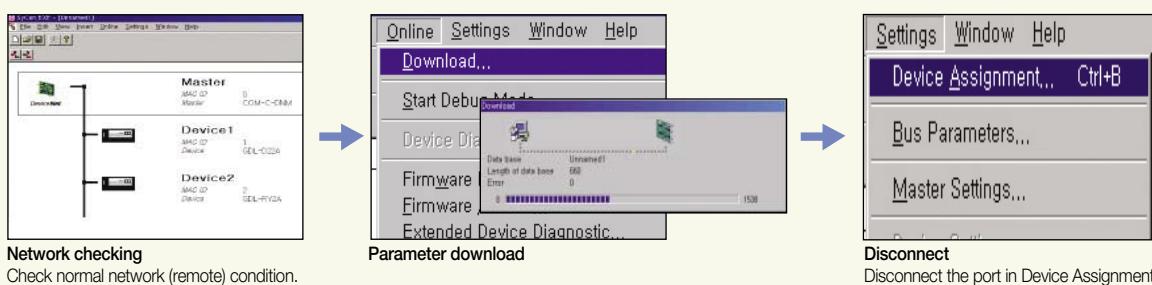
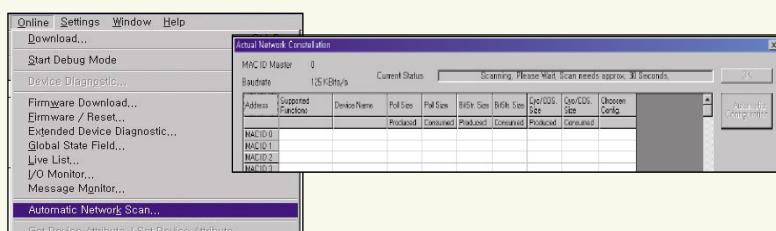
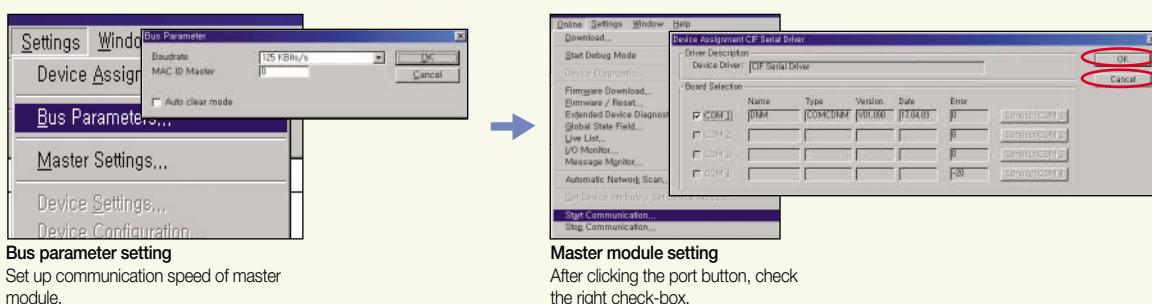
**Write a program using I/O address of Smart I/O Dnet.**



## Network / Communication example (SyCon setting Profibus, DeviceNet)

SyCon is the dedicated software that help user set up the communication environment for Profibus-DP and DeviceNet more easily and conveniently.

### Example of application



## Network / Smart I/O (Stand alone)

### Features

- Wiring reduction and real time control of distributed I/O
- Supporting Rnet, DeviceNet, Profibus-DP, MODBUS (RS-422/485)
- Various I/O (DC/TR/Relay) modules with the unit of 16/32 points



### Digital I/O specifications

Item		Input		Output		Mixed module	
		DC (Sink/Source)		Transistor (Sink)	Relay	DC (Sink/Source)	Transistor (Sink)
No. of point		16	32	16	32	16	16
Rated input (Load voltage)		DC 24V		DC 24V		DC 24V/AC 110V/220V	DC 24V
Input current (Load current)		7mA		0.1A/2A, 0.5A/3A		2A/5A	7mA
Response time	Off → On On → Off	3ms or less		3ms or less		3ms or less	3ms or less
Common		16 points/COM		16 points/COM		16 points/COM	16 points/COM
Current consumption		200mA	300mA	280mA	380mA	550mA	350mA
Network	Rnet	GRL-D22A	GRL-D24A	GRL-TR2A	GRL-TR4A	GRL-RY2A	GRL-DT4A
	Profibus-DP	GPL-D22A●	GPL-D24A●	GPL-TR2A▲	GPL-TR4A▲	GPL-RY2A●	GPL-DT4A▲
	DeviceNet	GDL-D22A●	GDL-D24A●	GDL-TR2A▲	GDL-TR4A▲	GDL-RY2A●	GDL-DT4A▲
	MODBUS	GSL-D22A	GSL-D24A	GSL-TR2A	GSL-TR4A	GSL-RY2A	GSL-DT4A

Note1) Specification stated in the table is specification of type A.  
Refer to XGT user's manual.

● A, C      ▲ A, A1, B, C, C1

A Sink, Rated current: 0.1A, terminal fixed type  
A1 Sink, Rated current: 0.5A, terminal fixed type  
B Source, Rated current: 0.5A, terminal separated type  
C Source, Rated current: 0.5A, terminal separated type  
C1 Sink, Rated current: 0.5A terminal separated type

### Analog I/O specifications

Item	GPL-AV8C	GPL-AC8C	Item	GPL-DV4C	GPL-DC4C
Input channels	8 channels		Output channels	4 channels	
Analog input	DC 1~5V, 0~5V, 0~10V, -10~-+10V	0~20mA, 4~20mA, -20~20mA	Digital input	0~4000, 0~8000, -8000~8000	0~8000
Digital output	0~4000, 0~8000, -8000~8000	0~4000, -8000~8000	Analog output	DC 1~5V, 0~5V, 0~10V, -10~-+10V	0~20mA, 4~20mA
Input impedance	1MΩ	250 Ω	Load impedance	1KΩ or more (0~5V or 1~5V) 2KΩ or more (0~10V or -10~10V)	500 Ω or less
Max. resolution	1.25mV	2.5μA	Resolution	1.25mV	2.5μA
Accuracy	±0.3% (full scale, Ta=0~55°C) ±0.4% (full scale, Ta=0~55°C)	±0.3% (full scale, Ta=23°C±5°C) ±0.4% (full scale, Ta=0~55°C)	Accuracy	±0.3% (full scale, Ta=0~55°C) ±0.4% (full scale, Ta=0~55°C)	±0.3% (full scale, Ta=23°C±5°C) ±0.4% (full scale, Ta=0~55°C)
Conversion speed	10ms or less / 8 channel		Conversion speed	10ms or less / 4 channel	
Response period	10ms or less / 8 channels + Transmission period (ms)		Response period	10ms or less / 8 channels + Transmission period (ms)	
Insulation method	Analog input/output terminal with FG→Insulation Analog input/output terminal with Communication terminal→Insulation Analog input/output terminal with each channel→No insulation		Insulation method	Analog input/output terminal with Communication terminal→Insulation Analog input/output terminal with each channel→No insulation	
External power supply	DC24V (21.6 ~ 26.4)		External power supply	DC24V (20.4 ~ 28.8)	
External current consumption	DC24V : 220mA		External current consumption	210mA	240mA
Weight (kg)	0.313	0.313	Weight (kg)	0.314	0.322

### Communication specifications

Item	Rnet (Dedicate network for LSIS Smart I/O)	Profibus-DP	DeviceNet	MODBUS
Protocol	LSIS dedicated protocol (Fnet for Remote)	Profibus-DP (RS-485/EN50170)	DeviceNet (CAN)	MODBUS (RS-422/485)
Transmission speed	1Mbps	9.6kbps ~ 12Mbps	125/250/500Kbps	2.4Kbps ~ 38.4Kbps
Transmission distance	750m/segment	100m ~ 1.2Km	500/250/125m (Thin cable: 100m)	500m
Topology	Bus Token	Bus	Trunk & Drop	Bus
Transmission	Pass & Broadcast	Token Pass & Master/Slave (Poll)	CSMA/NBA (Poll, Cyclic, COS, BitStrobe)	Master/Slave (Poll)
No. of stations	32/segment (Input: 32, Output: 32)	32/segment, 99/network	64	32
Link capacity	2,048 points/master (64 stations × 32 points)	7Kbyte/master	2,048 points/master	64 points/station

Note1) Smart I/O supports Poll type currently, but is supposed to support Cyclic, COS and Strobe later on.

## Network / SMART I/O (DeviceNet adapter)

### Features

- Max. 63 stations
- Flexible connection via DeviceNet
- Utilize same I/O modules with XGB
  - Max. 512 I/O points
  - Max. 32 channels analog input/output



### Specification

Items		Description		
Communication Specification		Poll, Bit-strobe, COS/Cyclic		
		Group 2 only slave		
		Auto baud rate		
Module's Type		Slave		
Max. Node Number (MAC ID)		64(0~63)		
Number of Expansion I/O Slots		8		
Max. DC I/O Data Size		Input:32bytes / Output:32bytes		
Max. Analog Channels		Input : 16Channels / Output : 16Channels		
Speed & Distance	Comm. Speed	125 kbps	250 kbps	500 kbps
	Distance	500 m	250 m	100 m
Input Power	System Power	DC 24V		
	Range	19.2V ~ 28.8V(11V operate)		
	Output Voltage/ Current	5V( $\pm 20\%$ ) / 1.5A		
Weight(g)		100		

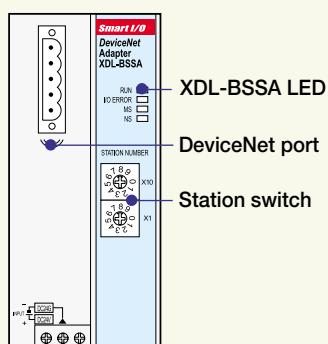
\* When I/O module is installed, check the current consumption  
(Max. Current: 1.5A)

### System configuration

Items	Description	Max. I/O point	
Digital I/O	XBE-DC08A DC24V input 8pt	256points	
	XBE-DC16A DC24V input 16pt		
	XBE-DC32A DC24V input 32pt		
	XBE-RY08A Relay output 8pt		
	XBE-RY16A Relay output 16pt		
	XBE-TN08A Tr output 8pt, Sink		
	XBE-TP08A Tr output 8pt, Source		
	XBE-TN16A Tr output 16pt, Sink		
	XBE-TP16A Tr output 16pt, Source		
Analog, Temperature	XBE-TN32A Tr output 32pt, Sink	16channels	
	XBE-TP32A Tr output 32pt, Source		
	XBE-DN16A DC24V input 8pt , Tr output 8pt		
	XBF-AD04A Current/Voltage input 4Ch		
	XBF-DC04A Current output 4Ch		
	XBF-DV04A Voltage output 4Ch		
XBF-RD04A RTD input 4Ch			
	XBF-TC04S TC input 4Ch		

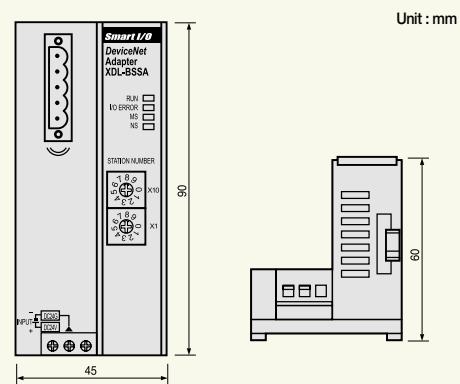
\* When Digital input and Analog input is used together or Digital output Analog output is used, configure the system within 32bytes  
(Ex) If 4ch analog input is used, Digital input can be used max. 192points

### Externals and inscriptions



Item	LED status
RUN	ON : Normal OFF : Module error
I/O ERROR	ON : I/O module error OFF : Normal
MS	Green ON: Normal Green blink: Normal Red ON: Module error
NS	Green ON: Normal Green blink: Waiting Green off: Comm. stop Red ON: Network error Red blink: Disconnect

### Dimension



## Network / SMART I/O (Profibus-DP adapter)

### Features

- Max. 100 stations (32stations per segment)
- Flexible connection via Profibus
- Utilize same I/O modules with XGB
  - Max. 512 I/O points
  - Max. 32 channels analog input/output

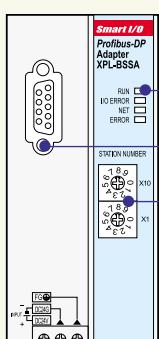


### Specification

	Item		Performance Specification				
Transmission	Standard		EN50170 / DIN 19245				
	Interface		RS-485(Electric)				
	Media Access		Polling				
	Topology		BUS				
	Encoding Method		NRZ				
	Interface		Sync mode , Freeze mode Auto baud rate				
	Master/Slave		Slave				
	Cable Type		Twisted Pair Shielded Cable				
	Comm.	Kbps	9.6	19.2	93.75	187.5	500
		m	1200	1200	1200	1000	400
	Distance	kbps	1500	3000	6000	12000	-
		m	200	100	100	100	-
	Max. Node Number		100 (0 ~ 99)				
	Number of Expansion I/O Slots		8				
	IO Data Size		64bytes (Input:32bytes /Output:32bytes)				
	Number of Analog Channels		32Channels (Input : 16Channels/Output : 16Channels)				
Input Power	System Power		Supply Voltage : DC 24Vdc 19.2 ~ 28.8Vdc				
	Output Voltage/ Current		5V(±20%) / 1.5A				
	Weight(g)		100				

\* When I/O module is installed, check the current consumption  
(Max. Current: 1.5A)

### Externals and inscriptions



XDL-BSSA LED  
Profibus-DP port  
Station switch

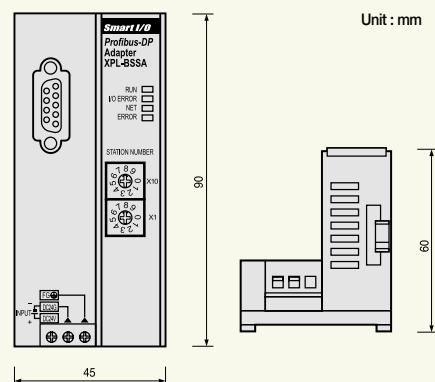
Item	LED status
RUN	ON : Normal Blink: Waiting or comm. error OFF : Module error
I/O ERROR	ON : I/O module error OFF : Normal
NET	ON : Data send/receive OFF : Disconnection
ERROR	ON : Comm. error OFF : Normal

### System configuration

Item	Description	Max. I/O point
Digital I/O	XBE-DC08A DC24V input 8pt	256points
	XBE-DC16A DC24V input 16pt	
	XBE-DC32A DC24V input 32pt	
	XBE-RY08A Relay output 8pt	
	XBE-RY16A Relay output 16pt	
	XBE-TN08A Tr output 8pt, Sink	
	XBE-TP08A Tr output 8pt, Source	
	XBE-TN16A Tr output 16pt, Sink	
	XBE-TP16A Tr output 16pt, Source	
	XBE-TN32A Tr output 32pt, Sink	
Analog, Temperature	XBE-TP32A Tr output 32pt, Source	16channels
	XBE-DN16A DC24V input 8pt , Tr output 8pt	
	XBF-AD04A Current/Voltage input 4Ch	
	XBF-DC04A Current output 4Ch	
	XBF-DV04A Voltage output 4Ch	
XBF-RD04A RTD input 4Ch	XBF-TC04S TC input 4Ch	

\* When Digital input and Analog input is used together or Digital output Analog output is used, configure the system within 32bytes  
(Ex) If 4ch analog input is used, Digital input can be used max. 192points.

### Dimension



## Network / SMART I/O (Rnet adapter)

### Features

- Max. 63 stations
- LS dedicated protocol (Rnet)
- Utilize same I/O modules with XGB
  - Max. 512 I/O points
  - Max. 32 channels analog input/output



### Specification

Item	Performance Specification
Transmission	Tran. Rate 1Mbps
	Transmission Path Bus type
	Method 750m
	Max. Cable Length 5 pin connector
	Connector type Twisted Pair Shielded Cable
	Cable type 32(non-used repeater),
	No. of Station 64(used repeater)
	(Included Master) 512(Input : 256, Output: 256)
	Max. Digital I/O points 96
	Max. Analog I/O points Digital I/O 8
	Number of I/O Slots Analog I/O 4
Selection of Latch/Clear	handling of mode change switch
Rated Voltage/current	DC24V/0.55A
Weight (g)	100

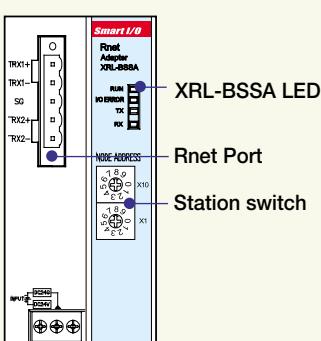
\* When I/O module is installed, check the current consumption  
(Max. Current: 1.5A)

### System configuration

Item	Description	Max. I/O point
Digital I/O	XBE-DC08A DC24V input 8pt	256points
	XBE-DC16A DC24V input 16pt	
	XBE-DC32A DC24V input 32pt	
	XBE-RY08A Relay output 8pt	
	XBE-RY16A Relay output 16pt	
	XBE-TN08A Tr output 8pt, Sink	
	XBE-TP08A Tr output 8pt, Source	
	XBE-TN16A Tr output 16pt, Sink	
	XBE-TP16A Tr output 16pt, Source	
	XBE-TN32A Tr output 32pt, Sink	
Analog, Temperature	XBE-TP32A Tr output 32pt, Source	16channels
	XBE-DN16A DC24V input 8pt, Tr output 8pt	
	XBF-AD04A Current/Voltage input 4Ch	
	XBF-DC04A Current output 4Ch	
	XBF-DV04A Voltage output 4Ch	
	XBF-RD04A RTD input 4Ch	
XBF-TC04S	TC input 4Ch	

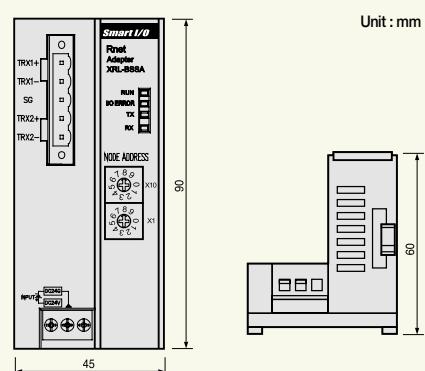
\* When Digital input and Analog input is used together or Digital output Analog output is used, configure the system within 32bytes  
(Ex) If 4ch analog input is used, Digital input can be used max. 192points.

### Externals and inscriptions

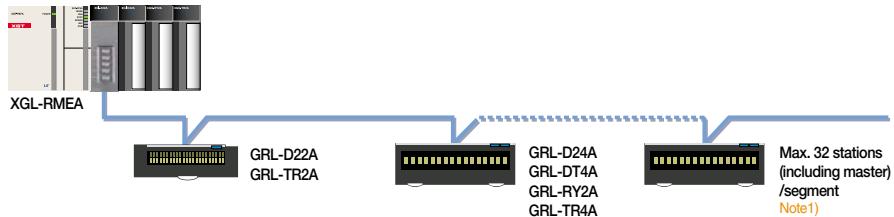


Item	LED status
RUN	ON : Normal OFF : Module error
I/O ERROR	ON : I/O module error OFF : Normal
TX	Data send
RX	Data receive

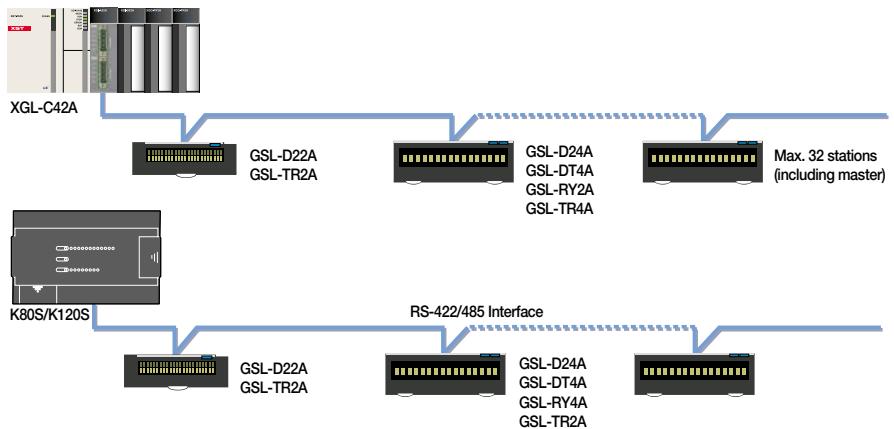
### Dimension



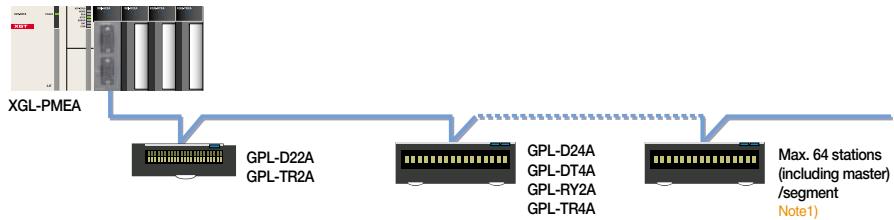
### Smart I/O Rnet system



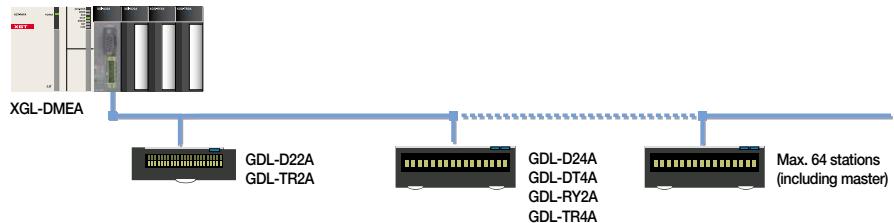
### Smart I/O MODBUS system



### Smart I/O Profibus-DP system



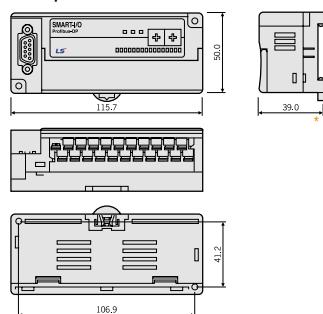
### Smart I/O DeviceNet system



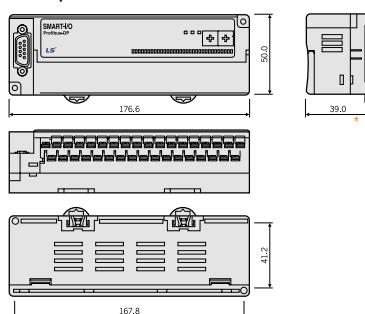
Note1) Segment: Communication section that does not use repeater or second master.

### Dimensions

- 16points

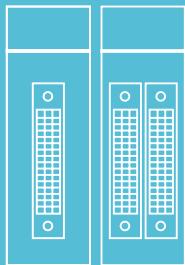


- 32points



Unit: mm

• GxL-RY2 (16-point relay output) module follows the dimension of 32-point module.  
• The length of C type Smart I/O is 47.5mm



# Special

XGT series offer diverse special modules such as analog, HSC, and positioning to satisfy complicated industrial needs

Special





## Revolution of easy to use ...XGT Special module

### Fast processing of parameter and data of special module

- Continually refreshing operation data of special module by CPU module
- Including contact points such as conversion data of AD/DA module and command of HSC & positioning module

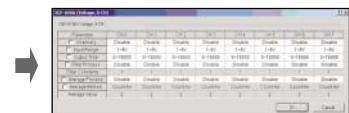
### Easy-to-use (Easy operation parameter setting and data monitoring)

- Convenient parameter setting available through XG5000
- Providing useful functions that can monitor and test operation data and contact points through XG5000

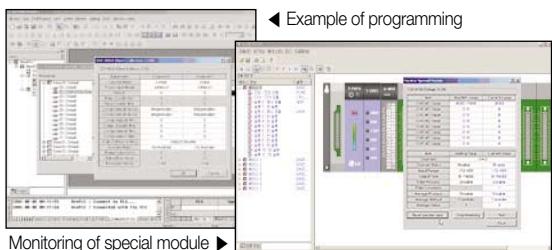
### Simple maintenance (Changing online module)

- Without turning off and holding CPU, users can change special module with ease.

Before



◀ Example of programming



Monitoring of special module ▶



#### Analog input module

XGF-AV8A	8 channels, voltage input
XGF-AC8A	8 channels, current input
XGF-AD4S	4 channels, voltage/current input
XGF-AD8A	8 channels, voltage/current
XGF-AD16A	16 channels, voltage/current input



#### Analog output module

XGF-DV4A	4 channels, voltage output
XGF-DV4S	4 channels, voltage output, insulation
XGF-DC4A	4 channels, current output
XGF-DC4S	4 channels, current output, insulation
XGF-DV8A	8 channels, voltage output
XGF-DC8A	8 channels, current output



#### Temperature input module

XGF-TC4S	4 channels, thermocouple input, Insulation
XGF-RD4A	4 channels, RTD input
XGF-RD4S	4 channels, RTD input, Insulation



#### High-speed counter module

XGF-HO2A	2 channels, Open collector
XGF-HD2A	2 channels, Line driver



#### Positioning module

XGF-PO1(2/3)A	1/2/3-axis, Open collector
XGF-PD1(2/3)A	1/2/3-axis, Line Driver

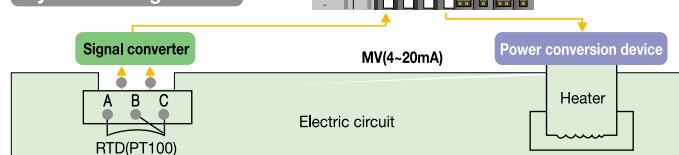


#### Temperature controller

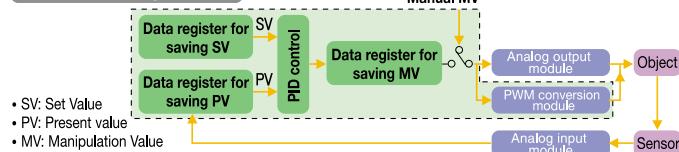
XGF-TC4UD	4 channels input: voltage/current/TC/RTD 8 channels output: current/TR
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### Example: PID control

#### System configuration

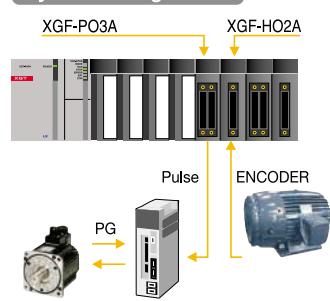


#### Control configuration

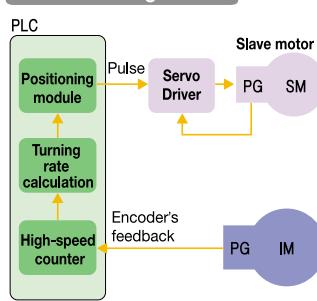


### Application example: Synchronous operation of inductive motor and servo motor

#### System configuration



#### Control configuration



## Special module / Analog input module



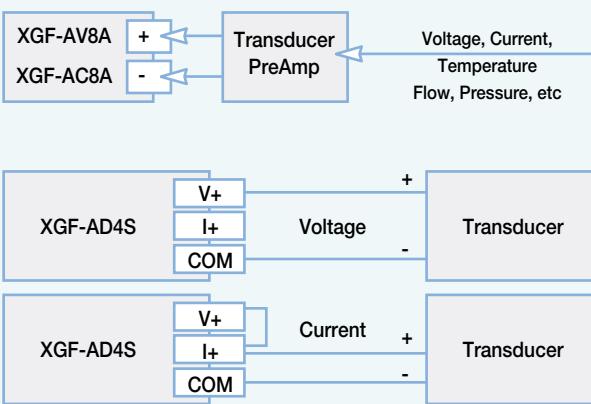
### Features

- Fast conversion processing
- High resolution
- Setting and monitoring the special module parameter through XG5000
- Supporting 4 types of digital output data format

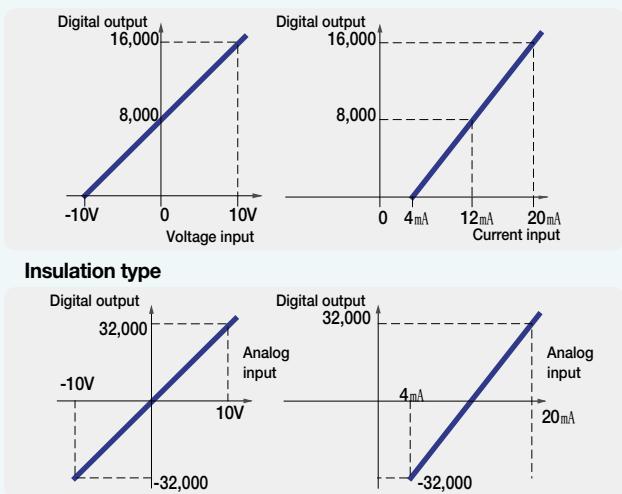
### Specifications

Item	XGF-AV8A (Voltage input)	XGF-AC8A (Current input)	XGF-AD4S (Voltage/Current input)					
No. of input channel	8 channels		4 channels					
Analog input	DC 1~5V, 0~5V, 0~10V, -10~10V	DC 4~20mA, 0~20mA	DC 1~5V, 0~5V, 0~10V, -10~10V DC 4~20mA, 0~20mA					
Selection of input range in program or S/W package (Available to be set per channel)								
Digital output	XGF-AV8A	Analog input		1~5V	0~5V	0~10V	-10~10V	
		Digital output	Unsigned value	0~16,000				
			Signed value	-8000~8,000				
		Digital output	Precise value	1,000~5,000	0~5,000	0~10,000	-10,000~10,000	
Digital output	XGF-AC8A		Percentile value	0~10,000				
	Analog input		4~20mA		0~20mA			
	Digital output	Unsigned value	0~16,000					
		Signed value	-8,000~8,000					
Resolution	XGF-AD4S	Digital output	Precise value	4,000~20,000		0~20,000		
			Percentile value	0~10,000				
			Analog input		1~5V	0~5V	0~10V	
			Signed value	4~20mA		-10~10V	0~20mA	
Accuracy			Precise value	1,000~5,000	0~5,000	-10,000~10,000	0~20,000	
			Percentile value	-32,000~32,000				
			1~5V		0~5V	0~10V	-10~10V	
			0~10V	0.250mV	0.3125mV	0.625mV	1.250mV	
Accuracy			-10V~10V	4~20mA	1.0μA	1.25μA	1.250μA	
			±0.2% or less (Ambient temperature 25°C)	1~5V		62.5nV	4~20mA	
			±0.3% or less (Range of operation temperature)	0~5V		78.1nV	250nA	
				0~10V	1.25μA	156.3nV	0~20mA	
Accuracy				±10V	1.250μV	312.5nV	312.5nA	
			±0.05% or less (Ambient temperature 25°C)	16,000		16,000	16,000	
			Temp. coefficient ±16.7ppm/°C(Range of operation temperature)	1/16,000		1/64,000	1/64,000	
				250μs/channel				
Conversion speed	15V		±30mA		Voltage: ±15V, Current: ±30mA			
Max. absolute input	±30mA		±30mA					
Insulation method	Photo-coupler Insulation between input terminal and power supply		No insulation between channels		Insulation between channels			
Connection terminal	18 points							
No. of occupied	Fixed type (Setting in basic parameter): 64 points							
I/O points	Variable type (Dissolving in basic parameter): 16 points							
Current consumption	420mA		610mA					
Weight (Kg)	0.14							

### Configuration



### A/D conversion characteristics



## Special module / Analog input module

### Features

- Fast conversion processing
- High resolution
- Setting and monitoring the special module parameter through XG5000
- Supporting 4 types of digital output data format



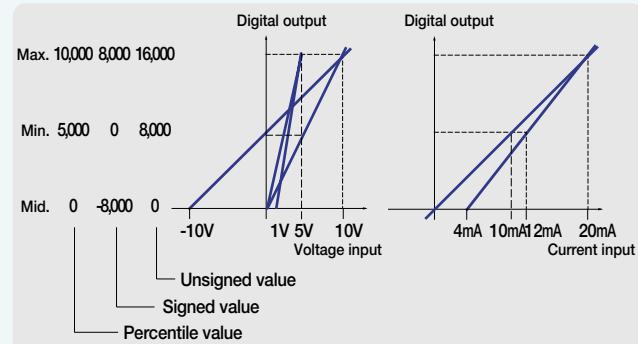
### Specifications

Item	XGF-AD16A			XGF-AD8A	
No. of input channel	16 channels			8 channels	
Analog input	Voltage input	DC 1~5V, DC 0~5V, DC 0~10V, DC -10~10V (Input resistance: 1MΩ)			
	Current input	DC4~20mA, DC 0~20mA (Input resistance: 250 Ω)			
	Input selection	Dip switch			
	Range selection	Selection of input range in the program or S/W package (Available to set per each channel)			
Digital output	Input type	Voltage input			Current input
		DC 1~5V	DC 0~5V	DC 0~10V	DC -10~10V
	Unsigned value	0~16,000			
	Signed value	-8,000~8,000			
	Precise value	0~10,000			
	Percentile value	1,000~5,000	0~5,000	0~10,000	-10,000~10,000
	Resolution(1/16000)	0.2500mV	0.3215mV	0.6250mV	1.250mV
Resolution	Range selection	Selection of input type by program or parameter (Available to be set per each channel)			
	±0.2%	or less (Ambient temperature 25°C), ±0.3% or less (Range of operation temperature)			
	Max. absolute input	±15V			±30mA
	Conversion speed	500 μs/channels			250 μs/channels
	Insulation method	Photo-coupler insulation between terminal and power supply			
	Terminal	32 points			18 points
	No. of occupied I/O points (XGK)	Fixed type (Setting in basic parameter): 64 points			Variable type (Dissolving in basic parameter): 16 points
	Current consumption	DC 5V : 420mA			
	Wight	140g			

### Configuration



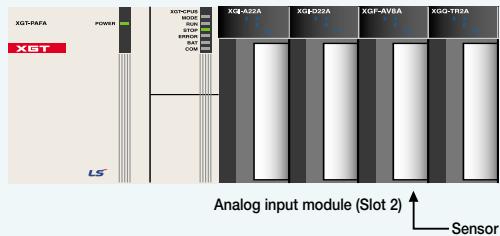
### A/D conversion characteristics



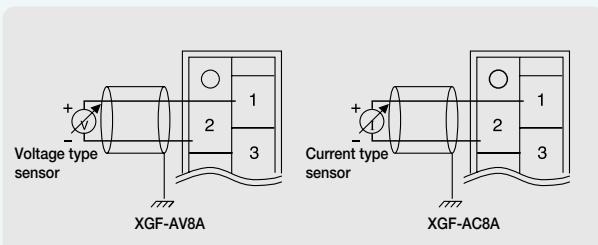
## Special module / Analog input module (Example)

This is a simple example to start Analog input module setting. For more details, refer to user's manual.

### System configuration



### Wiring



### Parameter setting

In the parameter setting box, select slot and analog module that you want to use. (This example shows to select '0' channel of voltage input type.)

Press the <Details> button at lower end of parameter setting box after selecting the module.

XGF-AV8A (Voltage, 8-CH)	
Parameter	CH 0
<input type="checkbox"/> Channels	Disable
<input type="checkbox"/> Input Range	1~5V
Output Type	0~16000
<input type="checkbox"/> Filter Process	Disable
Filter Constants	1
<input type="checkbox"/> Average Process	Disable
Average Method	Count-Avg
Average Value	2

You need to fill out each item suitable for your system.

### Programming

Create a program for A/D conversion (0~10V to 0~16,000).

#### Special devices for programming

Refer to user's manual for more details.

U02.0.0: Error

U02.11.0: Requesting error-clear

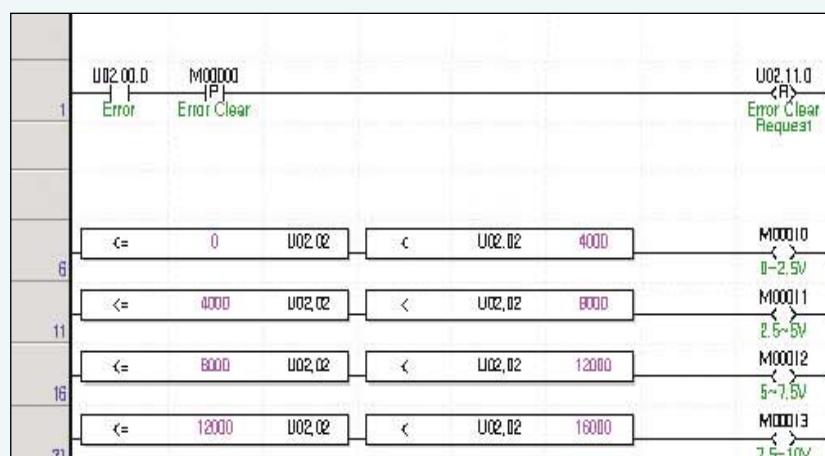
U02.02: Memory of channel A/D value

Uxy.aa.bb

x: Base number

y: Slot number

aa,bb: Refer to user's manual.



## Special module / Analog output module

### Features

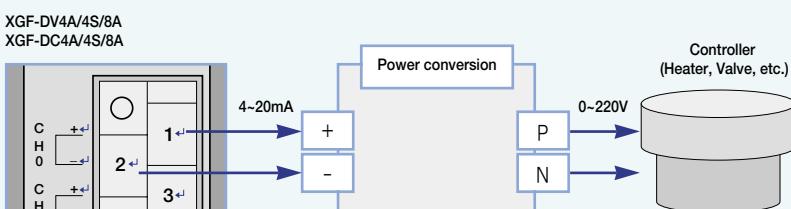
- Fast conversion processing
- High resolution
- Setting and monitoring the special module parameter through XG5000
- Supporting 4 types of digital input data format



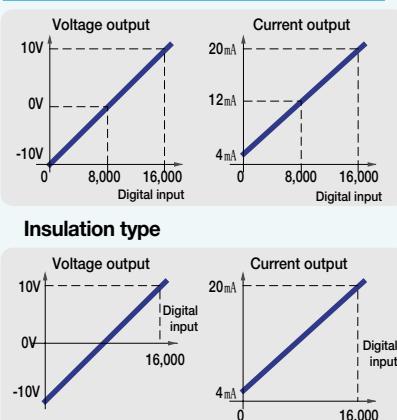
### Specifications

Item	XGF-DV4A,XGF-DV8A, XGF-DV4S (Voltage output type)		XGF-DC4A,XGF-DC8A, XGF-DC4S (Current output type)				
No. of output channel	XGF-DV4A/4S, XGF-DC4A/4S : 4 channels / XGF-DV8A, XGF-DC8A : 8 channels						
Analog output range	DC 1~5V, 0~5V		DC 4~20mA				
	DC 0~10V, -10~10V		DC 0~20mA				
Selection of input range in the program or S/W package (Available to set per each channel)							
Digital input range	Analog output	Voltage type		1~5V			
		Digital input	Unsigned value	0~16,000			
			Signed value	-8,000~8,000			
		Digital input	Precise value	1,000~5,000			
	Analog output		Percentile value	0~10,000			
	Digital input	Current type	4~20mA				
		Unsigned value	0~16,000				
	Digital input	Signed value	-8,000~8,000				
		Precise value	4,000~20,000				
		Percentile value	0~10,000				
16-bit binary value: selection of input type by program or parameter (Available to be set per each channel)							
Max. resolution		1/16,000 (Per each input range)					
	1~5V	0.250mV	4~20mA	1.0μA			
	0~5V	0.3125mV					
	0~10V	0.625mV	0~20mA	1.25μA			
	±10V	1.250mV					
Accuracy	XGF-DV4A/8A, DC4A/8A : ±0.2% or less (Ambient temperature 25°C), ±0.3% or less (Range of operation temperature)						
	XGF-DV4S/DC4S : ±0.1% or less (Ambient temperature 25°C), temp coefficient: ±80ppm/°C						
Conversion speed	250μs/channel						
Max. absolute output	±15V		±24mA				
Insulation method	Photo-coupler insulation between terminal and power supply XGF-DV4A/8A, XGF-DC4A/8A: No insulation between channels XGF-DV4S, XGF-DC4S (Insulation type): Insulation between channels						
Connection terminal	18 point terminal						
No. of occupied points	Fixed type (Setting in basic parameter): assign 64 points						
	Variable type (Dissolving in basic parameter): assign 16 points						
Current consumption (mA)	DV4A	DV8A	DV4S	DC4A			
	Internal	190	190	200			
	External	140	180	150			
Weight (Kg)	0.15						

### Output wiring



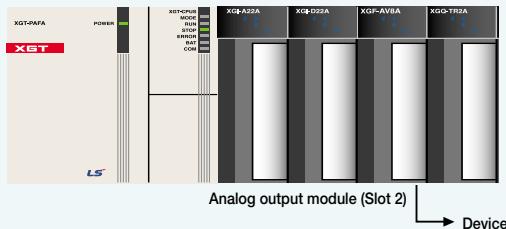
### I/O conversion characteristics



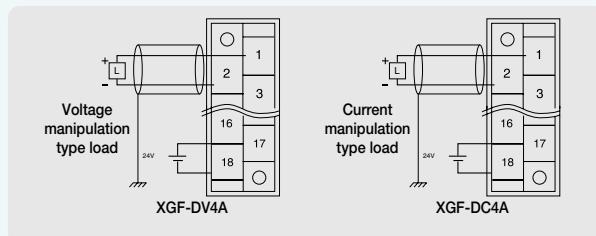
## Special module / Analog output module (Example)

This is a simple example to start Analog output module setting. For more details, refer to user's manual.

### System configuration



### Wiring



### Parameter setting

In the parameter setting box, select slot and analog module that you want to use. (This example shows to select '0' channel of voltage output type.)

I/O Parameter Setting - Fixed allocation(64points)

Module list

Slot	Module
0	
1	
2	Analog Output Module XGF-DV4A (Voltage, 4-CH)
3	Digital Module List
4	Special Module List
5	Analog Input Module
6	Positioning Module
7	XGF-DV8A (Voltage, 8-CH)
8	XGF-DC4A (Current, 4-CH)
9	XGF-DC8A (Current, 8-CH)
10	HSC Module
11	

Details

Press the <Details> button at lower end of parameter setting box after selecting the module.

XGF-DV4A (Voltage, 4-CH)	
XGF-DV4A (Voltage, 4-CH)	
Parameter	CH 0
<input type="checkbox"/> Channels	Enable
<input type="checkbox"/> Channels	0~10V
<input type="checkbox"/> Input Type	0~16000
<input type="checkbox"/> CH. Output Type	Min

You need to fill out each item suitable for your system.

### Programming

Create a program for D/A conversion (0~16000 to 0~10V).

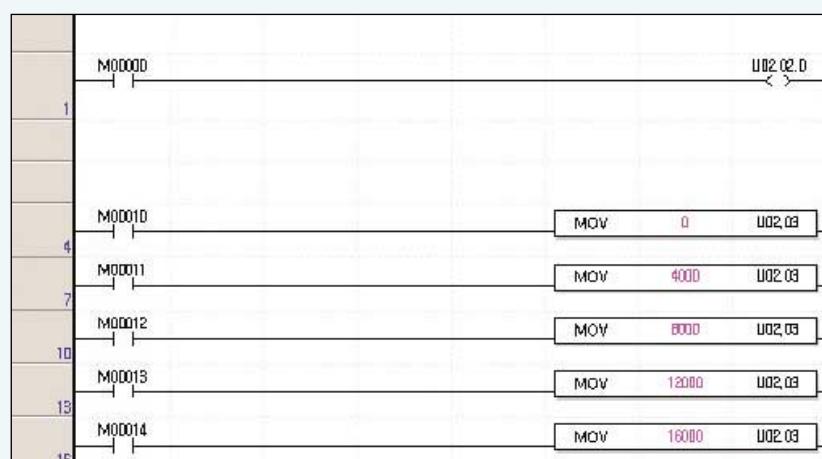
#### Special devices for programming

Refer to user's manual for more details.

U02.02:0: Admitting Channel 0 output

U02.03: Output data of channel 0

Uxy.aa.bb  
x: Base number  
y: Slot number  
aa,bb: Refer to user's manual.



## Special module / High-speed counter module

### Features

- Parameter setting and monitoring using XG5000
- Incremental encoder available
- Supporting various pulse input (5V, 12V, 24V)
- Various multiplication (1/2 phase pulse input)
- External present input
- Providing function to prevent from counting external signal
- Supporting HTL-level incremental encoder in the line-drive input type



### Specifications

Item		Specification		
		XGF-HO2A		XGF-HD2A
No. of command	Signal	A Phase, B Phase		
	Input type	Voltage input (Open Collector)		Differential input (Line Driver)
	Signal level	DC 5/12/24V		
	Input voltage	24V DC (17.0V ~ 26.4V)	12V DC (9.8V ~ 13.2V)	5V DC (4.5V ~ 5.5V)
	Input current	7~11mA	7~11mA	7~11mA
	Min. On guaranteed voltage	17.0V	9.8V	4.5V
	Max. Off guaranteed voltage	4.5V	3.0V	1.7V
Counter enable		Set by program (Count only in 'Enable')		
Max. counting speed		200Kpps		500Kpps (HTL input: 250Kpps)
No. of channels		2 channels		
Counting range		Signed 32 Bit (-2,147,483,647 ~ 2,147,483,647)		
Counting type		Linear count		
(Program setting)		(Generating Carry/Borrow when exceeding counting range, Max/Min value)		
Input mode		1 Phase input		
(Program setting)		2 Phase input		
		CW/CCW input		
Signal type		Voltage		
Up/Down counter setting	1-phase input	Program or B-phase		
	2-phase input	Phase difference		
	CW/CCW	A-phase input: Up count      B-phase input: Down count		
Multiplication	1-phase input	1/2 multiplication (Programming)		
	2-phase input	1/2/4 multiplication (Programming)		
	CW/CCW	1 multiplication		
Control input	Signal	Preset signal, Signal to admit additional signal (Setting by terminal block or programming)		
	Signal level	DC 5V/12V/24V input type (Selecting terminal)		
	Signal type	Voltage		
External output	No. of output point	2 points/channel: Terminal output available		
	Type	Single comparison (>,>=,=<,<) or section comparison		
	Output type	Open Collector (Sink)		
Operating status display	Input signal	A-phase, B-phase, Preset signal, Signal to admit additional signal		
	Output signal	OUT1, OUT2		
	Operation status	Module Ready, Pulse input status of A, B phase		
Addition functions (Program setting)		<ul style="list-style-type: none"> <li>• Count clear, Count latch</li> <li>• Section count (Set time value: 1~60000ms)</li> <li>• Measuring counting number per a unit time (Set time value: 1~60000ms)</li> <li>• Preventing from counting (Setting by internal/external input during counting)</li> </ul>		
No. of occupied I/O points		Fixed type (Setting in basic parameter): 64 points		
Terminal block		Variable type (Dissolving in basic parameter): 16 points		
Current consumption		270		330
Weight (Kg)		0.09		

## Terminal block configuration

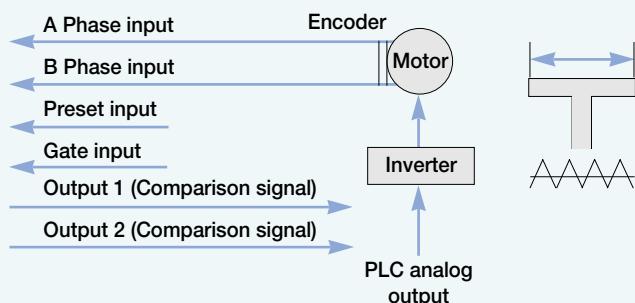
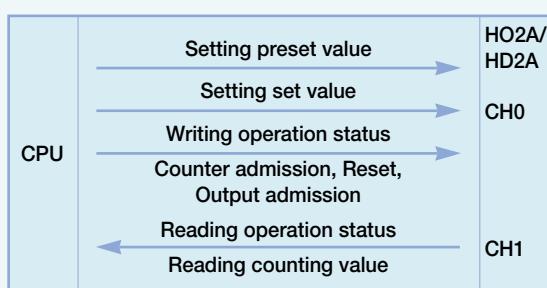
XGF-HO2A

Pin layout		Pin number		Signal name	
CHO	CH1				
		1	17	A12V	A phase DC12V input
		2	18	A24V	A phase DC24V input
		3	19	A_C	A phase COM
		4	20	A5V	A phase DC5V input
		5	21	B12V	B phase DC12V input
		6	22	B24V	B phase DC24V input
		7	23	B_C	B phase COM
		8	24	B5V	B phase DC5V input
		9	25	P12V	Preset DC12V input
		10	26	P24V	Preset DC24V input
		11	27	P_C	Preset COM
		12	28	P5V	Preset DC5V input
		13	29	G12V	Gate DC12V input
		14	30	G24V	Gate DC24V input
		15	31	G_C	Gate COM
		16	32	G5V	Gate DC5V input
CH0	OUT1 OUT0	33	35	OUT1	Comparison output OUT1
CH1	OUT1 OUT0	34	36	OUT0	Comparison output OUT0
		37	38	24V	External power supply
		39	40	24G	DC24V

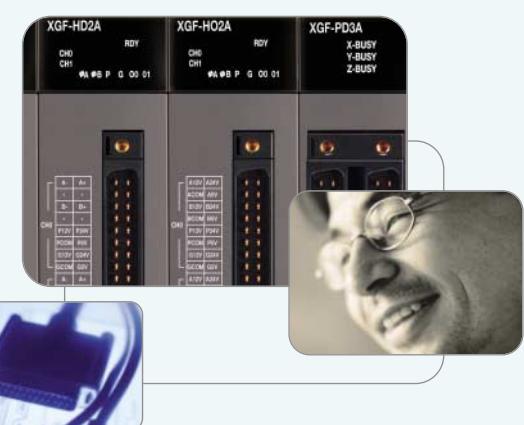
XGF-HD2A

Pin layout		Pin number		Signal name	
CHO	CH1				
		1	17	AI-	AI-Input (LINE DRIVE TTL LEVEL Input)
		2	18	AI+	AI+Input (LINE DRIVE TTL LEVEL Input)
		3	19	All-	All-Input (LINE DRIVE HTL LEVEL Input)
		4	20	All+	All+Input (LINE DRIVE HTL LEVEL Input)
		5	21	Bl-	Bl-Input (LINE DRIVE TTL LEVEL Input)
		6	22	Bl+	Bl+Input (LINE DRIVE TTL LEVEL Input)
		7	23	BII-	BII-Input (LINE DRIVE HTL LEVEL Input)
		8	24	BII+	BII+Input (LINE DRIVE HTL LEVEL Input)
		9	25	P12V	Preset DC12V input
		10	26	P24V	Preset DC24V input
		11	27	P_C	Preset COM
		12	28	P5V	Preset DC5V input
		13	29	G12V	Gate DC12V input
		14	30	G24V	Gate DC24V input
		15	31	G_C	Gate COM
		16	32	G5V	Gate DC5V input
CH0	OUT1 OUT0	33	35	OUT1	Comparison output OUT1
CH1	OUT1 OUT0	34	36	OUT0	Comparison output OUT0
		37	38	24V	External power supply
		39	40	24G	DC24V

## Configuration



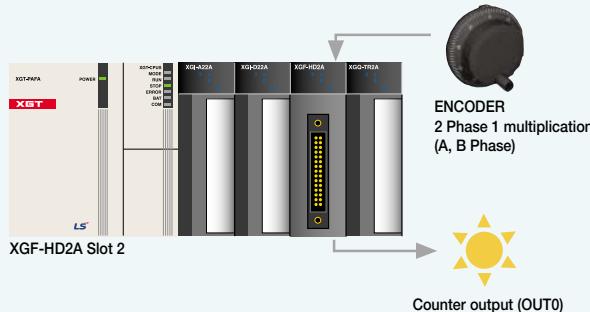
Special



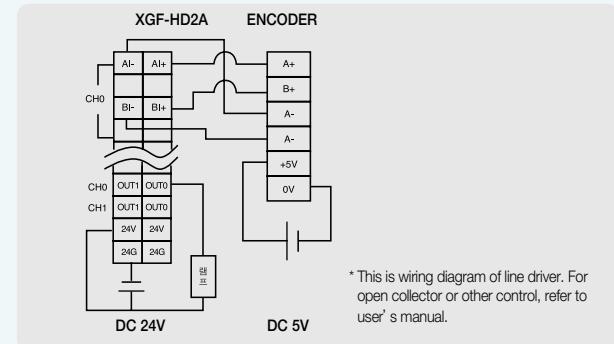
## Special module / High-speed counter module (Example)

This is a simple example of high-speed counter module setting.  
For more details, refer to user's manual.

### System configuration



### Wiring

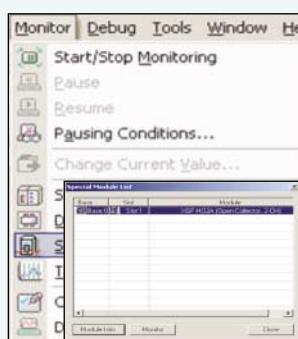


### Control configuration

- Light a lamp of output when present value reaches 1000 of pulse input counted by encoder.
- Current value of pulse is saved in D100~D101 and is monitored.

### Module test (Online)

- Module test function of XGT enables to monitor operation status of high-speed counter module and to test-run.



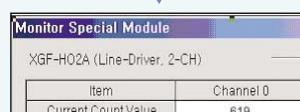
Select [Monitor] → [Special Module Monitoring] in menu and appoint high-speed counter.



After pressing the button for [Start Monitoring], press the button [FLAG monitor].



Change [Counter Enable] status to ON.

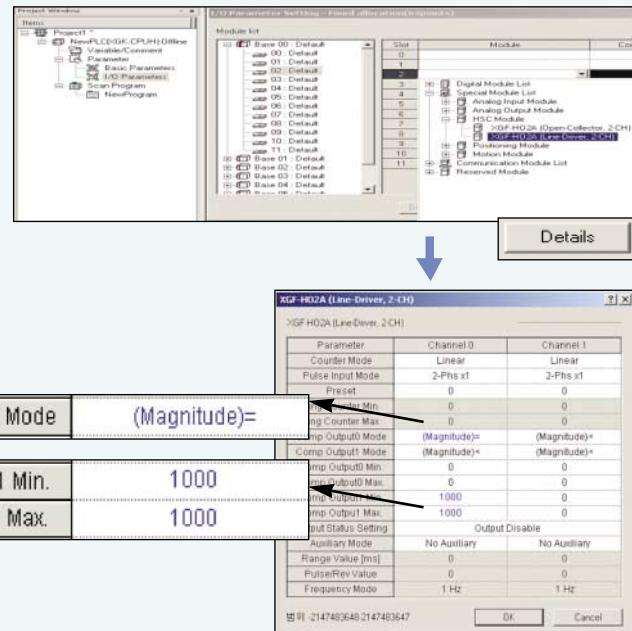


Check current counting value in 'Monitor Special Module' screen box.

## Parameter setting

- In I/O parameter setting box, select slot and analog module that you want to use.  
(This example shows to select 2-channel line driver.)

Press the <Details> button at lower end of parameter setting box after selecting the module.



## Programming

- After completing programming like following figure, download it to PLC and check operation status.

### Special devices for programming

Refer to user's manual for more details.

U02.23.0: Count operation admission

U02.23.1: Count preset

U02.23.4: Consistent output admission

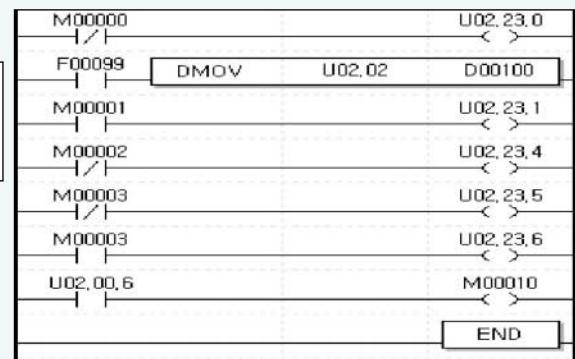
U02.23.5: Output external terminal admission

U02.23.6: OUT0 consistent signal reset

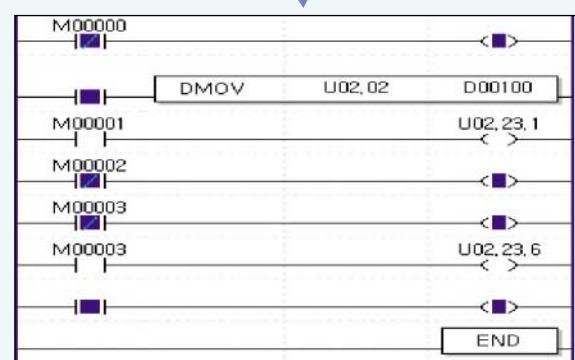
U02.00.6: Contact for checking external output (Practically effective output is outputted through OUT0 terminal)

U02.02~U02.03: Counter present value

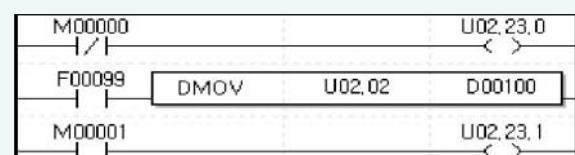
Uxy.aa.bb  
x: Base number  
y: Slot number  
aa.bb: Refer to user's manual



After downloading, monitor operation status.



For monitoring just present value, follow the example.



## Special module / Positioning module [APM]

### Features

- Highly reliable position control with LSIS ASIC-embedded processor
- Enhanced control with fast control processing speed
- High-speed motor control (Max. pulse output: 1Mbps)
- Circular/linear interpolation, separate/synchronous operation
- Trapezoidal & S-curve acceleration/deceleration
- Easy and quick control through external input (JOG operation included)
- Encoder input support
- High-speed processing of command (4ms)
- Easy to set positioning parameters (Windows)
- Monitoring/Tracking/Simulation
- Available to edit operation parameter data in EXCEL
- Self-diagnosis
- Real-time information and solution for each error



### Specifications

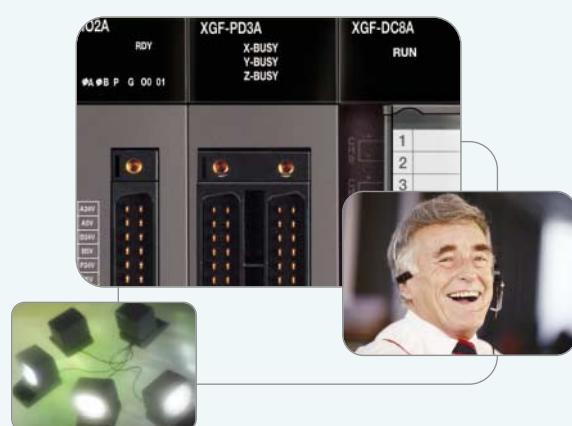
Item	Specifications		
	XGF-PO1A, XGF-PD1A	XGF-PO2A, XGF-PD2A	XGF-PO3A, XGF-PD3A
Number of axis	1	2	3
Interpolation		2-axis linear interpolation, 2-axis circular interpolation	2/3-axis linear interpolation, 2/3-axis circular interpolation
Control method		Position control, speed control, speed/position control, position/speed control	
Setting unit		Pulse, mm, inch, degree	
Positioning data	Each axis has 400 data items (Operation step number 1~400). It is available to set with software package or programming.		
Software package	Available (Connected with RS-232C Port of CPU module)		
Data backup	Flash memory (No battery)		
Positioning	Positioning method		
	Absolute / relative method		
	Position address range	mm	-214748364.8 ~ 214748364.7 (μm)
		Inch	-21474.83648 ~ 21474.83647
		Degree	-21474.83648 ~ 21474.83647
		Pulse	-2147483648 ~ 2147483647
	Type		
	XGF-PO□A: Open collector, XGF-PD□A: Line Driver		
	Position speed range	mm	0.01 ~ 2000000.00 (mm/min)
		Inch	0.001 ~ 2000000.00 (inch/min)
		Degree	0.001 ~ 2000000.00 (degree/min)
		Pulse	XGF-PO□A: 1~200,000 (pulse/sec), XGF-PD□A: 1~1,000,000 (pulse/sec)
Accel/Decel pattern	Trapezoidal & S-curve acceleration/deceleration		
	Accel/Decel time		
Max. output pulse		1 ~ 65,535 ms	
Max. distance		XGF-PO□A: 200Kpps / XGF-PD□A: 1Mpps	
Max. encoder input		XGF-PO□A: 2m / XGF-PD□A: 10m	
Error display		200 Kpps	
Operation display		LED	
Connection connector		40 Pin connector	
Size of cable		AWG #24	
Occupied points of I/O		64 points (Fixed type), 16 points (Variable type)	
Current consumption (mA)	XGF-PO1A: 340	XGF-PO2A: 360	XGF-PO3A: 400
	XGF-PD1A: 510	XGF-PD2A: 790	XGF-PD3A: 860
Weight (kg)	0.12	0.13	0.135

\* XGF-PO□O: Open Collector type, □: Number of axis  
XGF-PD□D: Line Drive type, □: Number of axis

## Terminal block configuration

Pin layout		Pin number			Signal name	Signal direction APM - Ext. device	Condition	
For	X	Y	Z					
A x i s	21	41	61	FP+	Pulse output (Differential +)	→		
	22	42	62	FP-	Pulse output (Differential -)	→		
	23	43	63	RP+	Pulse sign (Differential +)	→		
	24	44	64	RP-	Pulse sign (Differential -)	→		
	25	45	65	OV+ *	High limit	←		
	26	46	66	OV- *	Low limit	←		
	27	47	67	STOP	External stop signal	←		
	28	48	68	DOG	Approximate origin	←		
	29	49	69	VTP	Speed/Position switching signal	←		
				External command signal	Start	←		
	30	50	70	ECMD	Skip	←		
					JOG+ (Forward)	←		
	31	51	71		JOG- reverse operation	←		
C o m m o 	32	52	72	COM	Common (OV+, OV-, STOP, DOG, VTP, ECMD, JOG-)	↔		
	33	53	73	DR/INP	Imposition/Driver Ready signal	←		
	34	54	74	DR/INP COM	Imposition/Driver Ready signal Common	↔		
	35	55	75	HOME +24V	Zero signal (+24V)	←		
	36	56	76	NC	Not used			
	37	57	77	HOME +5V	Zero signal (+5V)	←		
	38	58	78	HOME COM	Zero signal (+24V, +5V) Common	↔		
	39	59	79	24V	24V Power supply (Not used in case of line drive output)			
	40	60	80	P COM	External 24V GND (Not used in case of line drive output)			
	1			MPG A+	Manual pulse generator/Encoder A+ Input	←		
2/3 axes	2			MPG A-	Manual pulse generator/Encoder A- Input	←		
	3			MPG B+	Manual pulse generator/Encoder B+ Input	←		
	4			MPG B-	Manual pulse generator/Encoder B- Input	←		
	5			NC	Not used	←		
	6			NC	Not used	←		
	7			CON	External simultaneous start	←		
	8			EMG *	Emergency stop	←		
	9			NC	Not used			
	10			COM	(CON, EMG) Common	↔		
	11~20			NC	Not used			

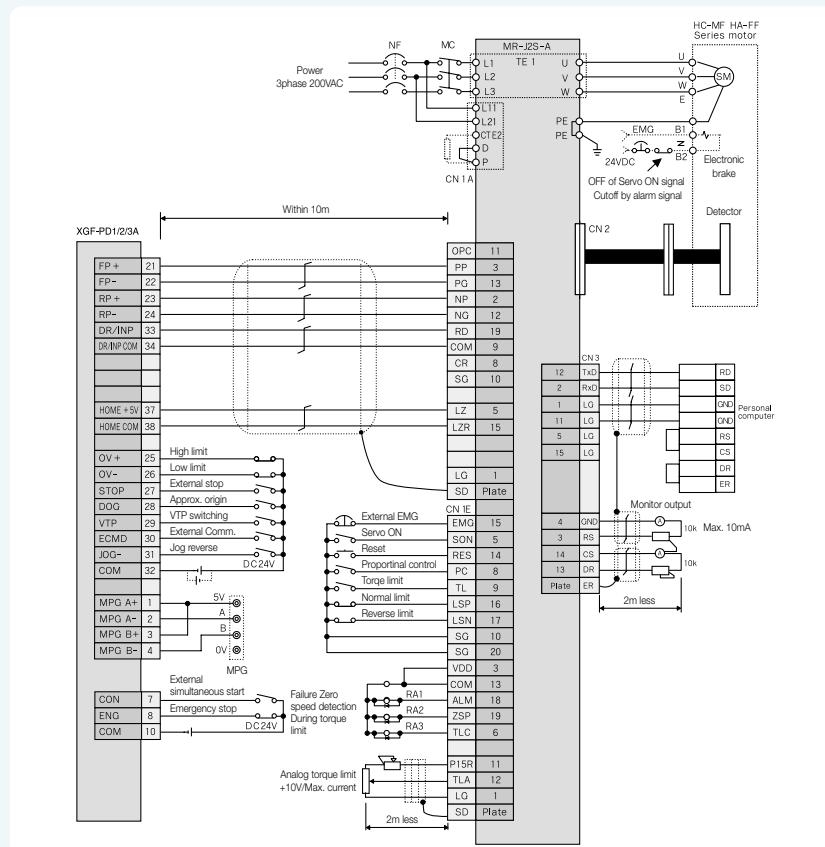
Special



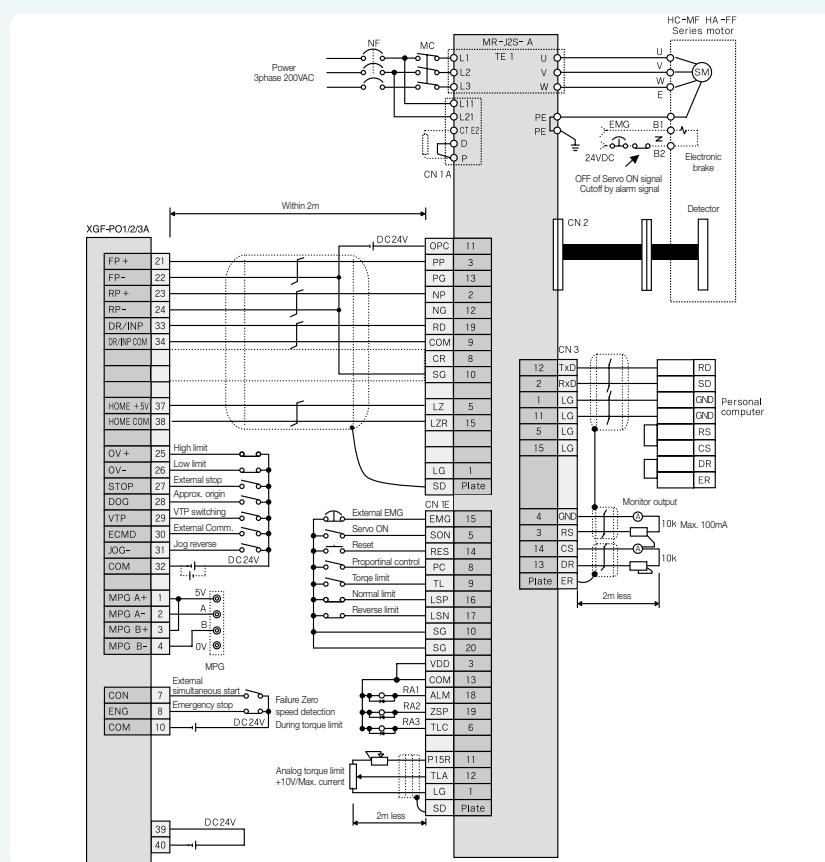
## Special module / Positioning module

### Connection with MR-J2/J2S-□A

- XGF-PD1/2/3A (Line Driver)

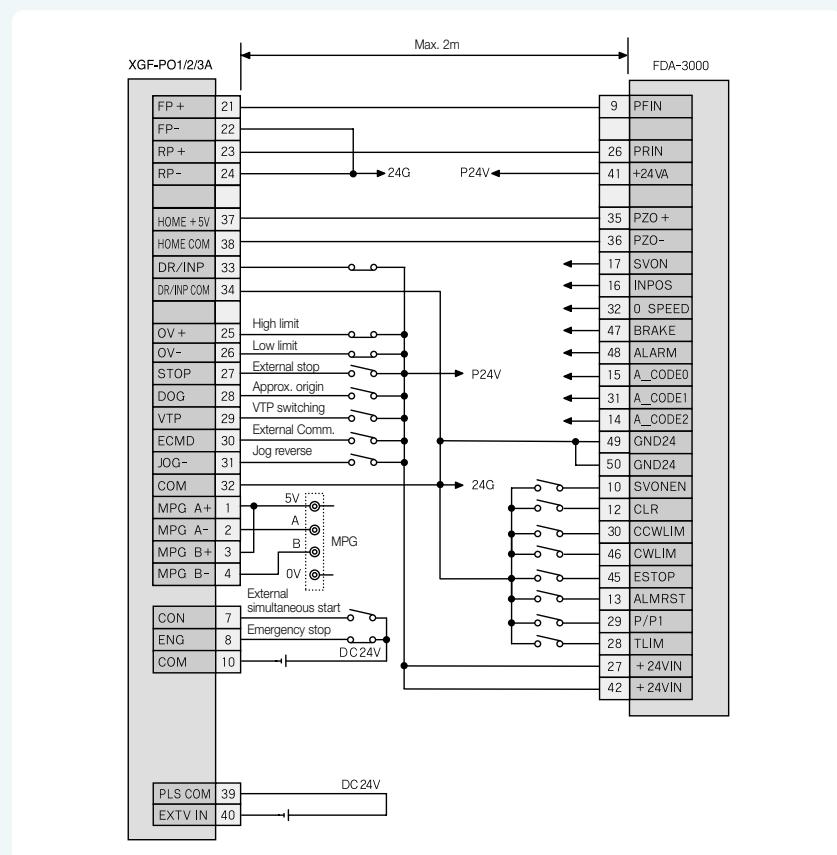


- XGF-PO1/2/3A (Open Collector)



## Connection with FDA-3000 AC Servo driver

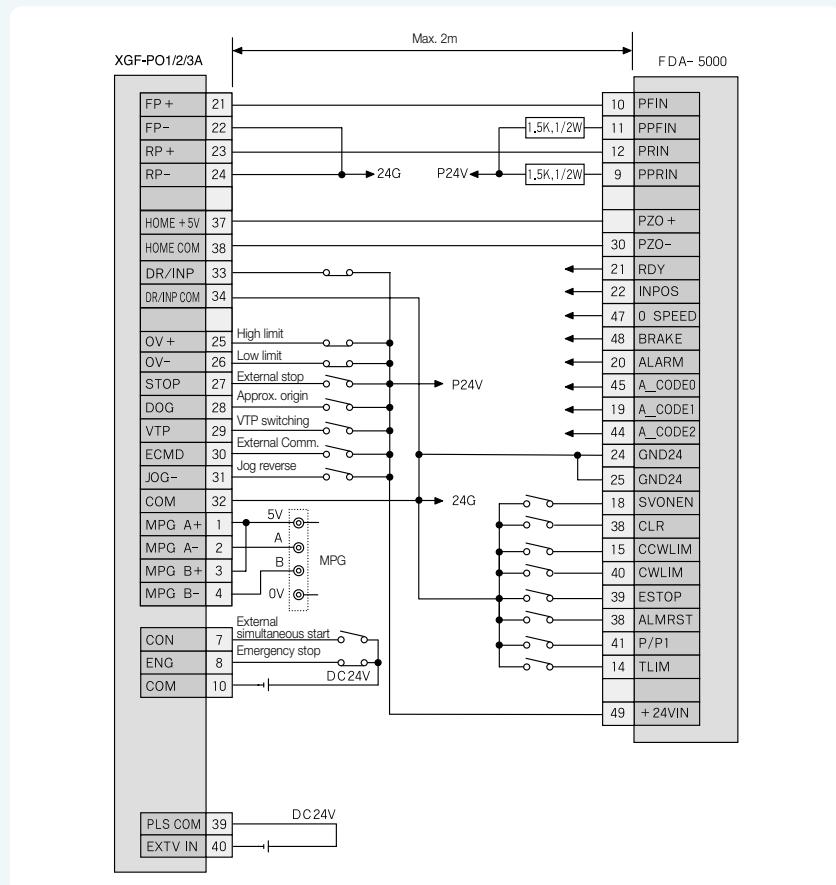
- XGF-PO1/2/3A (Open Collector)



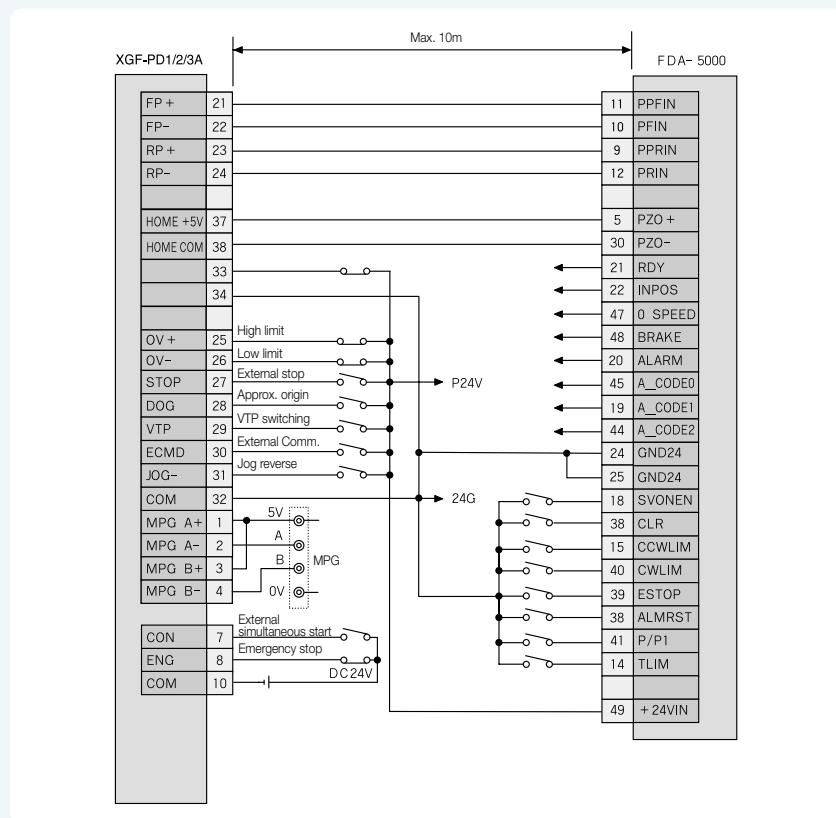
## Special module / Positioning module

### Connection with FDA-5000 AC Servo driver

- XGF-PO1/2/3A (Open Collector)



- XGF-PD1/2/3A (Line Driver)

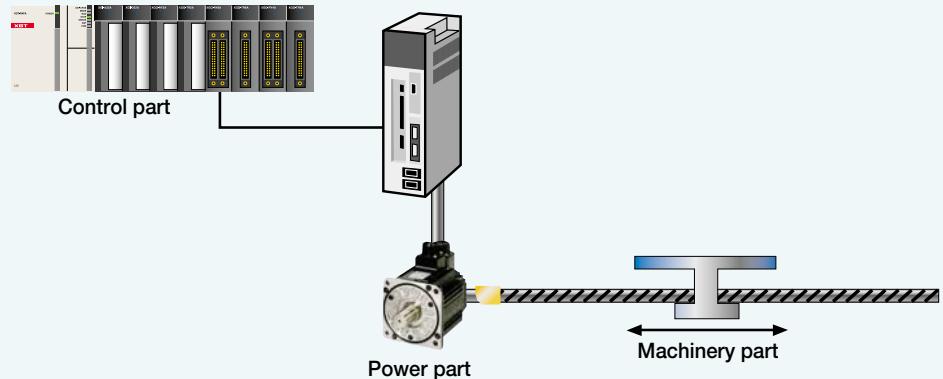


## Special module / Positioning module (Example)

This is a simple example to control 1-axis servo motor.

### System configuration

- Positioning system consists of control part, power part, and machinery part.
- Control part: Install APM module on base and complete parameter setting and programming.
- Power part: Power part generates momentum, and it consists of [servo-driver + servo-motor] and [step-driver + step-motor].
- Machinery part: Machinery part is to transport objects, and it can be ball screw, timing belt and rack gear.

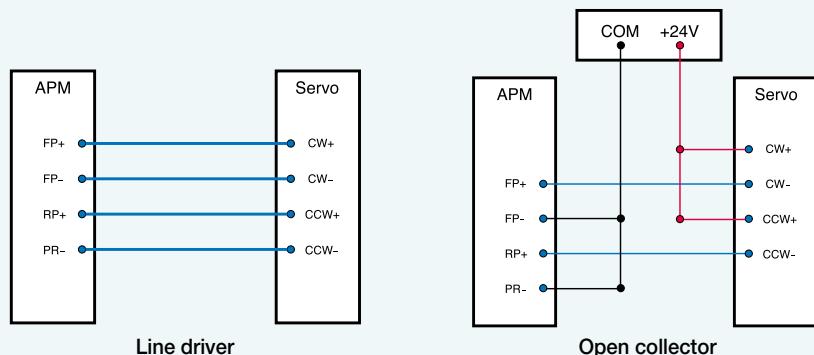


### System design

- APM: Determine type and quantity considering the number of control axis and operation function.
- Driver: Select driver with identical output type of APM.  
(In case output type of APM is line driver, driver should support a pulse train input type of line driver.)
- Motor: Select capacity considering operation characteristics of load.
- Mechanical: Design precise mechanical system to minimize error.

### Connection to drivers

- The following picture is wiring pulse train signal between driver and APM for pulse train signal.
- Terminal besides pulse train signal is used additionally according to user-purpose, system characteristics.
- For wiring of optional terminal of Servo (Step) driver, refer to user's manual.



## Special module / Positioning module (Example)

### Parameter, data setting and transmission

- Set system characteristic, target location, operation speed, and operation type using APM software package.
- Transmit operation parameter and data to APM.

	Item	X-Axis
Basic Parameter	Unit	1: mm
	Pulse per Rotation	5000 pls
	Travel per Rotation	5000.0 um
	Unit Multiplier	0 x 1
	Pulse Output Mode	0 CW/CCW
	Bias Speed	0.01 mm/m
	Speed Limit	10000.00 mm/m
	ACC/DEC No.1	500 ms
	ACC/DEC No.2	1000 ms
	ACC/DEC No.3	1500 ms
	ACC/DEC No.4	2000 ms
S/W Upper Limit	S/W Upper Limit	214748364.7 um
	S/W Lower Limit	-214748364.8 um
	Backlash Comp	0.0 um
	Position Complete Time	1000 ms
	Ext. Command Selection	0 Start

Setting parameter of system characteristic



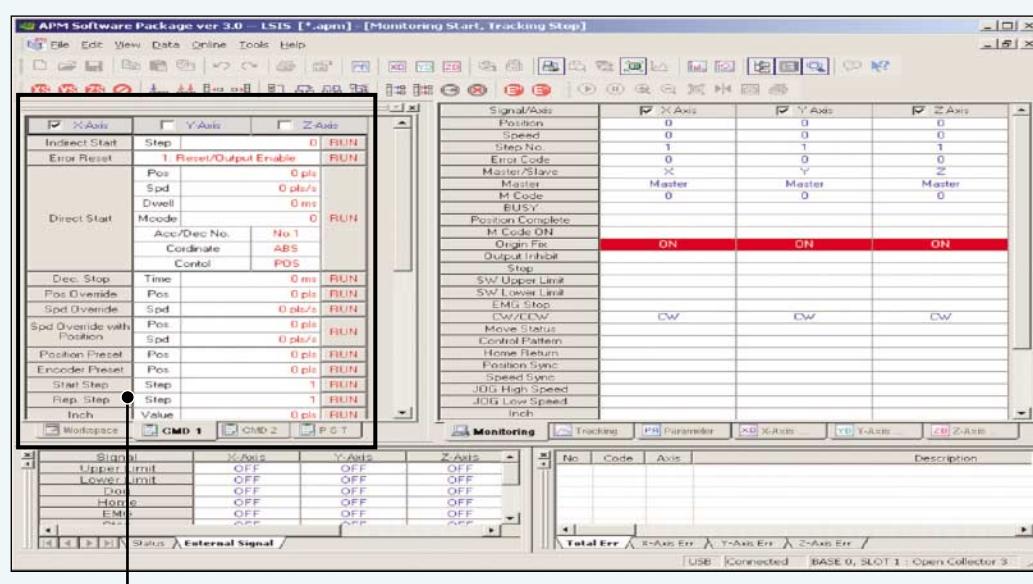
Step	Cord	Control	Pattern	Method	Address [un]	Sub Address [un]	M Code	A/D No.	Speed [mm/mm]	Dwell [ms]	Ctrl Dir
1	ABS	POS	END	SIN	0.0	0.0	0	No.1	0.00	0	CW
2	ABS	POS	END	SIN	0.0	0.0	0	No.1	0.00	0	CW
3	ABS	POS	END	SIN	0.0	0.0	0	No.1	0.00	0	CW
4	ABS	POS	END	SIN	0.0	0.0	0	No.1	0.00	0	CW

Target location, speed, operation type, operation data

APM software package

### Initial system inspection

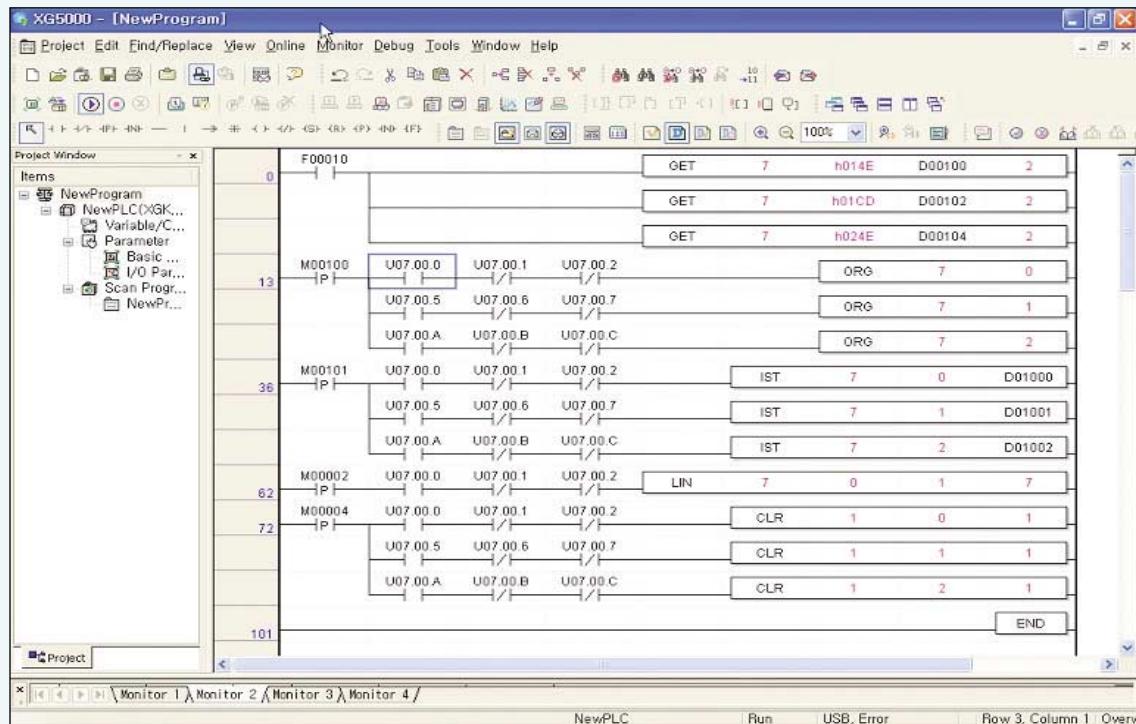
- Perform a trial-run using APM Software Package, and check external wiring, operation data setting, and status of machinery part. It is recommended to do trial-run before programming.
- If a program is saved in CPU and operation mode is 'RUN', a unexpected fault can occur due to disagreement between operation condition of operation control program and operation result of APM Software Package.



Operate APM without positioning programming

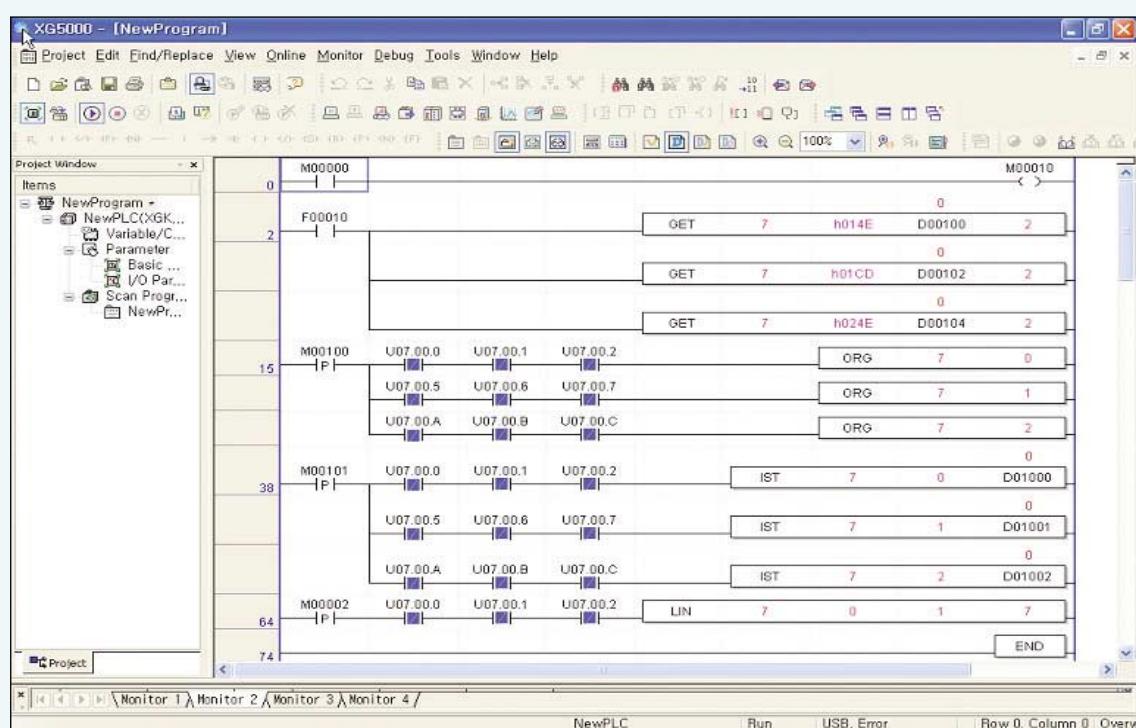
## Programming

- Create a program using dedicated command for APM control.  
ex) Origin point return-ORG, Independent operation-IST



## Program monitoring

- Monitor output condition following input condition and inspect operation status of APM and correct programming error.



## Special module / RTD input module

### Features

- Supports various additional functions (average, alarm, filter)
- Special module parameter setting and monitoring with XG5000
- Supports digital conversion, temperature display and user scaling

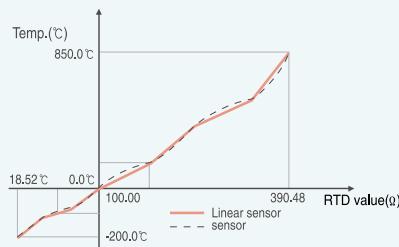
### Specifications

Item		XGF-RD4A	XGF-RD4S
No. of input channel		4 channels	4 channels
Input sensor type	Pt100	JIS C1604-1997	JIS C1604-1997
	JPt100	JIS C1604-1981, KS C1603-1991	JIS C1604-1981, KS C1603-1991
	PT1000	-	JIS C1604-1997
	NI100	-	DIN 43760-1987
Temperature input range	Pt100	-200.0 ~ 850.0°C	-200.0 ~ 850.0°C
	JPt100	-200.0 ~ 640.0°C	-200.0 ~ 640.0°C
	PT1000	-	-200.0 ~ 850.0°C
	NI100	-	-60.0 ~ 180.0°C
Digital output	Temperature display (unit: 0.1)	Pt100: -2,000 ~ 8,500 JPt100: -2,000 ~ 6,400 PT1000: - NI100: -	-2,000 ~ 8,500 -2,000 ~ 6,400 -2,000 ~ 8,500 -2,000 ~ 1,800
	Scaling display (Customize)	0 ~ 65535 -32768 ~ 32767	
	Accuracy	Normal temp.(25°C): ±0.2% Full temp.(0~55°C): ±0.3%	±0.1% ±70ppm/ °C
	Conversion speed		40ms / channel
Insulation	Channel to Channel	Non-insulation	Insulation
	Terminal to PLC Power		Photo-coupler
Wiring method	3-wire		4-wire
	Average		Time average (320~64000ms) Counting average(2~64000 count) Moving average(2~100 samples)
	Alarm		Process alarm Input changing rate alarm Disconnection detection
	Filtering		Digital filter (160~64000ms) 18-point terminal block
Terminal block		5V: 450mA	5V: 720mA
Current consumption			
Weight [g]		150g	

### Characteristics of temperature conversion

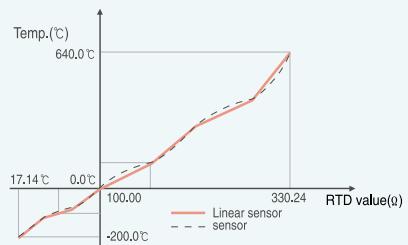
• Pt100 :

JIS1604-1997



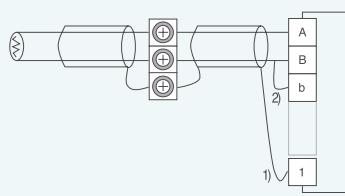
• jPt100 :

JIS1604-1981,  
KS C1603-1991

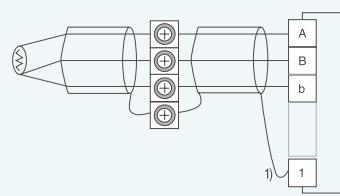


### Wiring

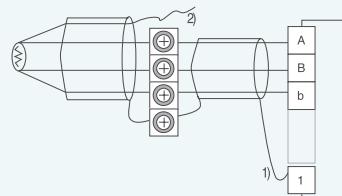
• Connection with 2-wire type sensor



• Connection with 3-wire type sensor



• Connection with 4-wire type sensor



1) When sensor and compensating wire are shielded, shield-connection to FG terminal of the module is available.

2) The wiring of 4-wire type sensor is identical with the wiring of 3-wire type sensor. 3 wires is connected to the module. But the other wire is not connected with the module.

## Special module / Thermocouple module

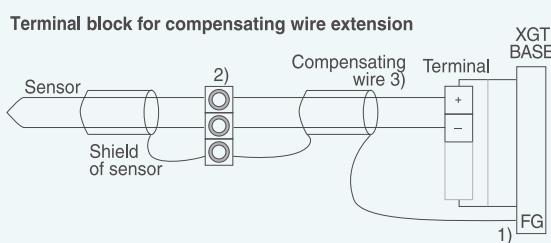
### Features

- Insulation between channels
- $\pm 0.1\%$  ( $25^\circ\text{C}$ ) constant density
- Supports various input sensor (supporting C-type sensor)
- Various additional functions (average, filter, alarm, max/min value display)
- Special module parameter setting and monitoring with XG5000

### Specifications

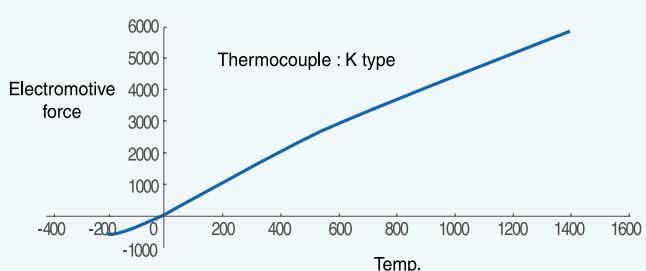
Item	XGF-TC4S	
Input channels	4 channels	
Input sensor type	K, J, E, T, B, R, S, N, C	JIS C1602-1995ITS-90
	K	-250 ~ 1350°C
	J	-200 ~ 1200°C
	E	-250 ~ 1000°C
	T	-250 ~ 400°C
	B	400 ~ 1800°C
	R	-50 ~ 1750°C
	S	-50 ~ 1750°C
	N	-270 ~ 1300°C
	C	0 ~ 2300°C
	Temperature display (unit: 0.1)	Display down to the first decimal place (0.1°C)
Digital output	Scaling (User range setting)	0 ~ 65535 -32768 ~ 32767
	Normal temp. ( $25^\circ\text{C}$ )	$\pm 0.1\%$ Some section can permit 0.5%
Accuracy	Temperature coefficient (Operating temp. range)	$\pm 100\text{ppm}^\circ\text{C}$
Conversion speed	40ms/ channel	
Insulation	Between channels	Insulation
	Between terminals and power	Insulation(Photo-Coupler)
Compensation	Automatic compensation by RJC sensing (PT100)	
	Compensation degree	$\pm 1.0\%$
	Average	Average time (320 ~ 6400ms) Average number (2~ 64000) Average move (2 ~ 100)
Function	Alarm	Process Alarm Change rate alarm Burn-out detection
	Filter	Digital filter (160 ~ 64000ms)
	Max./Min. values display	Max./Min. values display
Terminal block	18-point terminal block	
Current consumption	5V : 610mA	
Weight (kg)	0.150	

### Input wiring



- 1) When sensor and compensating wire are shielded, shield connection to FG terminal is available.
- 2) To minimize an error, overall temperature of block terminal need to be equal.
- 3) Compensating sensor should be the same type of sensor which is used for measurement.

### Characteristics of I/O conversion



## Special module / Temperature controller

### Features

- Optimum temperature control
- Universal input: TC, RTD, Voltage, Current
- Isolated input
- Output: Current/Transistor
- Parameter setting via dedicated software: TG-CON
- Variety of control types
  - PID control
  - Cascade control
  - On/ Off control
- Disconnection detection
- Various input functions: Bias, Filter, Square root
- Auto-tuning



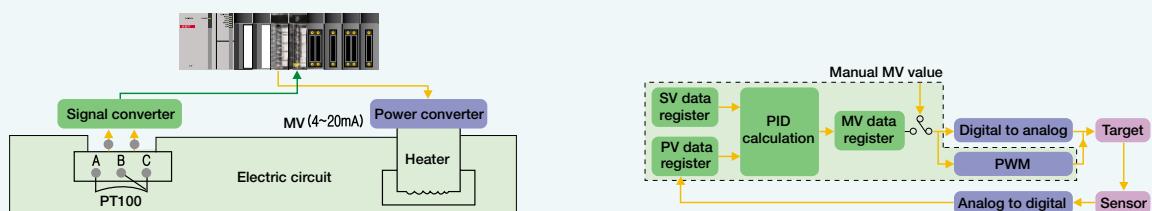
### Specifications

Item	XGF-TC4UD		
No. of loop	4 loops		
Input	Thermo couple	K	-200 ~ 1300°C 0 ~ 500°C
		J	-200 ~ 1200°C 0 ~ 500°C
		E	-200 ~ 1000°C
		T	-200 ~ 400°C
		B	400 ~ 1800°C
		R	0 ~ 1700°C
		S	0 ~ 1700°C
		N	-200 ~ 1300°C
		C(W5Re/W26Re)	0 ~ 2300°C
		PL II	0 ~ 1300°C
	RTD	L	-200 ~ 900°C
		U	-200 ~ 600°C
		Pt100	-200 ~ 850°C
Voltage	DC mV	Pt100	-200 ~ 600°C
		JPt100	-200 ~ 800°C
		Pt1000	-200 ~ 800°C
		DC mV	0 ~ 10mV 0 ~ 100mV
		DC V	0 ~ 1V 1 ~ 5V 0 ~ 5V 0 ~ 10V -5V ~ 5V 10V ~ 10V
		Current	4 ~ 20mA 0 ~ 20mA
	Input channel		4 channels (Input type selection per channel)

## Specifications

Item	XGF-TC4UD					
Resolution	Resolution Refer to the user's manual (Resolution for each input type)					
Cold junction compensation	Compensation	Automatic compensation by RJC sensor				
	Precision	$\pm 0.2^\circ\text{C}$				
Digital output	Temperature display	$0.1^\circ\text{C}/1^\circ\text{C}$ (Selection by software)				
	Linear display	0~1000				
Control type	Scale display	Only for voltage/current input Range : -3,000~3,000 Setting range: 0~3000				
		0.2sec/4 loops				
Conversion speed	PID, On/Off control					
Parameter	Set value (SV)	Selection per input type				
	Gain	0 : ON/OFF control, Real type				
	Integrated time	0 : No Differential control, Real type				
	Differential time	0 : No Integrated control, Real type				
Output	No. of output channel	8 channels (PWM or analog output)				
	PWM	Rated load voltage	DC 24V			
		Max. current point	0.1A points			
		On voltage drop	DC 0.3V or less			
		Off leakage current	0.1mA or less			
		Response time	ON $\Rightarrow$ OFF	1ms or less		
			OFF $\Rightarrow$ ON	1ms or less		
	Analog output	Periodic	0.5~120.0sec (resolution: 0.5sec)			
		Time resolution	High value between 10ms or 0.5% of full scale			
		Range	4~20mA			
		Resistance	600 $\Omega$ or less			
Insulation	Resolution	$\pm 1.0\%$ , 25°C				
	Precision	8 $\mu$ A				
	Item	Insulation	Insulation withstand voltage	Insulation resistance		
	Channel - Channel	Trans	500V AC, 50/60Hz 1min,	500V DC, 10M $\Omega$ or more		
Terminal	Input terminal - PLC	Photocoupler	Leakage 10mA or less			
	Current output - Current output	Non insulation				
Power	External power- Output					
	Warm-up	20min or more				
Terminal		18 points terminal				
Power		5V, DC 24V (external)				
Current consumption		DC 5V : 900mA (Internal) DC 24V : 300mA (external)				

## Example: Constant temperature





# Software

Software innovation for integrated solution.

XG5000 is the optimum software which can cover various programming needs, debugging, and easy maintenance. Especially, XG-PD achieves customer satisfaction with useful maintenance tool by internet.





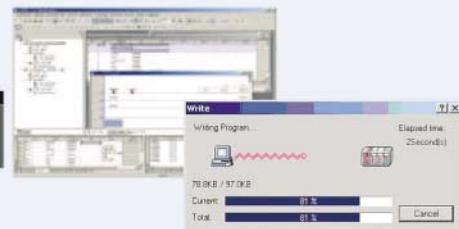
## Software / XG5000 programming

### Features

- Program editing & Engineering software
- Windows-based easy operation
- Multi-PLC, Multi-program, Multi-task in one project
- Various monitoring and diagnosis functions
- Windows 2000, XP (Limited use in Windows 98, ME)



**Connection**  
-Direct connection with  
CPU (USB, RS-232C)  
-Ethernet  
-Modem



### Programming tools

#### MPMP (Multi-PLC Multi-programming)

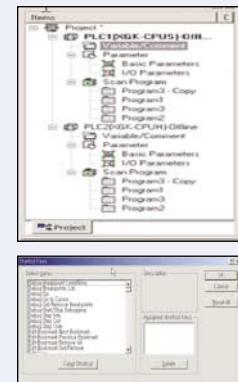
Different PLC systems can be edited, monitored, and managed simultaneously in one project.

#### Drag & Drop

It is available in project, variable/comment, ladder diagram editing and monitoring.

#### User-defined shortcut keys

User-defined shortcut keys increase editing convenience.

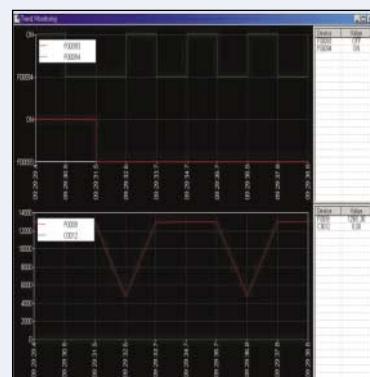


### Monitoring

Monitor Special Module		
Item	Channel 0	Channel 1
Current CountValue	0	0
Latch CountValue	0	0
Range CountValue	0	0
Input Frequency	0 (°/s)	0 (°/s)
Revolution/Unit Time	0	0
FLAO Monitor	FLAO Monitor	
Item	Setting Value	Current Value
Channel	Linear	Linear
Counter Mode	2-Phs x1	2-Phs x1
Pulse Input Mode	0	0
Preset	0	0
Ring Counter Min	0	0
Ring Counter Max	0	0
Comp Output0 Mode	(Magnitude) <	(Magnitude) <
Comp Output0 Mode	(Magnitude) <	(Magnitude) <
Comp Output0 Min	0	0
Comp Output0 Max	0	0
Comp Output1 Min	0	0
Comp Output1 Max	0	0
Output Status Setting	Output Disable	Output Disable
Auxiliary Mode	No Auxiliary	No Auxiliary
Range Value [ms]	0	0
Pulse/RewValue	1 Hz	1 Hz
Frequency Mode		

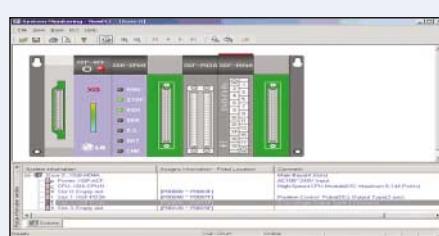
#### Special module monitoring

Monitoring and test-run of various special modules are available.



#### Trend monitoring

The changing value of specific device can be monitored and saved as a file.



#### System monitoring

Device monitoring		
Value	Variable	Comment
0	0	
1	1	
2	2	
3	3	
4	4	
5	5	
6	6	
7	7	
8	8	
9	9	
10	10	
11	11	
12	12	
13	13	
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15	15	
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99	99	
100	100	

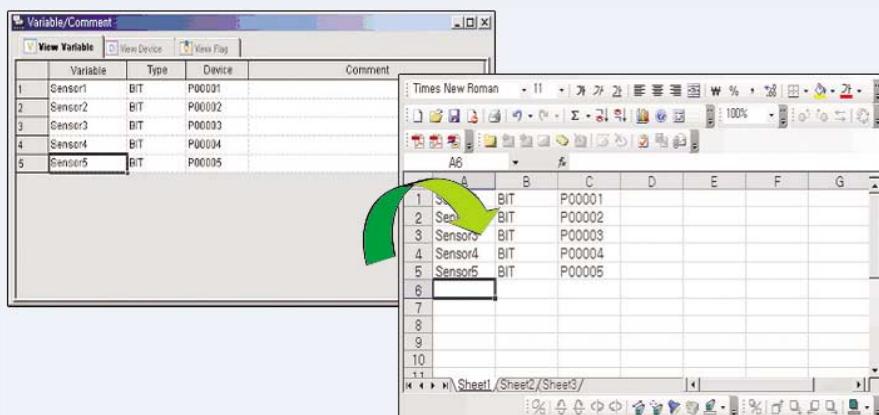
#### Variable monitoring

## System requirement

Item	System requirement
O/S	Windows 2000, XP (Limited use in Windows 98, ME)
CPU	IBM compatible PC with Min. 200MHz Pentium processor
Memory	Min. 128M
HDD	100 MB (Free memory space)
Serial port	Communication port for program transmission (RS-232C, USB)
Printer	Compatible with Windows 98 or later
Mouse	Compatible with Windows 98 or later

## Variable and programming editing

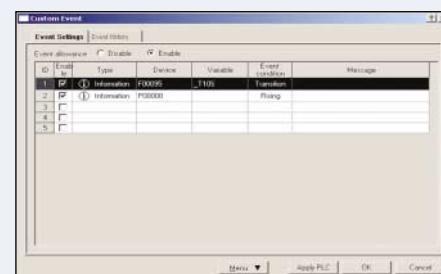
- Data input like EXCEL
- Cell-unit edit
- Auto Fill function
- Compatible with Microsoft Excel
- Redo and Undo (Unlimited)
- Segment screen edit



## Improved diagnosis and maintenance



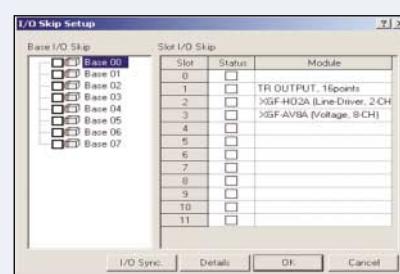
**Module exchange wizard**  
It supports safe module exchange during 'RUN' mode.



**User-defined event**  
By registering user-defined event, users can read the record of specified event and use it for PLC operation and debugging.



**Forced I/O**  
The status of external output device can be checked without program.  
And when input device breaks down, forced input function specifies ON/OFF and can operate the system without interruption of equipment.

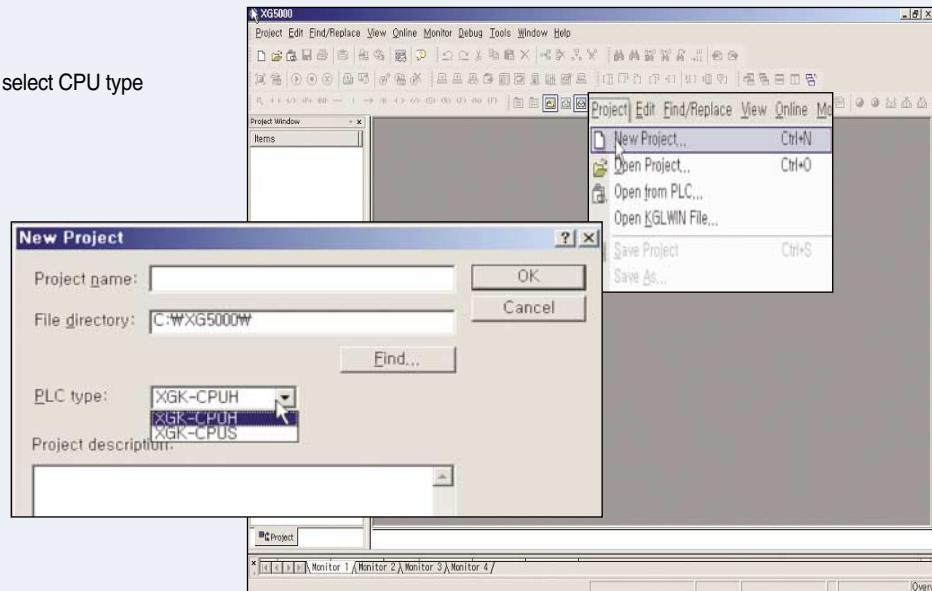


**I/O skip, Error Mask**  
I/O inspection and renewal can be set for specific module and continuous operation is available when an error is occurred.

## Software / XG5000 programming

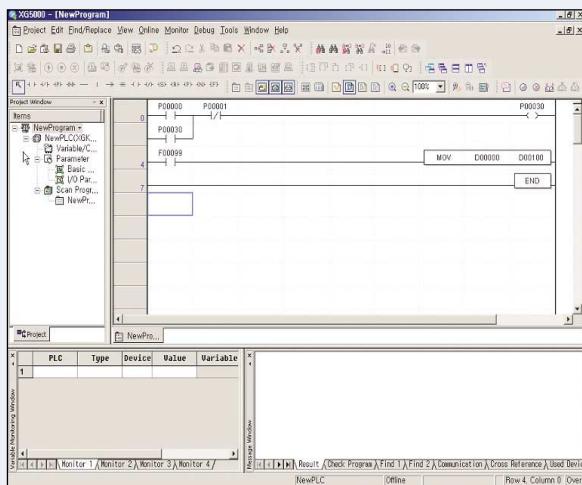
### Program editing

- Start XG5000
- Select [New Project]
- Write project name and select CPU type



### Configure ladder lines as below with ladder input tool bar

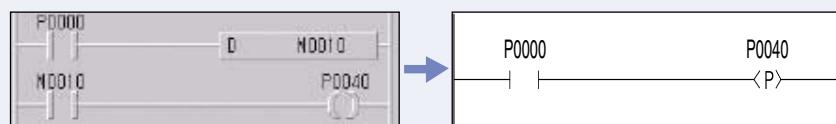
- Select input point and command with ladder tool bar.



Icon	Description	Short key
	Arrow mode	ESC
	Normally open contact	F3
	Normally closed contact	F4
	Positive transition-sensing contact (On for 1 scan when Off->On)	Shift+F1
	Negative transition-sensing contact(On for 1 scan when On->Off)	Shift+F2
	Horizontal line	F5
	Vertical line	F6
	Fill horizontal line.	Shift+F8
	Coil	F9
	NOT instruction contact	Shift+F9
	Negated coil	F11
	SET coil	Shift+F3
	RESET coil	Shift+F4
	Positive transition-sensing coil (On for 1 scan when Off->On)	Shift+F5
	Negative transition-sensing coil (On for 1 scan when On->Off)	Shift+F6
	Function	F10

### Note) Addition of 'EDGE' detection instructions

Develop user-friendly programming through adding D, D NOT instructions (Rising EDGE, dropping EDGE) to contact and output coil.



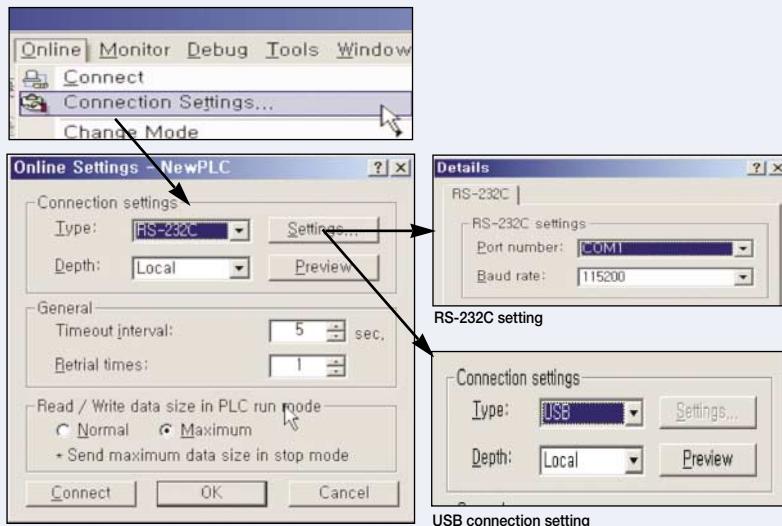
## Program download

### Connection setting

- Check a setting for connection between XGT and XG5000
- XGT supports USB and RS-232C

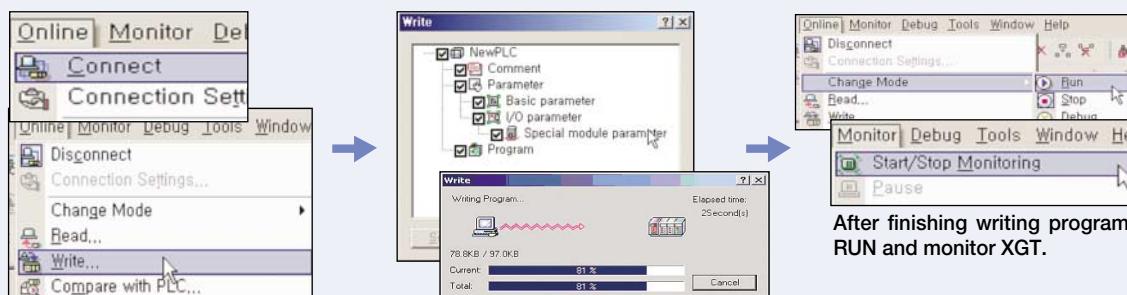
Set up communication port and download speed

\* using 'USB TO RS-232C' converter, 115,200bps connection may be unavailable depending on characteristics of converter. In this case, change the communication speed to 38,400bps.



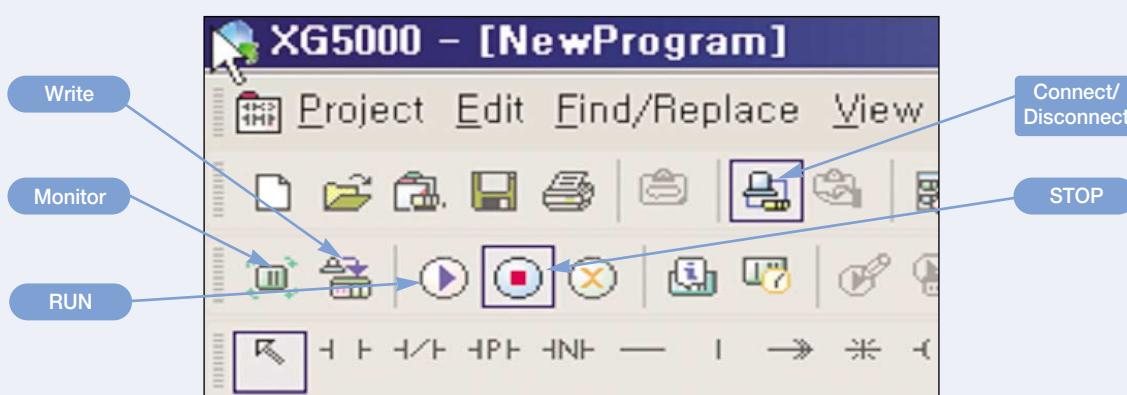
### Connection

Connect to PLC and download the program as below.



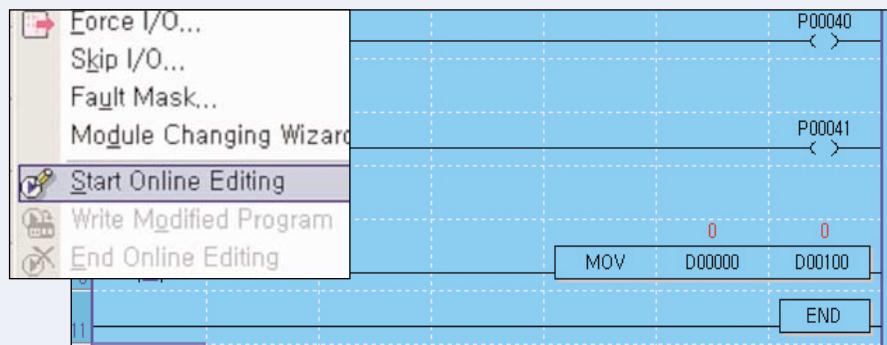
### Short icon

\* XGT doesn't support collective-writing monitoring for system safety.



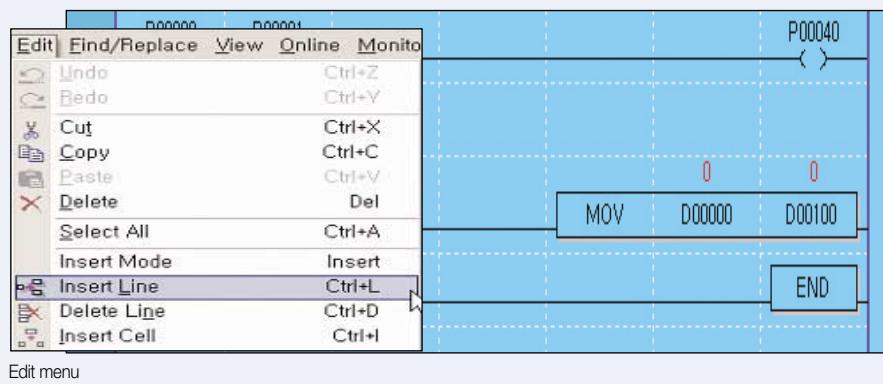
### Online Editing

Select [Start Online Editing] in Online menu.



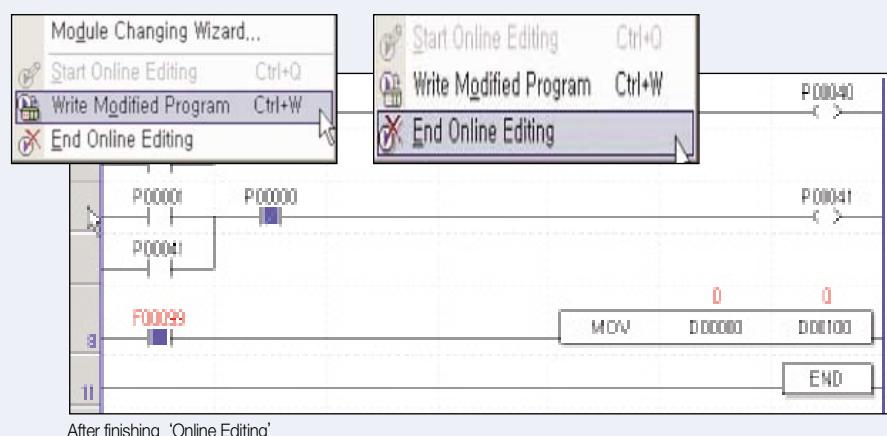
When starting Online Editing, the screen color becomes blue.

Modify the program.



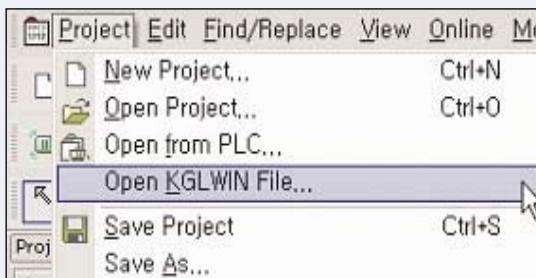
Edit menu

After finishing modifying the program, select [Write Modified Program] and [End Online Editing].



After finishing 'Online Editing'

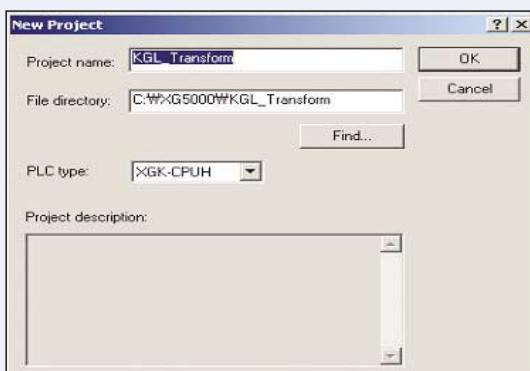
### Open a project written in KGL-WIN



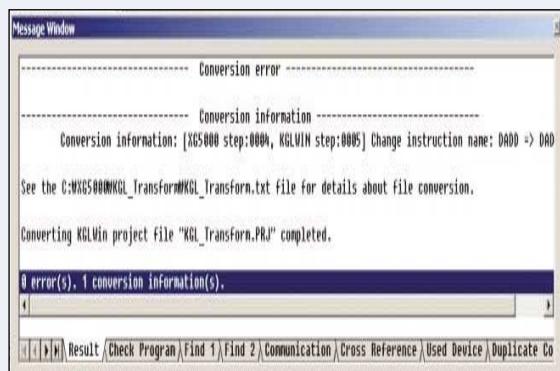
Select [Open KGLWIN file] in project.



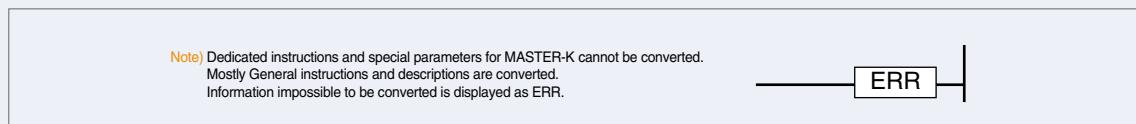
Select the file.



Select the type of XGT CPU.



Check converted information in the message window.

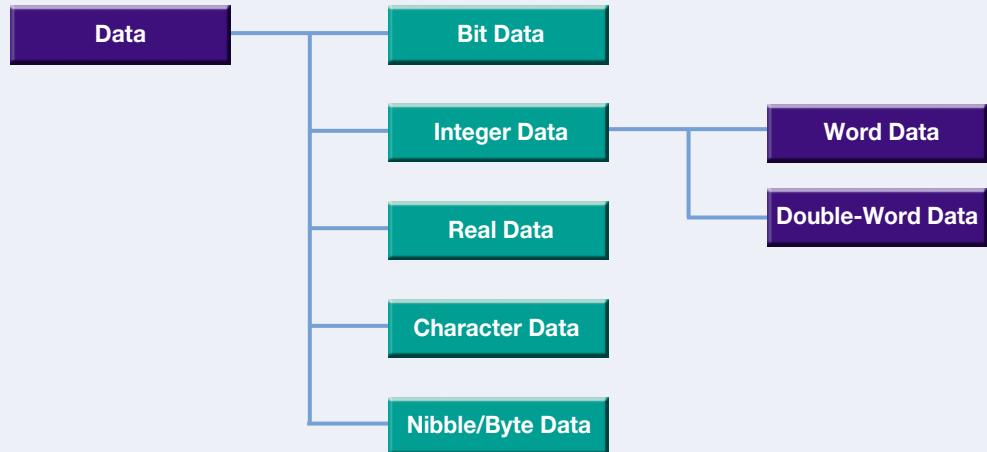


- Content of main special flag (F) change

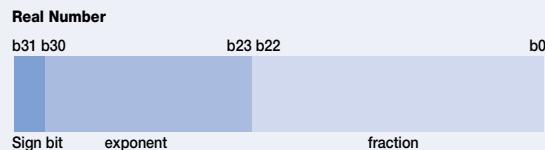
MASTER-K	XGT	Specifications
F10	F99	ON regularly
F11	F9A	OFF regularly
F12	F9B	ON during first one scan
F13	F9C	OFF during first one scan

For more detailed information, refer to user's manual.

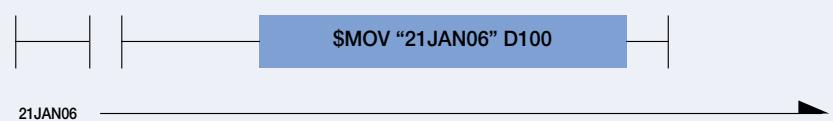
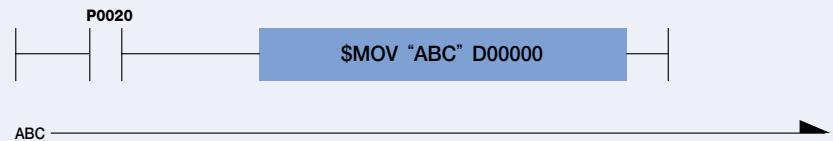
## Data type



- Nibble: 4-bit unit data
  - Byte: 8-bit unit data
  - Real Data: 32-bit/64-bit floating point data



- Character Data: Saving numbers, alphabets, symbols as a type of ASCII code



D100	Ox31	Ox32
D101	Ox41	Ox4A
D102	Ox30	Ox4E
D103	Ox00	Ox36
D104	Ox00	Ox36

## Device Type

Device	Size	Bit Contact	Word Data	Name
P	32768 points	P0000 ~ P2047F	P0000 ~ P2047	I/O Relay
M	32768 points	M00000 ~ M2047F	M0000 ~ M2047	Assistant Relay
L	180224 points	L00000 ~ L11263F	L0000 ~ L11263	Link Relay
N <sup>①)</sup>	21K words	N/A	N00000 ~ N21503	Comm. data register
K	32768 points	K00000 ~ K2047F	K0000 ~ K2047	Keep Relay
F	32768 points	F00000 ~ F2047F	F0000 ~ F2047	Special Relay
T <sup>②)</sup>	2048 points	T0000 ~ T2047	T0000 ~ T2047	Timer
C <sup>③)</sup>	2048 points	C0000 ~ C2047	C0000 ~ C2047	Counter
U	3072 words	U00.00 ~ U7F.31.F	U00.00 ~ U7F.31	Special Module Counter
Z	128 words	N/A	Z0 ~ Z127	Index Register
S	128 groups	S00.00 ~ S127.99	N/A	Step Control Relay
D	32K words	D00000.0 ~ D32767.F	D00000 ~ D32767	Data Register
R (Internal RAM) <sup>④)</sup>	32K words	R00000.0 ~ R32767.F	R00000 ~ R32767	File Register
ZR (Internal RAM) <sup>⑤)</sup>	32K words	N/A	ZR00000 ~ ZR65535	File Register
R (Expanded)	1M words	N/A	Available as much as extension size	File Register
ZR (Expanded)	1M words	N/A	Available as much as extension size	File Register

**Note)** 1. When communication module is not used, it can be used as internal data area.

2. Word data in timer shows a current value of relevant bit contact.

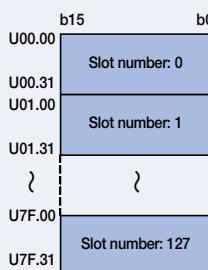
3. Word data in counter shows a current value of relevant bit contact

4. Even when using more than 32K words internal RAM, bit contact available to display is R00000.0-R32767.F Also word data enable to be displayed in the range of R00000.0-R32767.F

5. When internal RAM is more than 32K words, bit contact can be in the range of ZR00000.0-ZR32767.F and word data can be displayed as much as the size of internal RAM

## Special module register U

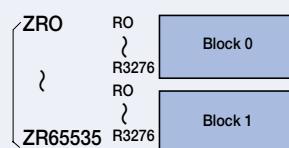
Register for reading data from special module mounted in slot



- Assigning 32 words per slot in U area
- Bit type display available  
Ex) U93.12.x (x: Bit location, Hexadecimal display)
- Available to read/write internal memory value of special module without using PUT (P), GET (P), PUTS (P), GETS (P)
- Basic display in U area  
Ex) Uxy.z  
x: Base number (0~7)  
y: Slot number (0~F)  
z: Word number of special module internal memory

## File register R, ZR

Register that a recorded value is not deleted when power failure is occurred. File register is used for data backup or data storage.

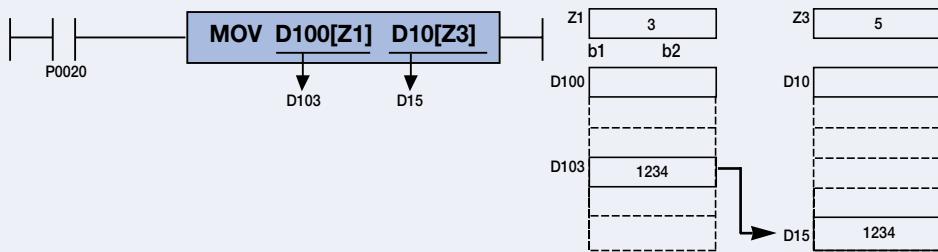


R: Block unit access  
ZR: Entire file register access  
Internal RAM (Temporary preservation): 32K words  
FLASH (Permanent preservation): 1M words

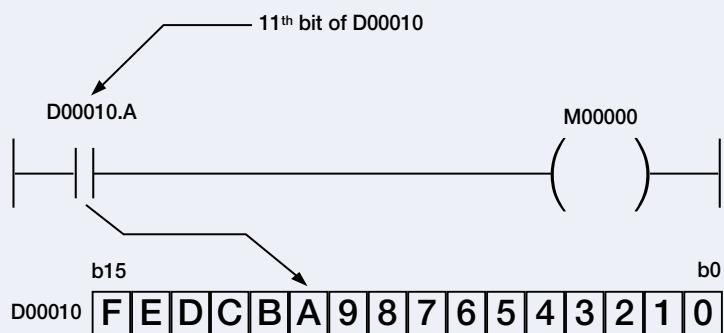
**Index register**

Index register sets up devices using index function.

The sum of index register value and directly specified device number is real device number.

**Available Device**

- Bit Device: P, M, L, K, F, T, C
  - Word Device: U, D, R, ZR, N, present value of T and present value of C
- Ex) MOV T1[Z1] D10 : If Z1 is 5, present value of T(1+5)=T6 is transmitted to D10.  
Ex) LOAD D10[Z1].5 : If Z1 is 5, LOAD(10+5).5 => LOAD D15.5 is set.

**Bit specifying method of word device**

By assigning bit number to word device, bit data is available to use.

Word device number	.	Bit number
--------------------	---	------------

In this case, word device number should be addressed as decimal and bit number should be addressed as hexadecimal.

Relevant Device: U, D, R

## Instructions

Classification	Designations	Symbol	Description	No. of step
16 Bits transfer	MOV	—MOV [S D]—	(S) —————→ (D)	2
	MOVP	—MOVP [S D]—		3
32 Bits	DMOV	—DMOV [S D]—	(S+1, S) —————→ (D+1, D)	2
	DMOVP	—DMOVP [S D]—		3

①      ②      ③      ④      ⑤

① **Classification:** Classifies instructions into applications.

② **Designations:** Displays instruction names to be used in program.

- Display rules: Instructions shall be basically displayed in word unit. According to data size, operation characteristics, real number data process, text process, the rules are as follows;
- Based on Data Size & Type
  - D: Double Word related instruction.
  - R: Real Number related instruction.
  - L: Long Real Number related instruction.
  - However, LMOV is 64 Bits transfer instruction.
  - \$: String related instruction.
  - G: Group calculation.
  - 4: Nibble related instruction, used only at the back of instruction.
  - 8: Byte related instruction, used only at the back of instruction.
  - 3: Instruction that process 3 operands, used only at the back of instruction.
- Based on Operation Characteristics
  - P: Instruction that is executed for 1 scan when input signal is changed OFF → ON

③ **Symbol:** Displays symbols used in program, showing the number of used operands and the type of Source or Destination. Operand display rules are as follows;

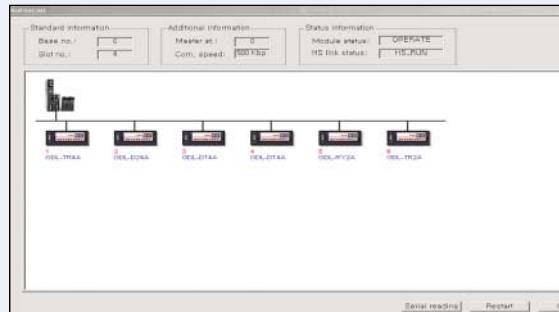
- S: Source, with data value not changed after calculated.
- D: Destination, with data value changeable after calculated.
- N, n: The number to process.
- St, En: Start and End, used only in BSFT & WSFT.
- Sb: Source in case Bit position is specified, mostly used in Nibble/Byte instruction.
- Db: Destination in case Bit position is specified.
- Z: Control word, which means previously specified format as based on each instruction.

④ **Description:** Describes general functions of instruction.

⑤ **No. of step:** The number of basic steps of instruction, which means the number of steps in case indirect specification, index formula and direct variable input were not used.

## Features

- Convenient user-program, network initial basic setting
- Providing extended monitoring, control function of network system and communication module
- Fast interface with CPU by efficient network management
- Unification of instruction system
- Simple and easy connection using dedicated driver (XGT) and other driver (MODBUS)
- Various built-in Diagnosis functions (Link, Auto-scan, Frame, etc.)



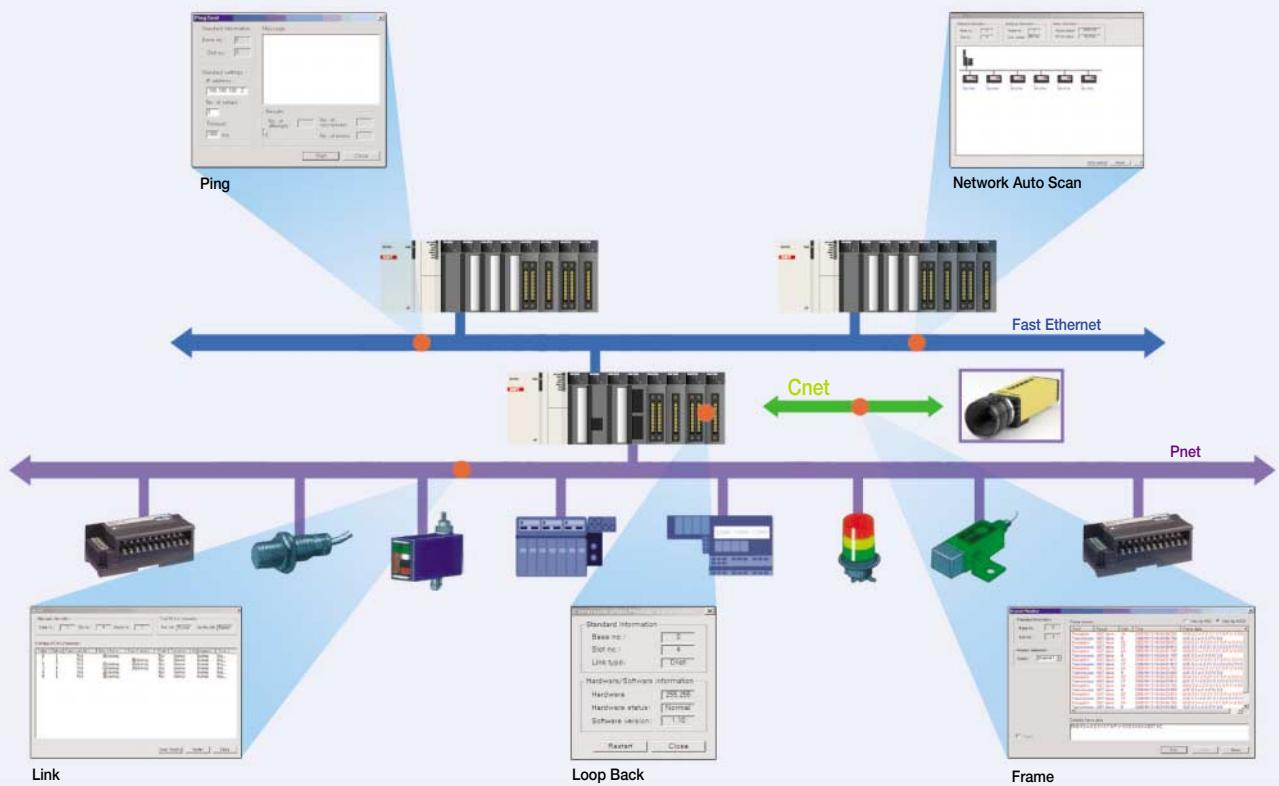
	Item	RAPIDnet	FEnet	FDEnet	IFOS FEnet	Cnet	Rnet	DeviceNet	Profibus-DP
Service	High speed link	○	○	○	○	-	○	○	○
	XGT server protocol	-	○	-	○	○	-	-	-
	MODBUS server protocol	-	○	-	○	○	-	-	-
	P2P	-	○	○	○	○	-	-	-
	XG5000 Service	○	○	○	○	○	○	-	-
High speed link	Max. station	64	64	64	64	-	64	64	126/123
	No. of block	128	128	128	128	-	64	64	126
	Send block	64	32	32	32	-	32	64	126
	Receive block	128-Send block				-	32	64	126
P2P	Data per block	200 words				-	60 words	25 6bytes	244bytes
	No. of block	-	64	64	64	64	-	-	-
	Data per block	-	1 <sup>st</sup> , 2 <sup>nd</sup> stage connection			256 words	-	-	-
System diagnosis		Connection status, network status							
Media		10/100Base-T/FX		100Base-FX	900~115200bps	1Mbps	125/250/500Kbps	9.6K~12Mbps	
Topology		Ring, Bus	Star	Ring, Bus	Star	Bus	Bus, Star	Bus	
Configuration Tool		XG-PD					XG-PD/SyCon		

### Various network diagnosis and monitoring

- Auto Scan: Searching and displaying each node connected to network
- Link Monitor: Monitoring status of high-speed link communication of each station
- Frame Monitor: Collecting and displaying sending/receiving frame in real time



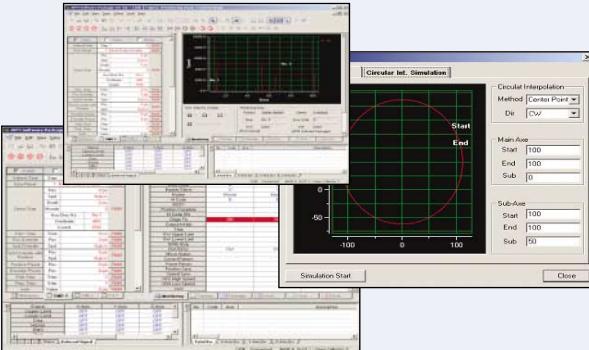
Item	FEnet	FDEnet	Cnet	Pnet	Dnet
	Fast Ethernet	Dedicated Ethernet			
Auto Scan	●	●	●	●	●
Link Monitor	●	●	●	●	●
Frame Monitor	—	—	●	—	—



## Software / APM[Positioning module] Software Package

### Features

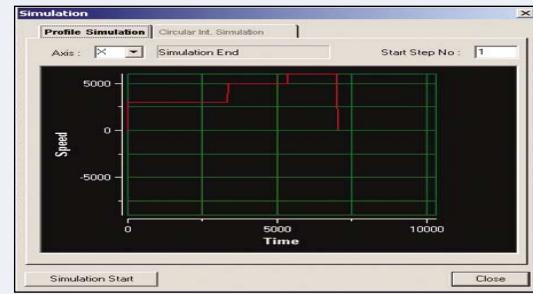
- Windows-based easy operation
- Supporting all types of LS APM module
- Improved parameter editing (Copy, Paste, Initialization, etc.)
- Various monitoring (Operation type of each axis, etc.)
- Profile trace and operation monitoring
- Profile graph and simulation of circular interpolation
- Available to edit operation parameter in EXCEL



Step	Code	Control	Pattern	Method	Address [pulse]	Sub Address [index]	M Code	A/D No.	Speed [pulse/s]	Dwell [ms]	Cr. Int Dir
1	ABS	POS	END	SIN	10000	0	0	No.1	1000	0	CW
2	ABS	POS	END	SIN	0	0	0	No.1	0	0	CW
3	ABS	POS	END	SIN	0	0	0	No.1	0	0	CW
4	ABS	POS	END	SIN	0	0	0	No.1	0	0	CW
5	ABS	POS	KEEP	SIN	100000	0	0	No.1	0	0	CW
6	ABS	POS	END	SIN	0	0	0	No.1	10000	0	CW
7	ABS	POS	END	SIN	0	0	0	No.1	10000	0	CW
8	ABS	POS	END	SIN	0	0	0	No.1	0	0	CW
9	ABS	POS	END	SIN	0	0	0	No.1	0	0	CW
10	ABS	POS	CONT	SIN	100000	0	0	No.1	0	0	CW
11	ABS	POS	END	SIN	1000	0	0	No.1	10000	0	CW
12	ABS	POS	END	SIN	0	0	0	No.1	5000	0	CW

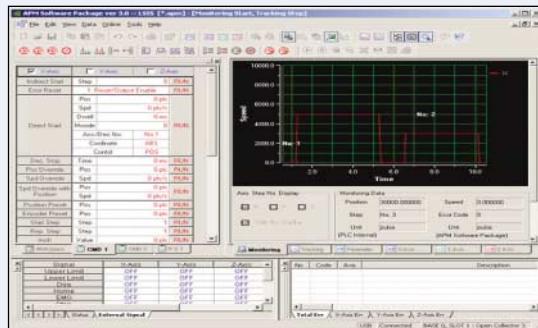
#### Operation Data

Define operation method, target location, operation speed of each axis.



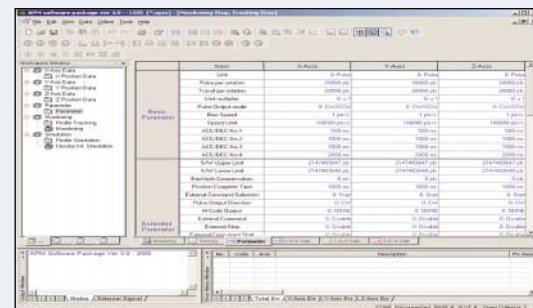
#### Profile simulation (Off-line)

Monitoring operation speed of each axis with graph type and saving result as image file.



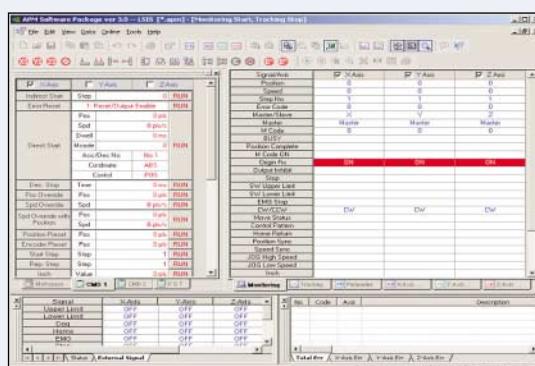
#### Profile Trace (On-line)

Monitoring operation speed of each axis with graph type and saving result as image file.



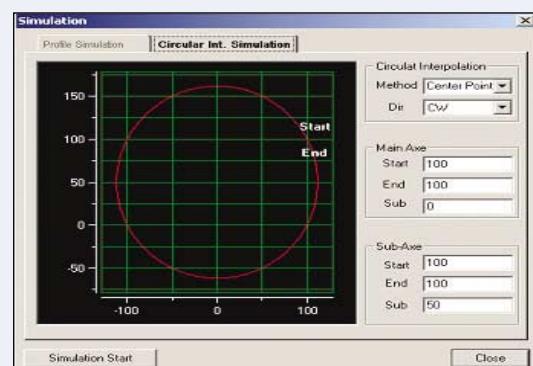
#### Operation parameter

Setting basic operation characteristics and limit value.



#### Monitoring (On-line)

Checking basic operation characteristics about each axis and monitoring operation condition.



#### Circular interpolation simulation (Off-line)

## Product list

### CPU / PWR / Base / I/O

CPU	XGI-CPUU	6,144pt (IEC type), Program memory: 1Mbyte
	XGI-CPUH	6,144pt (IEC type), Program memory: 1.5Mbyte
	XGK-CPUU	6,144pt, Program memory : 128Ksteps
	XGK-CPUH	6,144pt, Program memory : 64Ksteps
	XGK-CPUA	3,072pt, Program memory : 32Ksteps
	XGK-CPUS	3,072pt, Program memory : 32Ksteps
	XGK-CPUE	1,536pt, Program memory : 16Ksteps
Power	XGP-ACF1	Free Voltage/DC5V 3A, DC24V 0.6A
	XGP-ACF2	Free Voltage/DC5V 6A
	XGP-AC23	220V/DC5V 8.5A
	XGP-DC42	DC24V/DC5V 6A
Main base	XGB-M04A	4 Slot
	XGB-M06A	6 Slot
	XGB-M08A	8 Slot
	XGB-M12A	12 Slot
Expansion base	XGB-E04A	4 Slot
	XGB-E06A	6 Slot
	XGB-E08A	8 Slot
	XGB-E12A	12 Slot
Input	XGI-A12A	AC110V, 16pt
	XGI-A21A	AC220V, 8pt
	XGI-D21A	DC24V, 8pt
	XGI-D22A	DC24V, 16pt, Sink/Source
	XGI-D22B	DC24V, 16pt, Source
	XGI-D24A	DC24V, 32pt, Sink/Source
	XGI-D24B	DC24V, 32pt, Source
	XGI-D28A	DC24V, 64pt, Sink/Source
	XGI-D28B	DC24V, 64pt, Source
Output	XGQ-RY1A	Relay, 8pt
	XGQ-RY2A	Relay, 16pt
	XGQ-RY2B	Relay, 16pt, Surge killer
	XGQ-SS2A	Triac, 16pt
	XGQ-TR2A	Transist, 16pt, Sink
	XGQ-TR2B	Transist, 16pt, Source
	XGQ-TR4A	Transist, 32pt, Sink
	XGQ-TR4B	Transist, 32pt, Source
	XGQ-TR8A	Transist, 64pt, Sink
	XGQ-TR8B	Transist, 64pt, Source
Input/output	XGH-DT4A	DC24V 16pt, Transist, 16pt, Sink

### Communication module

RapiNet	XGL-EIMT	RapiNet Twisted pair
	XGL-EIMH	RapiNet Twisted pair/ Fiber
	XGL-EIMF	RapiNet Fiber optic 2ch
	XOL-EIMT	RapiNet Twisted pair 2ch
	XOL-EIMF	RapiNet Fiber optic 2ch (PC)
Cnet	XGL-CH2A	RS-232C/RS-422
	XGL-C22A	RS-232C, 2ch
	XGL-C42A	RS-422, 2ch
Ethernet	XGL-EFMF	Fiber optic, Open type
	XGL-EFMT	Twisted pair, Open
	XGL-ESHF	Fast Ethernet type (Industrial optic ring)
	XGL-EHST	Fast Ethernet switch hub
Dedicated	XGL-EDMF	Fiber optic, Dedicated
	XGL-EDMT	Ethernet Twisted pair, Dedicated Ethernet
Rnet	XGL-RMEA	Rnet, Master
Dnet	XGL-DMEA	DeviceNet, Master
Pnet	XGL-PMEA	Profibus-DP, Master
	XGL-PMEC	

### Special module

Analog input	XGF-AV8A	Voltage, 8ch
	XGF-AC8A	Current, 8ch
	XGF-AD8A	Voltage /Current, 8ch
	XGF-AD4S	Voltage /Current, 4ch,
	XGF-AD16A	Insulation Voltage /Current, 16ch
Analog output	XGF-DV4A	Voltage, 4ch
	XGF-DC4A	Current, 4ch
	XGF-DV8A	Voltage, 8ch
	XGF-DC8A	Current, 8ch
	XGF-DV4S	Voltage, 4ch, Insulation
High speed counter	XGF-HO2A	Open collector, 2ch
	XGF-HD2A	Line drive, 2ch
	XGF-PO3A	Open collector, 3axes
	XGF-PO2A	Open collector, 2axes
	XGF-PO1A	Open collector, 1axis
Positioning	XGF-PD3A	Line drive, 3axes
	XGF-PD2A	Line drive, 2axes
	XGF-PD1A	Line drive, 1axis
	XGF-TC4S	Thermo couple, 4ch, Insulation
Temperature input	XGF-RD4A	RTD, 4ch
	XGF-RD4S	RTD, 4ch, Insulation
Temperature controller	XGF-TC4UD	4 loops, Insulation

### Cable

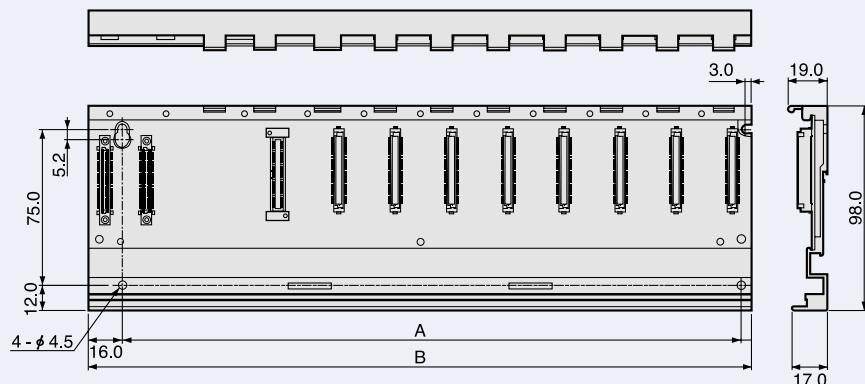
Item	Product	Description
Expansion cable	XGC-E041	0.4m
	XGC-E061	0.6m
	XGC-E121	1.2m
	XGC-E301	3.0m
	XGC-E501	5.0m
	XGC-E102	10m
	XGC-E152	15m
Termination connector	XGT-TERA	Termination connector for expansion base download cable
USB cable	USB-301A	USB download cable
RS232C cable	K1C-050A	RS232C download cable
Dummy	XGT-DMMA	Dummy module

### XGR module

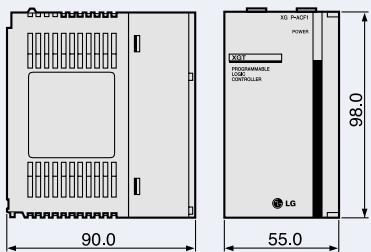
CPU	XGR-CPUH/T	Twisted pair
	XGR-CPUH/F	Fiber optic
Power	XGR-AC12	110V, 5.5A(Main base)
	XGR-AC13	110V, 8.5A(Expansion base)
	XGR-AC22	220V, 5.5A(Main base)
	XGR-AC23	220V, 8.5A(Expansion base)
Base	XGR-M06P	6Slot(Main base)
	XGR-E12P	12Slot(Expansion base)
Expansion drive	XGR-DBST	Twisted pair - Twisted
	XGR-DBSF	pair Fiber optic - Fiber optic
	XGR-DBSH	Twisted pair - Fiber optic
Sync & Expansion cable	XGC-F201	2m (Fiber optic)
	XGC-F501	5m (Fiber optic)

## Dimensions

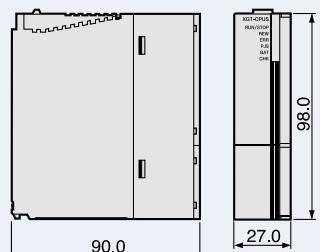
## • Base



## • Power module



## • CPU and I/O module



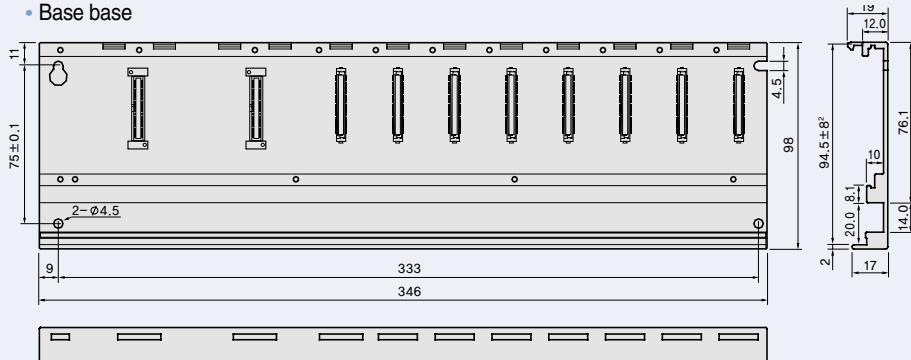
## Base Dimensions (W)

Item	XGB-M04A/E04A	XGB-M06A/E06A	XGB-M08A/E08A	XGB-M12A/E12A
A	190	244	298	406
B	210	264	318	426

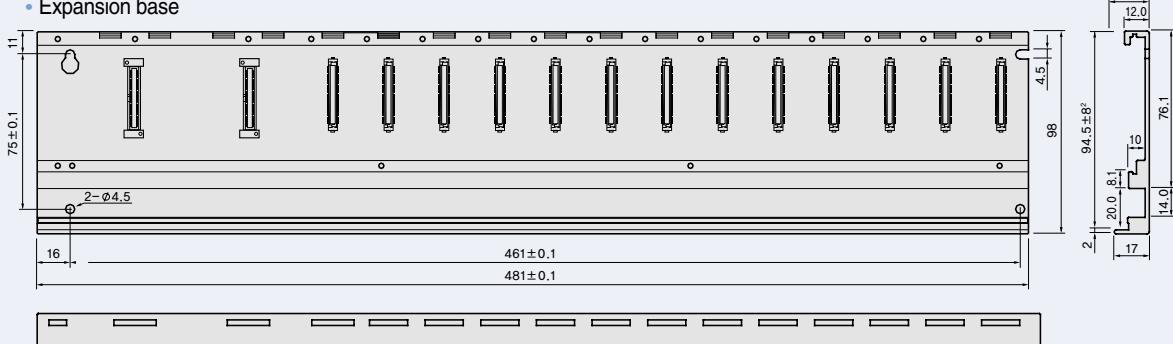
## XGR Dimensions

### Dimensions

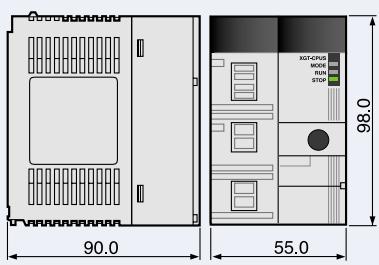
- Base base



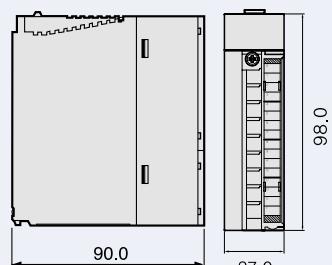
- Expansion base



- Power and CPU



- I/O



### Base Dimensions (W)

Item	XGR-M06P	XGR-E12P
A	333	461
B	346	481



**Memo**



Leading Innovation, Creating Tomorrow 



- For your safety, please read user's manual thoroughly before operating.
- Contact the nearest authorized service facility for examination, repair, or adjustment.
- Please contact qualified service technician when you need maintenance.  
Do not disassemble or repair by yourself!
- Any maintenance and inspection shall be performed by the personnel having expertise concerned.

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